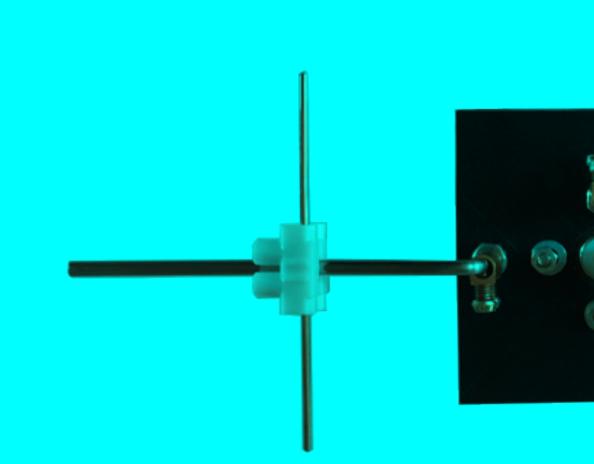
LORA / LORAWAN TUTORIAL 48

Yagi-Uda Antenna



v1.0.0





INTRO

• In this tutorial I will explain what a Yagi-Uda antenna is and how to build one.

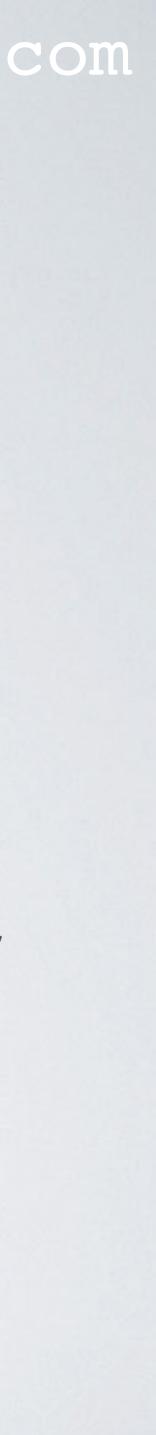


ATTENTION

- The antennas built in this tutorial are intended for test and educational purpose and should be used indoors.
- The antennas are constructed in such a way so it can be easily disassembled and its parts can be re-used in other antenna projects.
- The antennas are not properly constructed and the antenna another way of construction.

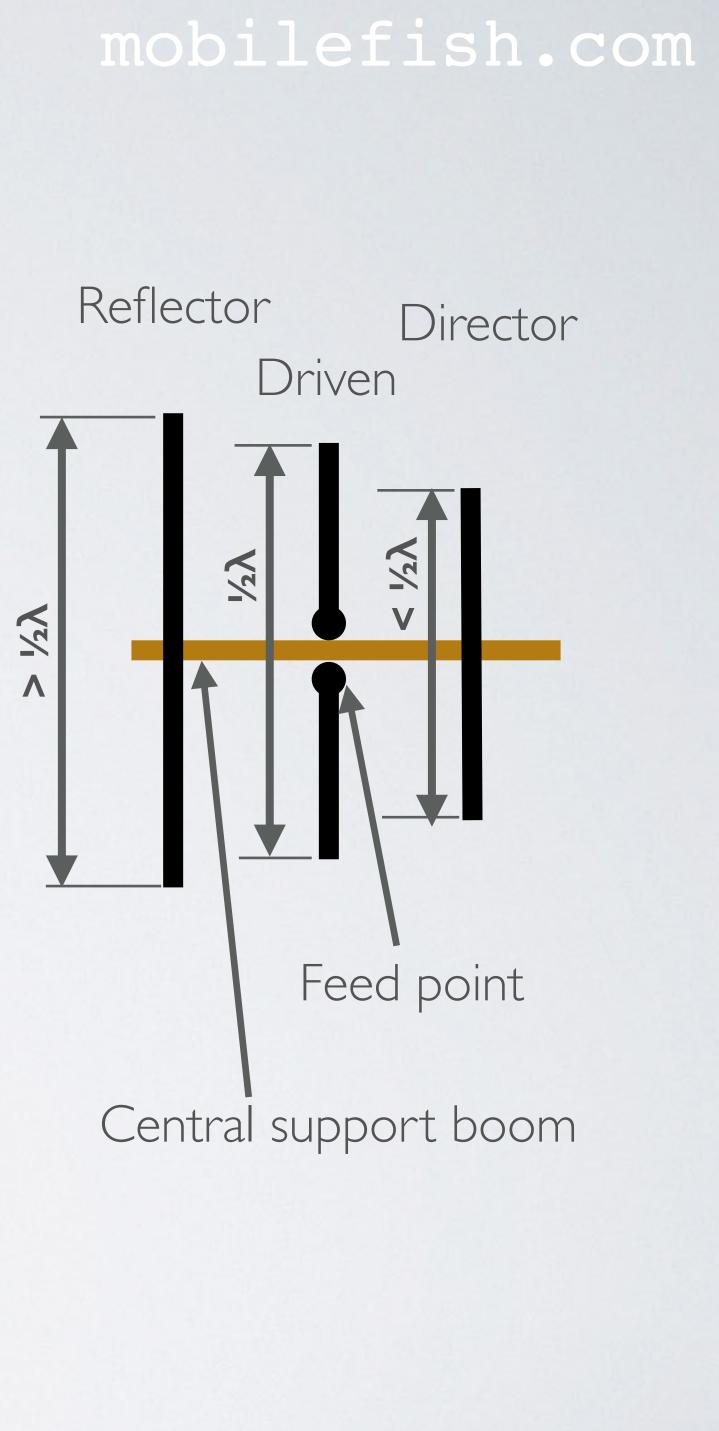
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performance can be improved by using better materials, parts or



YAGI-UDA ANTENNA

- The Yagi-Uda antenna, also known as Yagi antenna, is a directional high gain antenna.
- A basic Yagi-Uda antenna consists of three elements. A reflector, a driven element and a director.
- The driven element is a half wave dipole and parallel to the driven element on either side of it, are straight wires, the reflector and the director.
- The reflector is slightly longer than 1/2 wavelength, the driven element is 1/2 wavelength long and the director is slightly shorter than 1/2 wavelength.



YAGI-UDA ANTENNA

- This online calculator uses the equations found on the next slide to calculate the 3 element Yagi-Uda antenna dimensions.

mobilefish.com

• I used an online Yagi-Uda antenna calculator to calculate the antenna dimensions: https://www.rfwireless-world.com/calculators/3-element-Yagi-Antenna-Calculator.html

Yagi Antenna Calculator

Operating Frequency in MHz (input1) :

868

CALCULATE

Reflector Length (Output#1):

0.17108294930875576

Dipole Length (Output#2):

0.16347926267281104

Director length (Output#3):

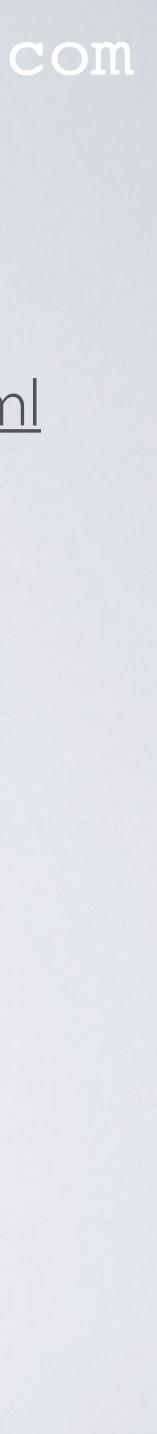
0.15207373271889402

Reflector to Dipole Spacing (Output#4):

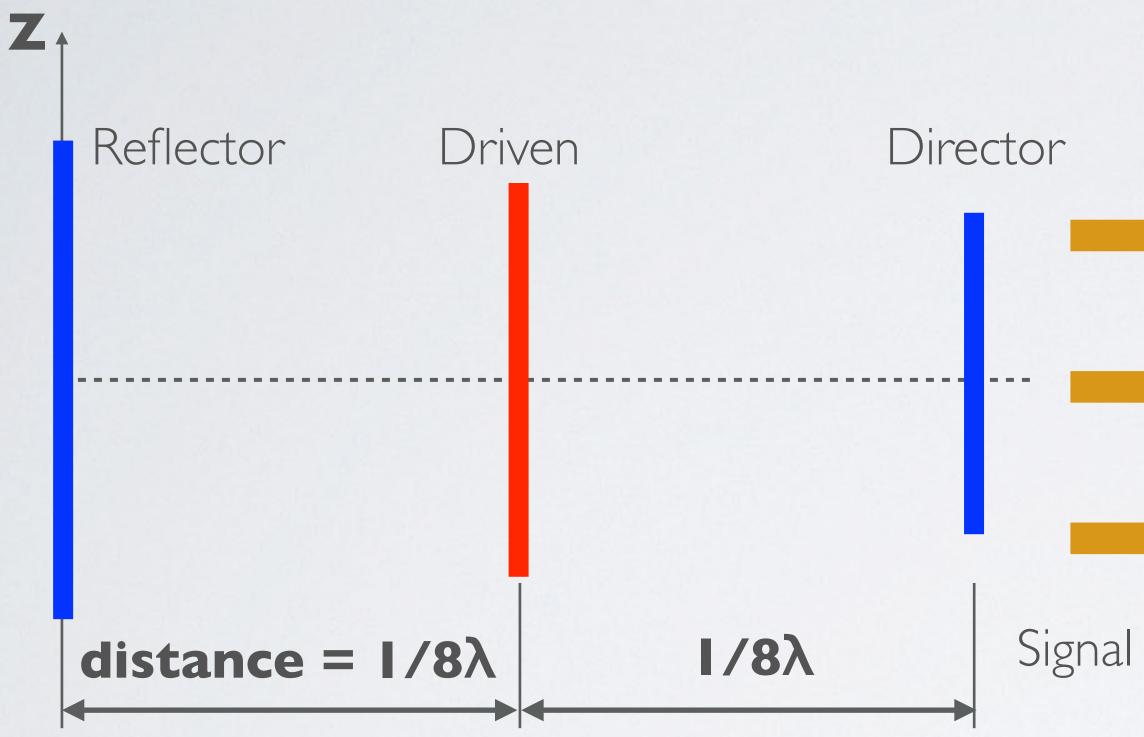
0.043202764976958526

Dipole to Director Spacing (Output#5):

0.043202764976958526



YAGI-UDA ANTENNA DESIGN



 $L_{Reflector} = 0.495 \lambda$ $L_{Driven} = 0.473 \lambda$ $L_{Director} = 0.440 \lambda$

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f = 868 MHz $\lambda = c / f$ $\lambda = 299792458 / (868 \times 10^6)$ $\lambda = 345.38 \text{ mm}$

 $L_{Reflector} = 171 \text{ mm}$ $L_{Driven} = 163 \text{ mm}$ $L_{Director} = 152 \text{ mm}$

distance = 43 mm Drawing not to scale

Signal direction



YAGI-UDA ANTENNA

- I have used the 4NEC2 antenna modelling software to verify the design.
- 4NEC2 card deck: https://www.mobilefish.com/download/lora/ yagi 868mhz 4nec2 before optimisation.nec.txt

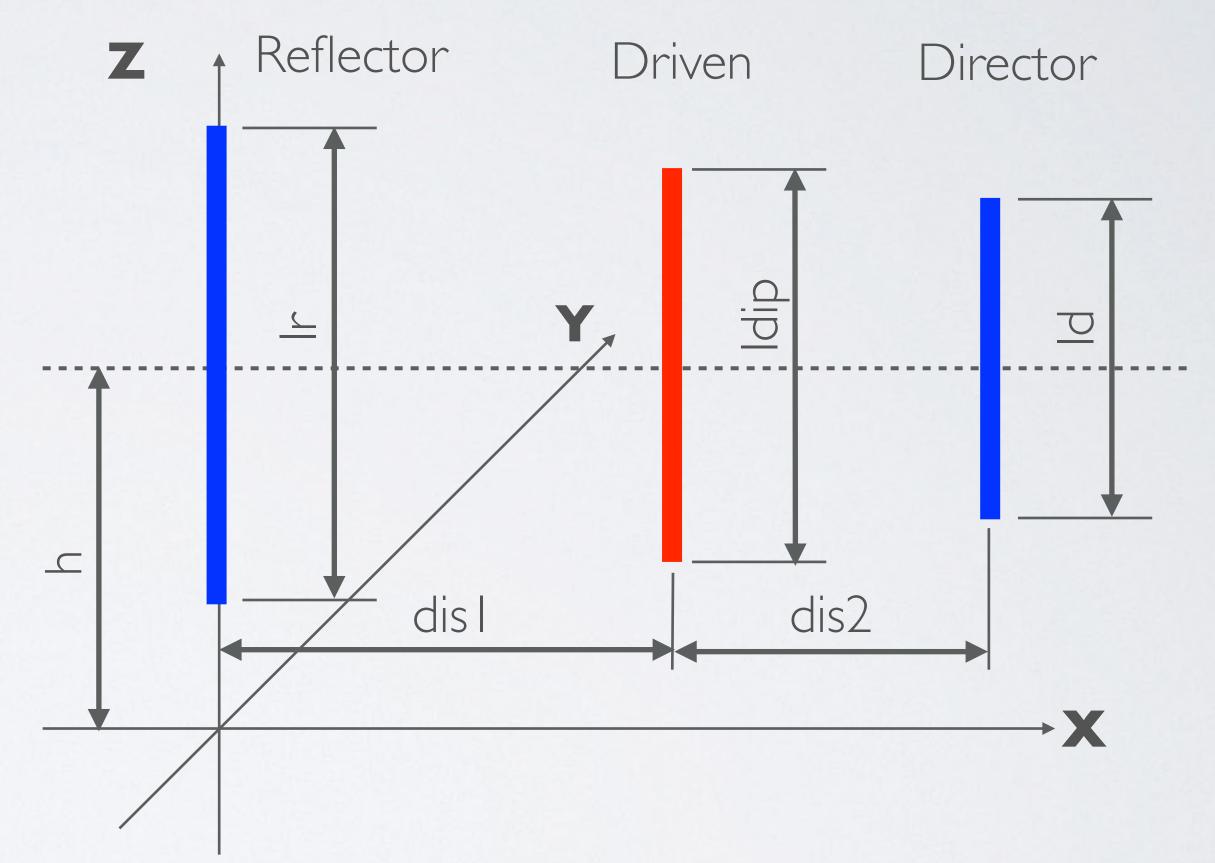


 Yagi-Uda antenna f = 868 MHz wire diameter = 1.8 mm wire material: stainless steel

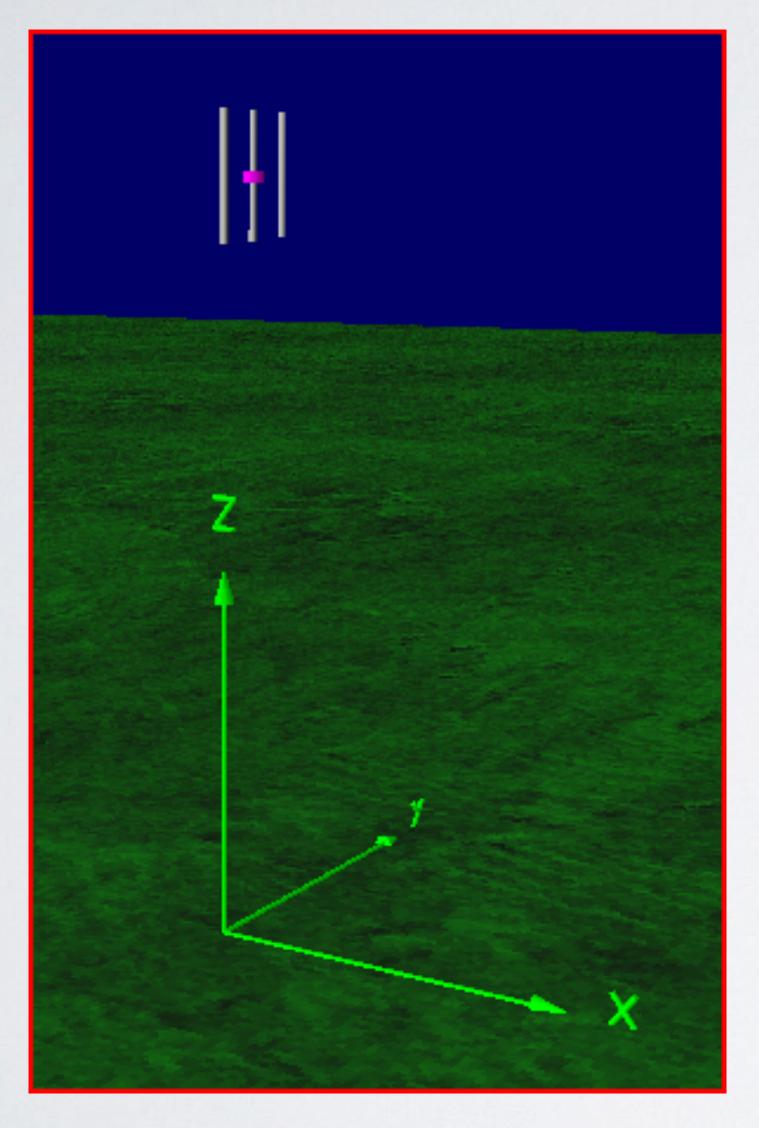
$$h = 1 m$$

 $lr = 171 mm$
 $ldip = 163 mm$
 $dis1 = 43 mm$
 $dis2 = 43 mm$

Drawing not to scale

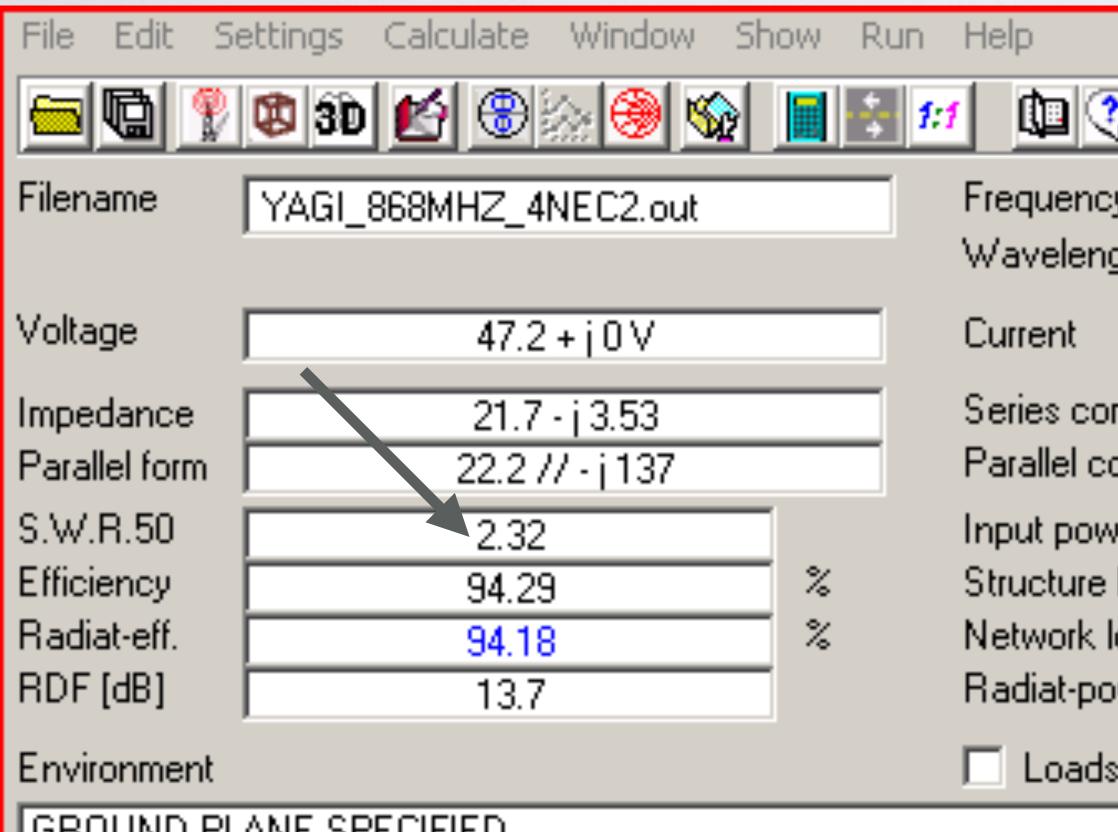






Created in 4NEC2



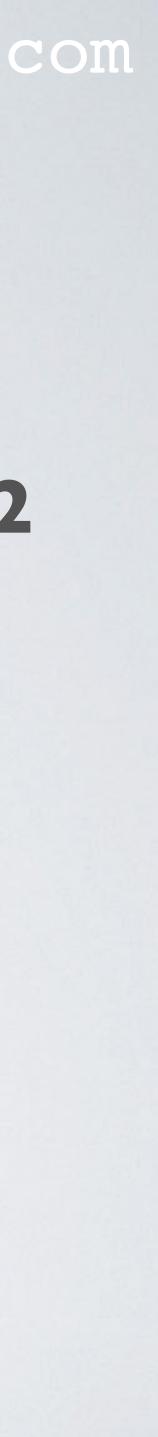


GROUND PLANE SPECIFIED. WHERE WIRE ENDS TOUCH GROUND, CURRENT WILL BE INTERPOLATED TO IMAGE IN GROUND PLANE PERFECT GROUND

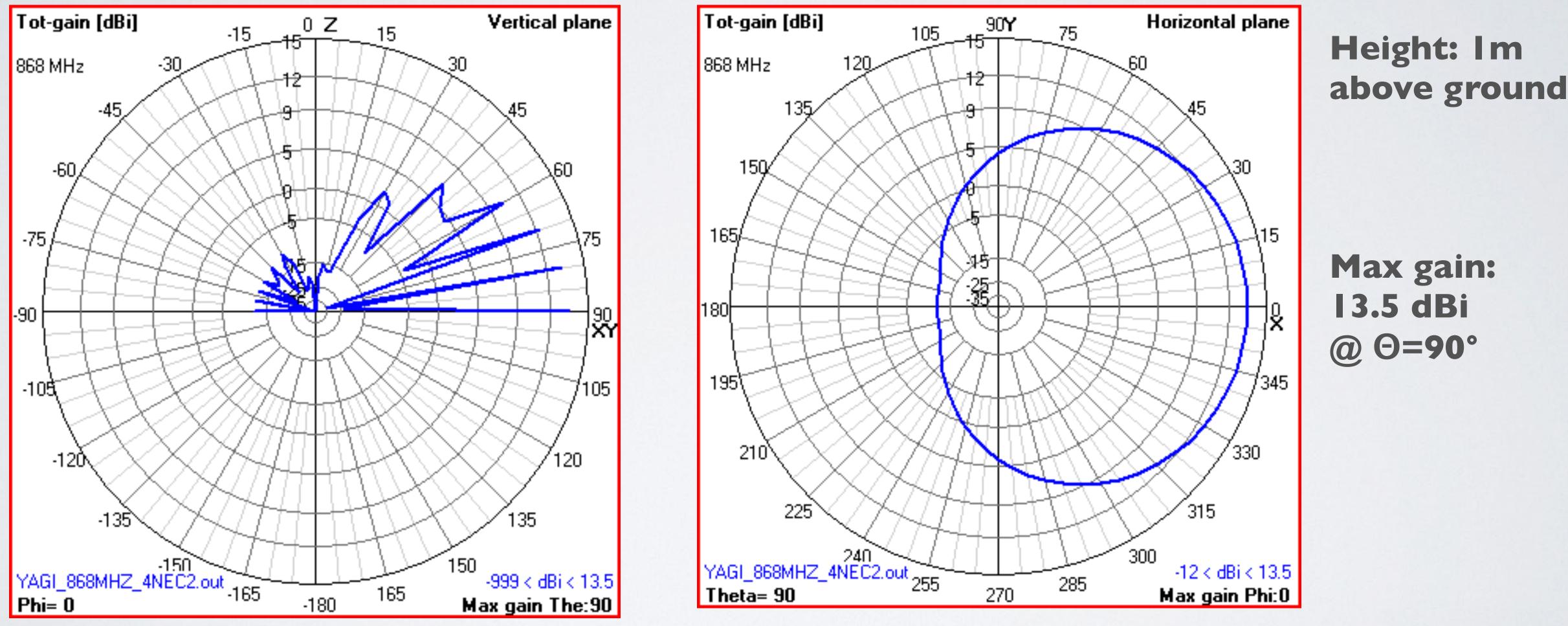
Ground: **Perfect ground** (= perfectly conducting ground). Height: I m above ground.

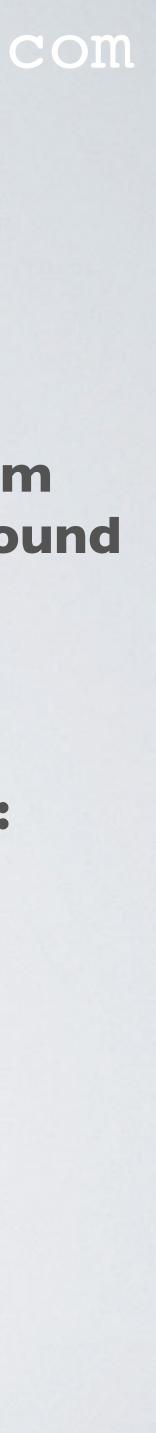
?			
су	868	M	hz
ngth	0.345	m	tr
	2.12 + j 0.35 A		
omp.	6.e-4		uН
omp.	0.025		uH
wer	100		W
e loss	5.708		W
loss	0		u₩
ower	94.29		W
ls	🗖 Polar		

VSWR=2.32



• Ground: **Perfect ground** (= perfectly conducting ground).



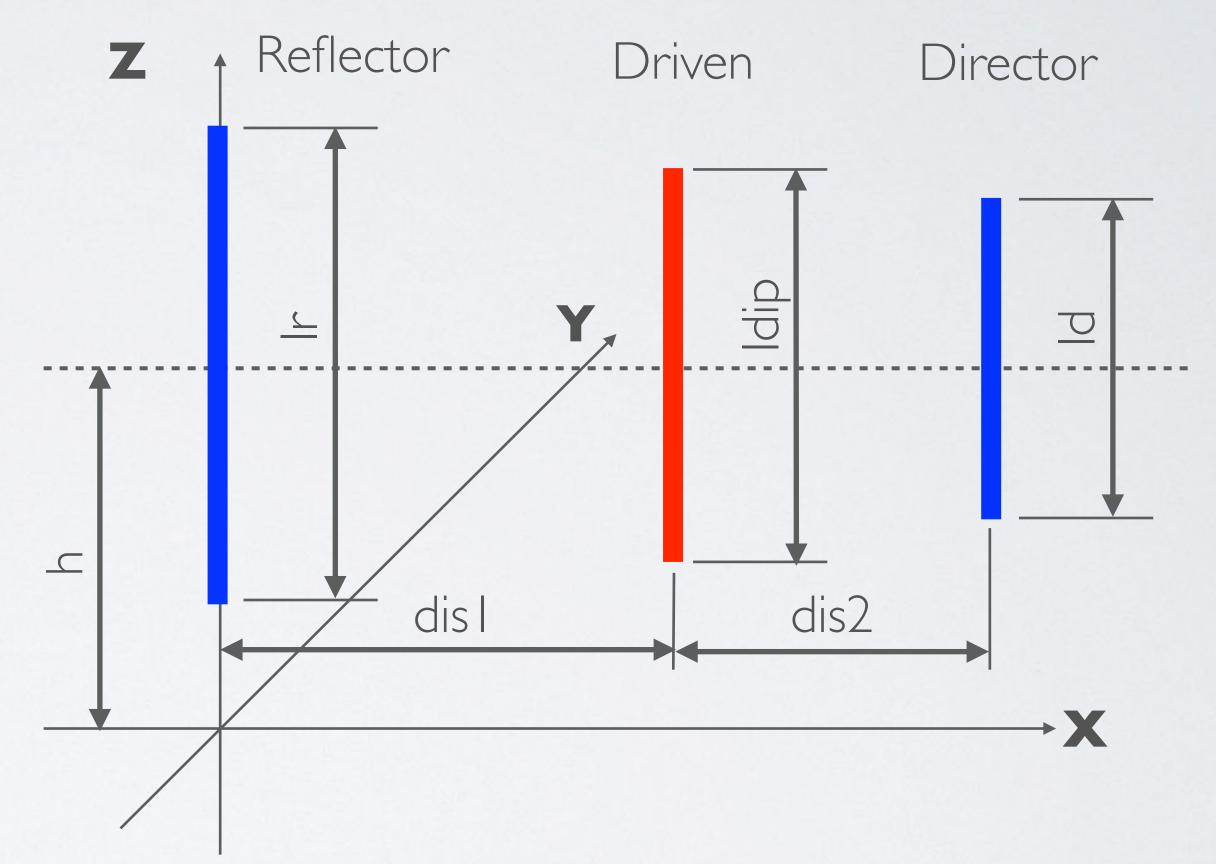


- Next I used the 4NEC2 optimising functionality to improve the design.
- 4NEC2 card deck: https://www.mobilefish.com/download/lora/ yagi 868mhz 4nec2 after optimisation.nec.txt

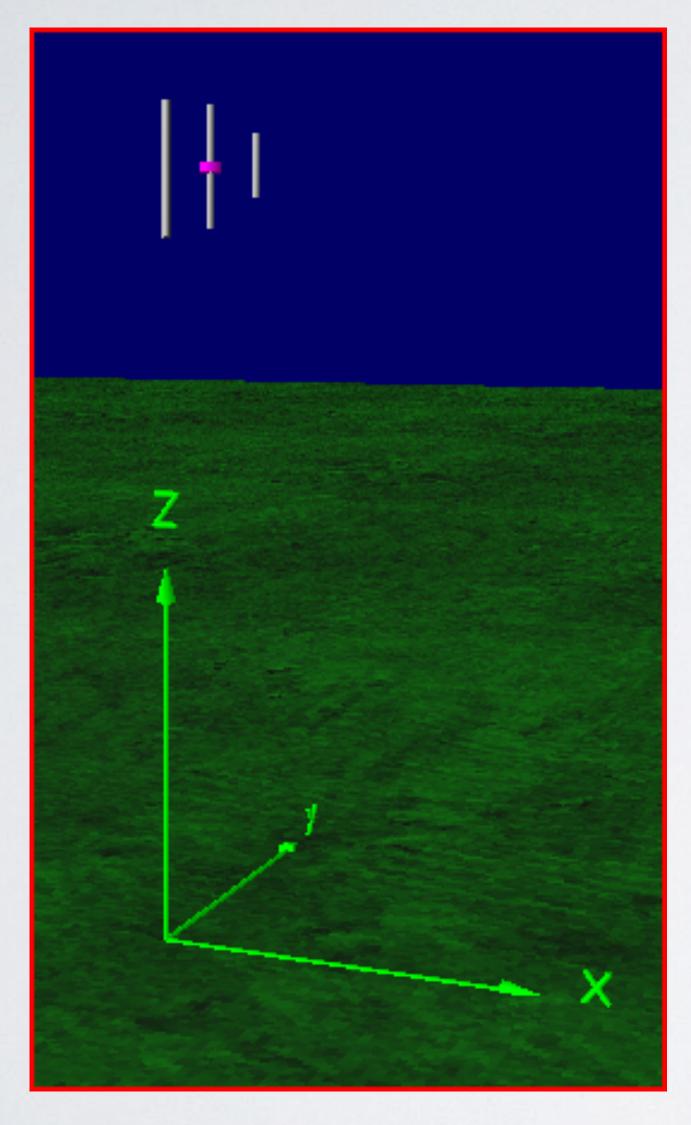


 Yagi-Uda antenna f = 868 MHz
 wire diameter = 1.8 mm
 wire materia: stainless steel

Drawing not to scale

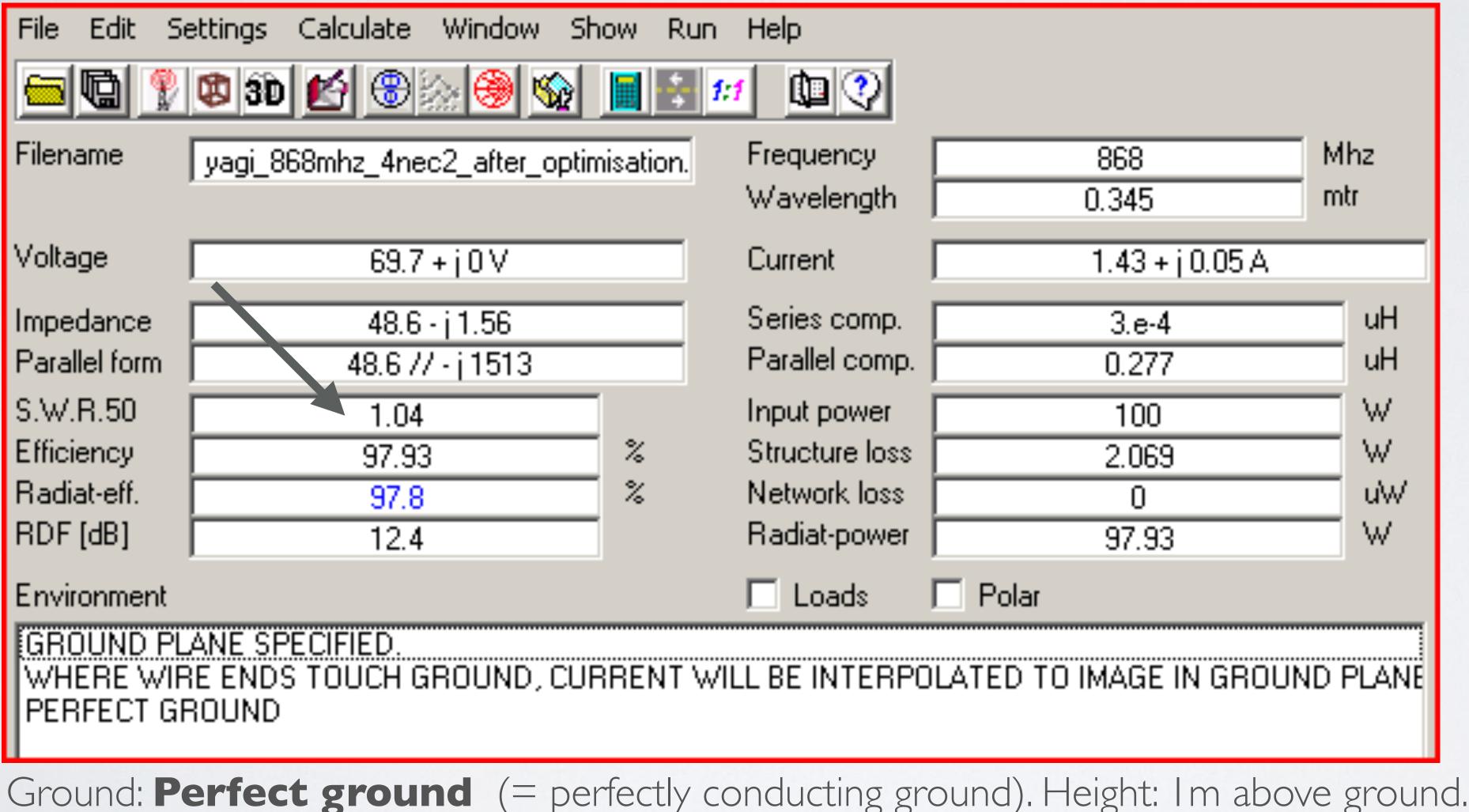






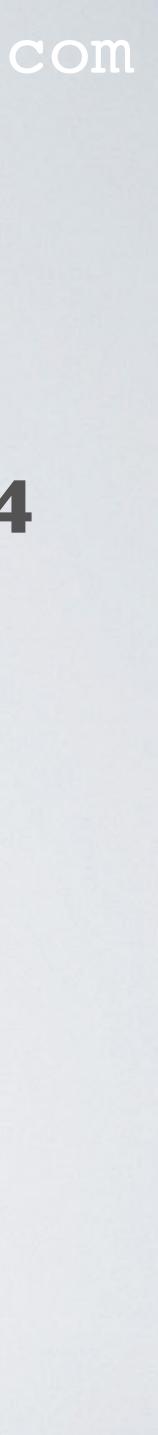
Created in 4NEC2



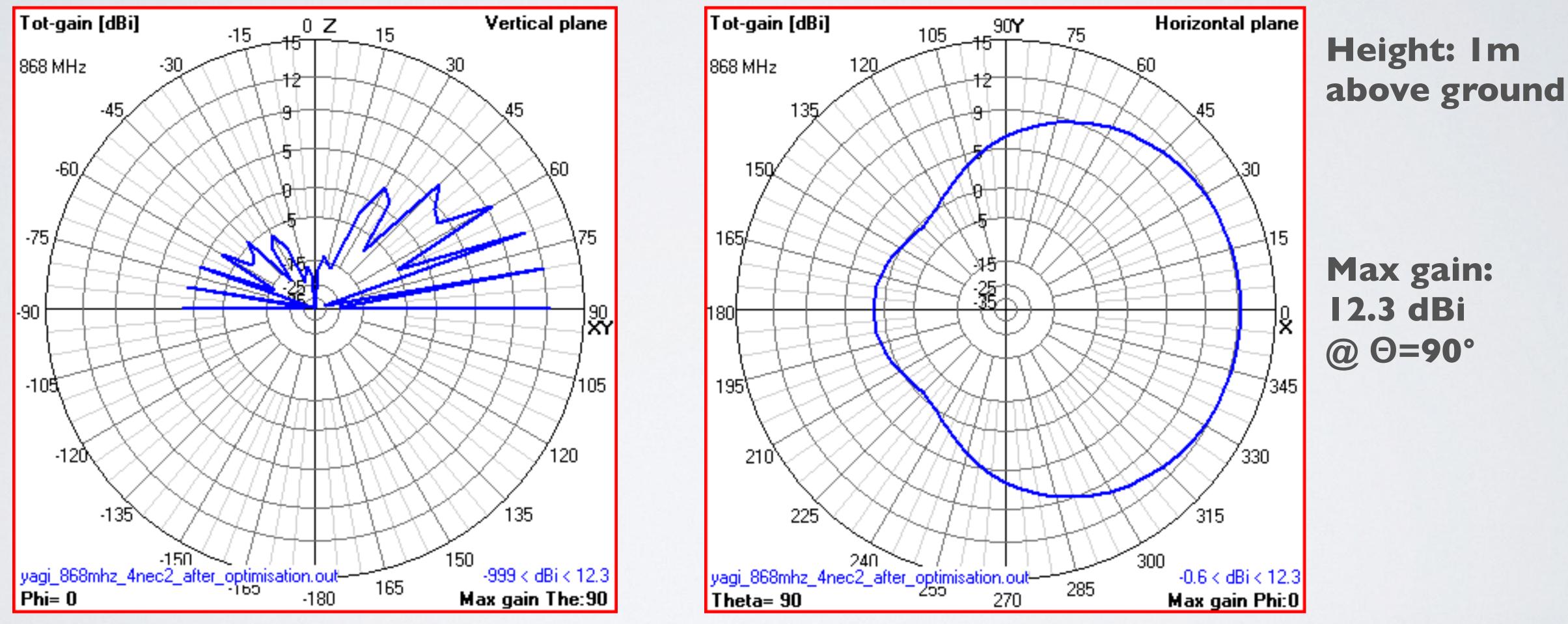


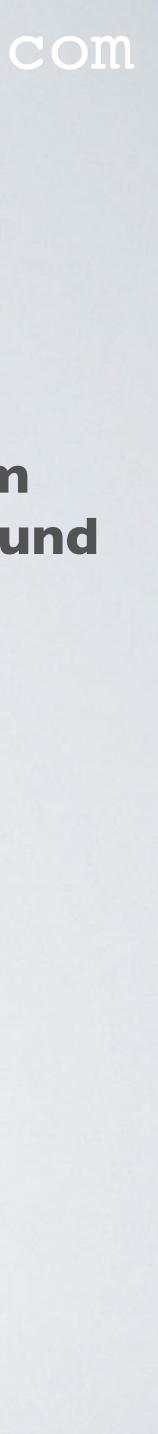
,	868	Mhz	
lth	0.345	mtr	
	1.43 + j 0.05 A		
np.	3.e-4	uH	
mp.	0.277	uH	
er	100	W	
oss	2.069	W	
oss	0	uW	
ver	97.93	W	
	Polar		

VSWR = 1.04

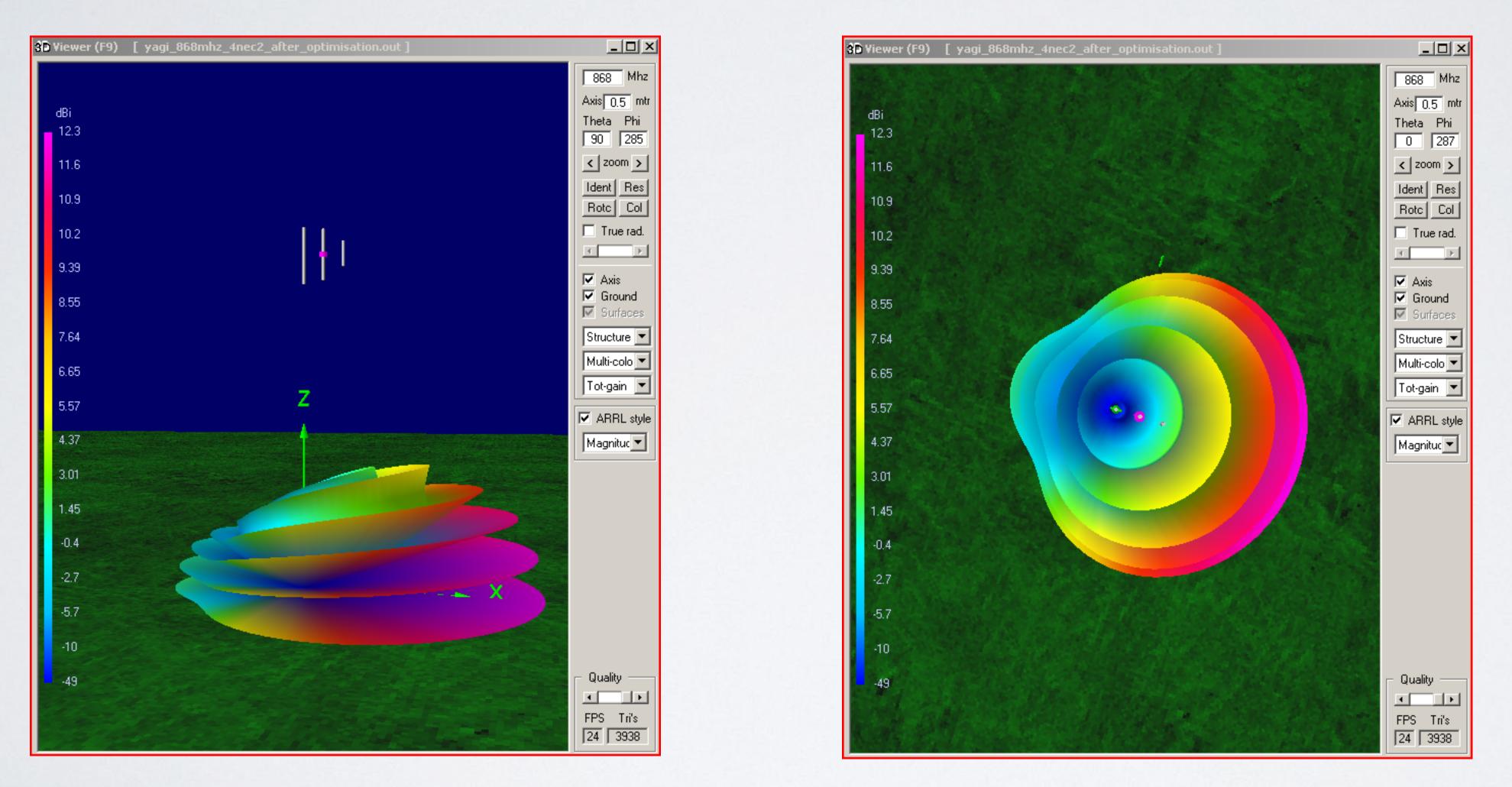


• Ground: **Perfect ground** (= perfectly conducting ground)

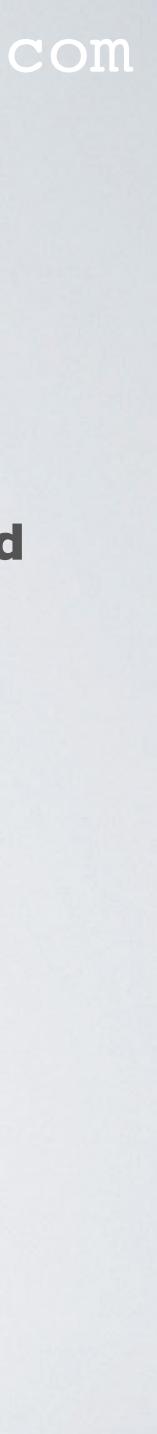




• Ground: **Perfect ground** (= perfectly conducting ground)



Height: Im above ground



😵 Main [¥5.8.16] (F2)					
File Edit Se	ettings Calculate Window Sh	iow Ru	n Help		
<u>6</u>	🕸 3D 🛃 🛞 🐎 🥮 🎡		<u>1:1</u>		
Filename	yagi_868mhz_4nec2_after_optim	nisation.	Frequency		
			Wavelength		
Voltage	69.7 + j 0 V		Current		
Impedance	48.6 - j 1.54		Series comp.		
Parallel form	48.6 // - j 1529		Parallel comp.		
S.W.R.50	1.04		Input power		
Efficiency	97.93	%	Structure loss		
Radiat-eff.	57.13	%	Network loss		
RDF [dB]	13.2		Radiat-power		
Environment			🗖 Loads		

GROUND PLANE SPECIFIED. WHERE WIRE ENDS TOUCH GROUND, CURRENT WILL BE INTERPOLATED TO IMAGE IN GROUND PLANE FINITE GROUND. SOMMERFELD SOLUTION RELATIVE DIELECTRIC CONST.= 3.000 CONDUCTIVITY= 1.000E-04 MHOS/METER COMPLEX DIELECTRIC CONSTANT= 3.00000E+00-2.07097E-03

Ground: Real ground

Ground type: City industrial area

868 0.345	Mhz mtr
1.43 + j 0.05 A	
3.e-4 0.28	uH uH
100	W
2.069	
0	u₩
97.93	W

_ 🗆 🗵

Polar

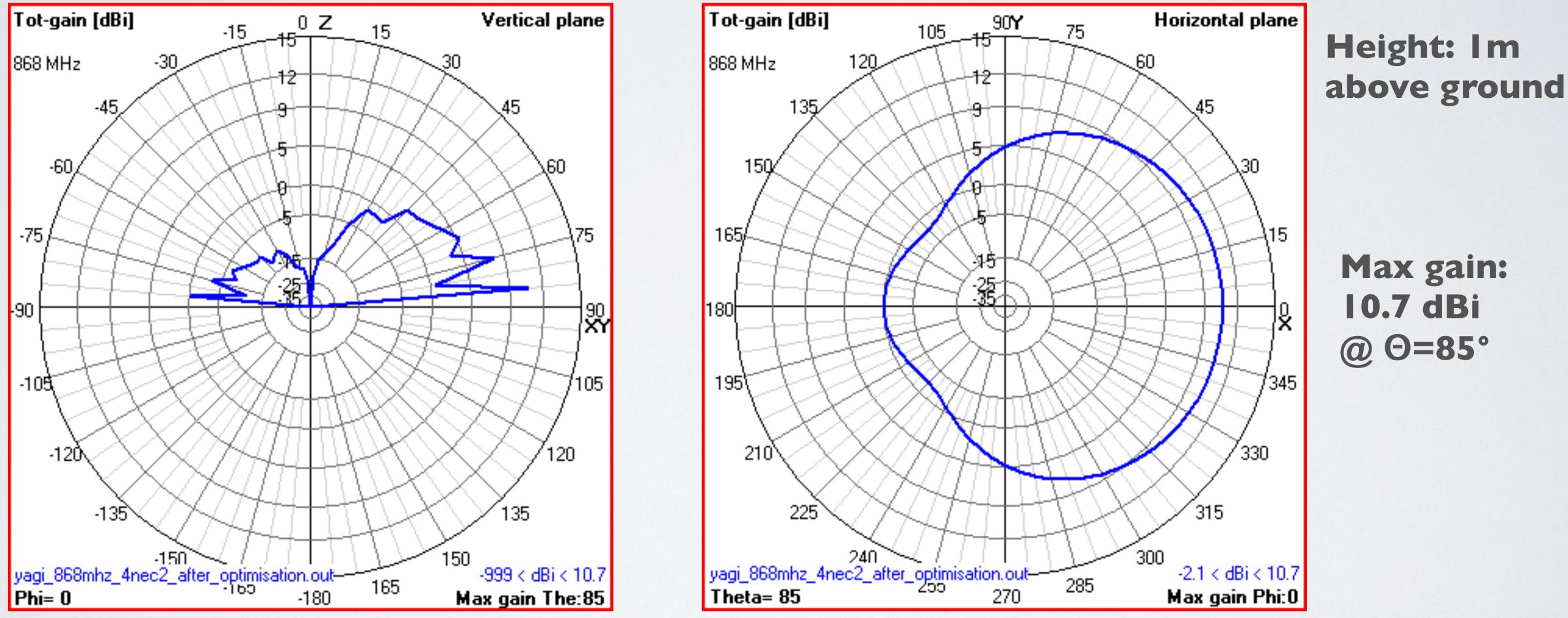
VSWR=1.04

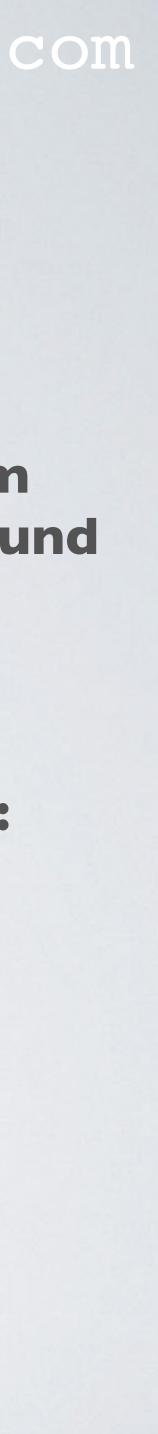
Change ground

rea Height: Im above ground

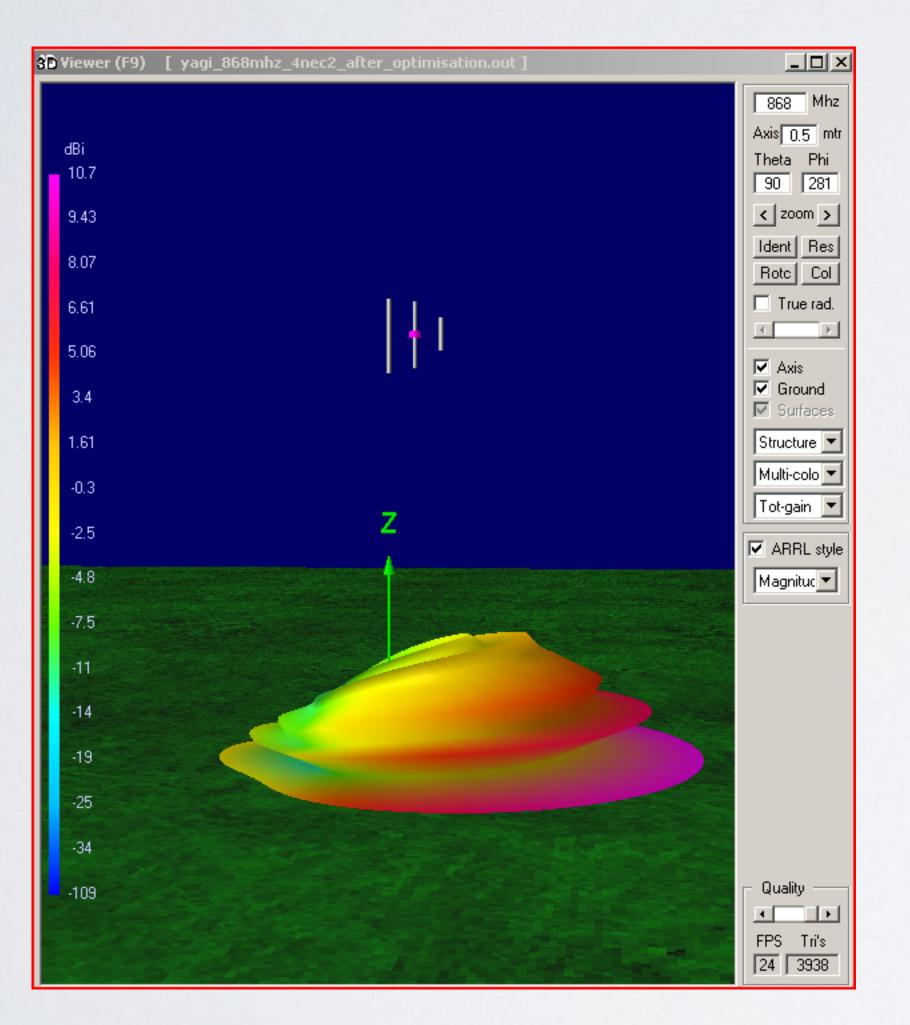


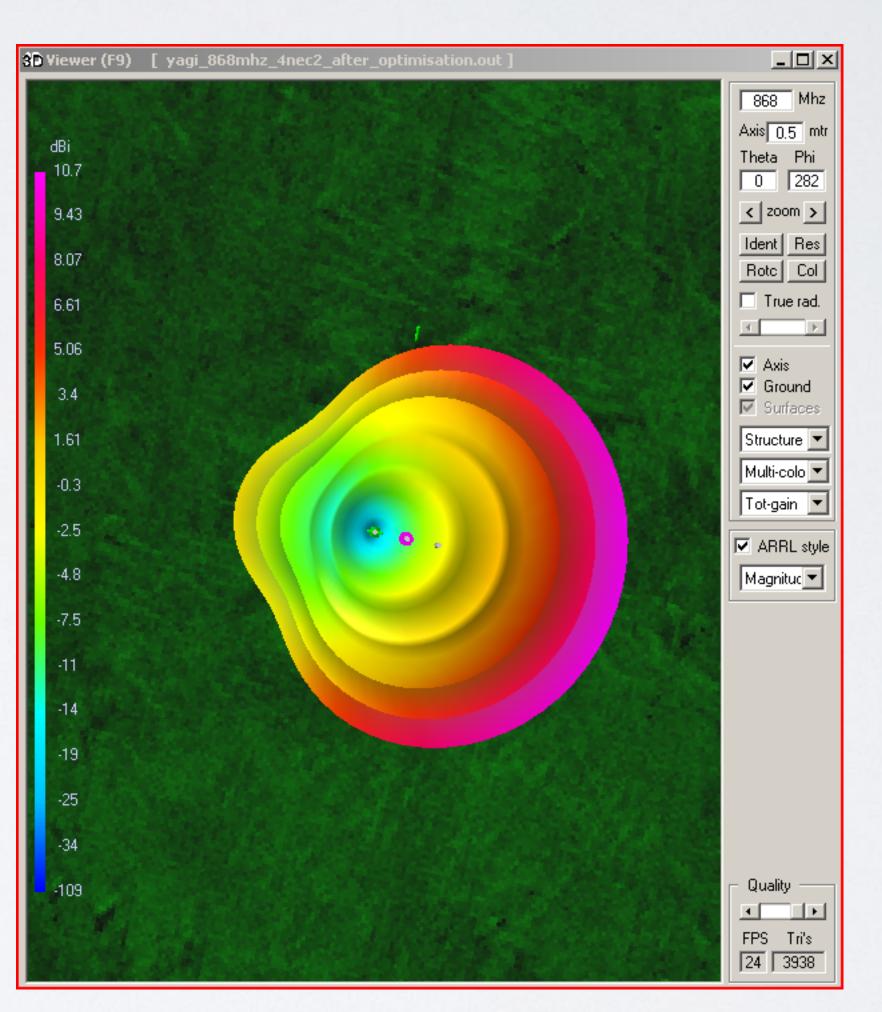
• Ground: Real ground Ground type: City industrial area





Ground: Real ground Ground type: City industrial area





Height: Im above ground



📸 Main [¥5.)	8.16] (F2)			
File Edit Se	ettings Calculate Window Sh	ow Run	Help	
<u>6</u>	🕸 😰 🛞 🛞 🎯	i	1 🛄 😲	
Filename	yagi_868mhz_4nec2_after_optim	nisation.	Frequency	
			Wavelength	
Voltage	69.7 + j 0 V		Current	
Impedance	48.6 - j 1.34		Series comp.	
Parallel form	48.6 // - j 1766		Parallel comp.	
S.W.R.50	1.04		Input power	
Efficiency	97.93	%	Structure loss	
Radiat-eff.	31.85	%	Network loss	
RDF [dB]	10.3		Radiat-power	
Environment			🔲 Loads 🔤	

GROUND PLANE SPECIFIED. WHERE WIRE ENDS TOUCH GROUND, CURRENT WILL BE INTERPOLATED TO IMAGE IN GROUND PLANE FINITE GROUND. SOMMERFELD SOLUTION RELATIVE DIELECTRIC CONST.= 3.000 CONDUCTIVITY= 1.000E-04 MHOS/METER COMPLEX DIELECTRIC CONSTANT= 3.00000E+00-2.07097E-03

Ground: Real ground

Ground type: City industrial area Height: 10 m above ground

	Mhz mtr
1.43 + j 0.04 A	
2.e-4	uH
0.324	uН
100	W
2.07	uw I
0	uW
97.93	W
Polar	

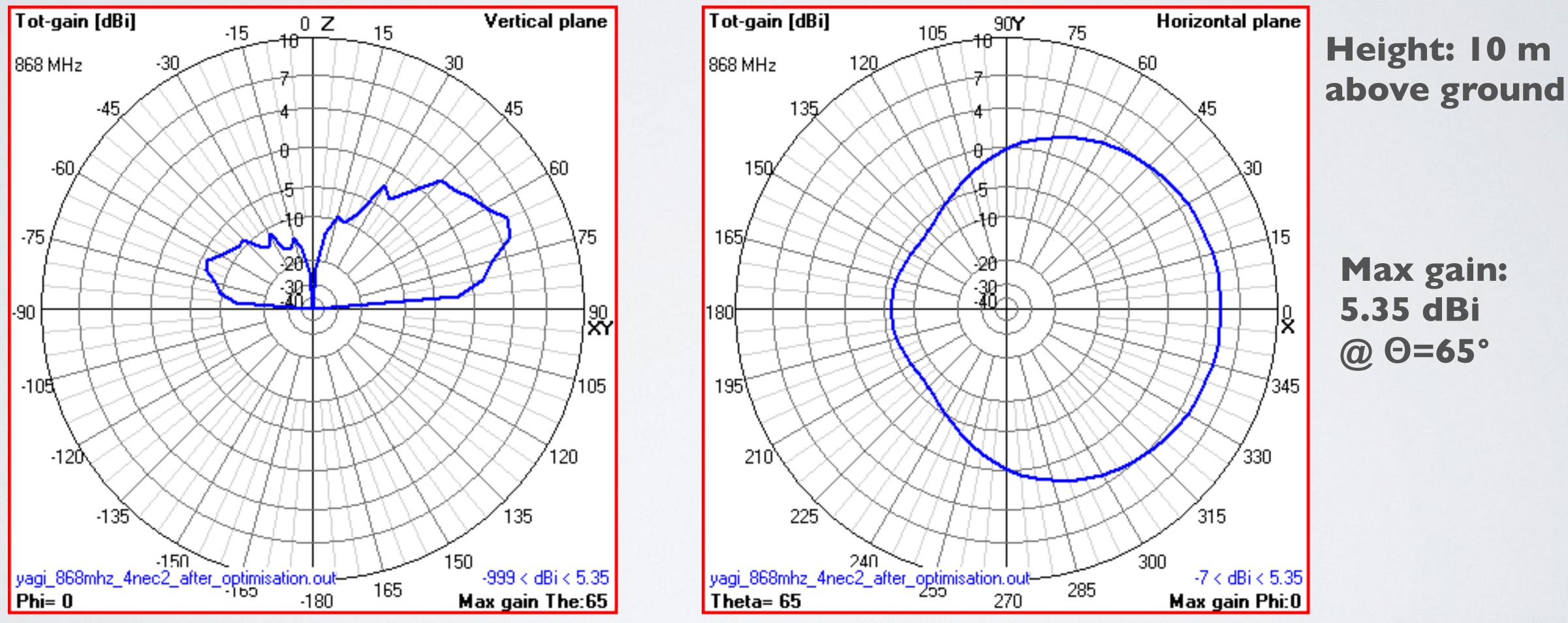
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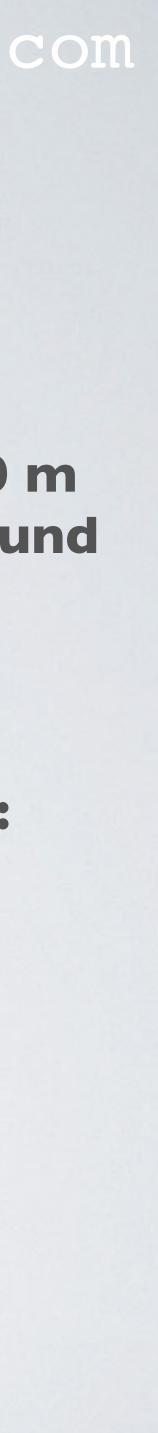
VSWR=1.04

Change height



• Ground: Real ground Ground type: City industrial area





📸 Main [¥5.8	8.16] (F2)			
File Edit Se	ettings Calculate Window Sh	ow Run	Help	
<u>6</u>	🕸 😰 🛞 🛞 🎯	i	1 🛄 😲	
Filename	yagi_868mhz_4nec2_after_optim	nisation.	Frequency	
			Wavelength	
Voltage	69.7 + j 0 V		Current	_
Impedance	48.6 - j 1.34		Series comp.	
Parallel form	48.6 // - j 1766		Parallel comp.	
S.W.R.50	1.04		Input power	
Efficiency	97.93	%	Structure loss	
Radiat-eff.	41.74	%	Network loss	
RDF [dB]	9.99		Radiat-power	
Environment			🗌 Loads 🛛 🗌	

GROUND PLANE SPECIFIED. WHERE WIRE ENDS TOUCH GROUND, CURRENT WILL BE INTERPOLATED TO IMAGE IN GROUND PLANE FINITE GROUND. SOMMERFELD SOLUTION RELATIVE DIELECTRIC CONST.= 3.000 CONDUCTIVITY= 1.000E-04 MHOS/METER COMPLEX DIELECTRIC CONSTANT= 3.00000E+00-2.07097E-03

Ground: Real ground

Ground type: City industrial area

868 0.345	M	hz tr
1.43 + j 0.04 A		
2.e-4 0.324		uH uH
100	_	w
2.07	_	W
0		uW
97.93		W
Polar		

_ D ×

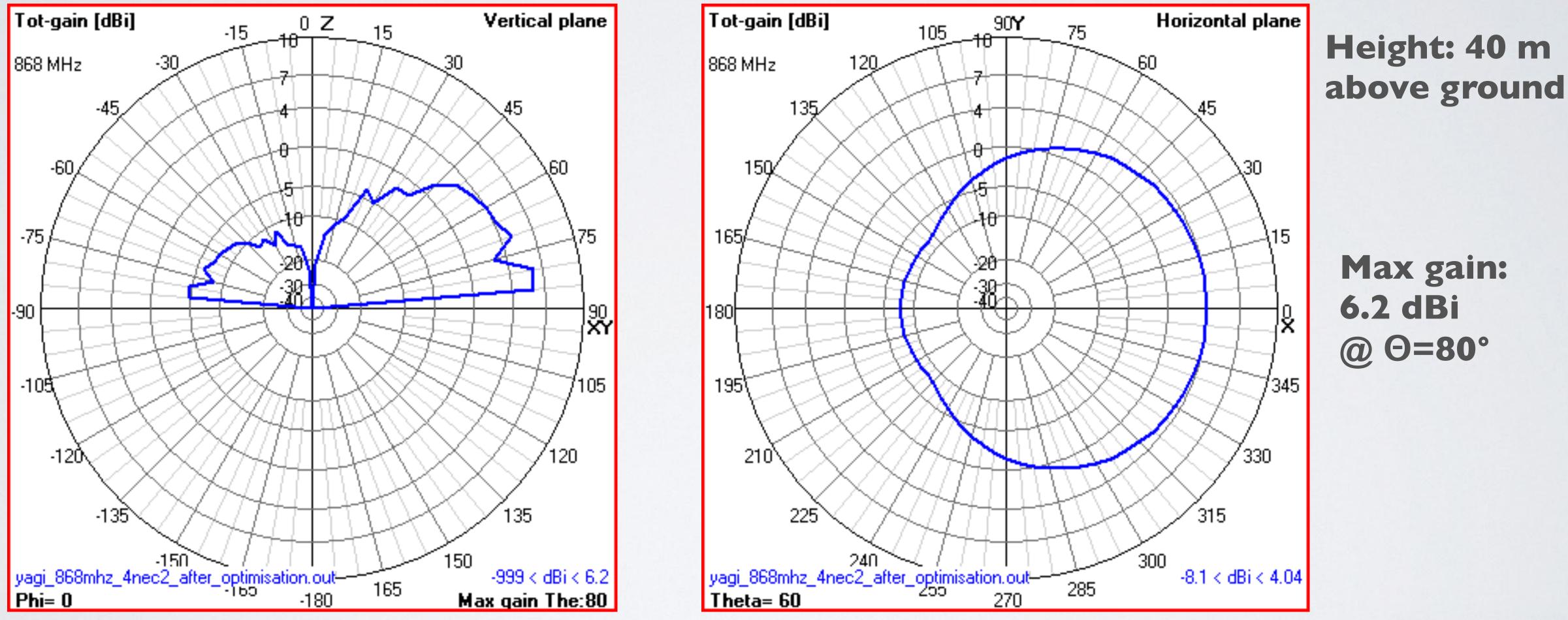
VSWR=1.04

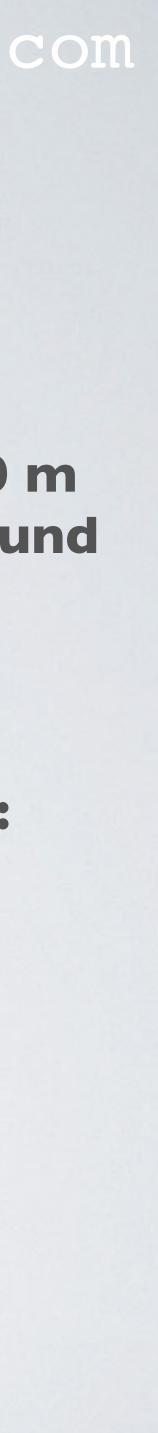
Change height

trial area Height: 40 m above ground



• Ground: Real ground Ground type: City industrial area





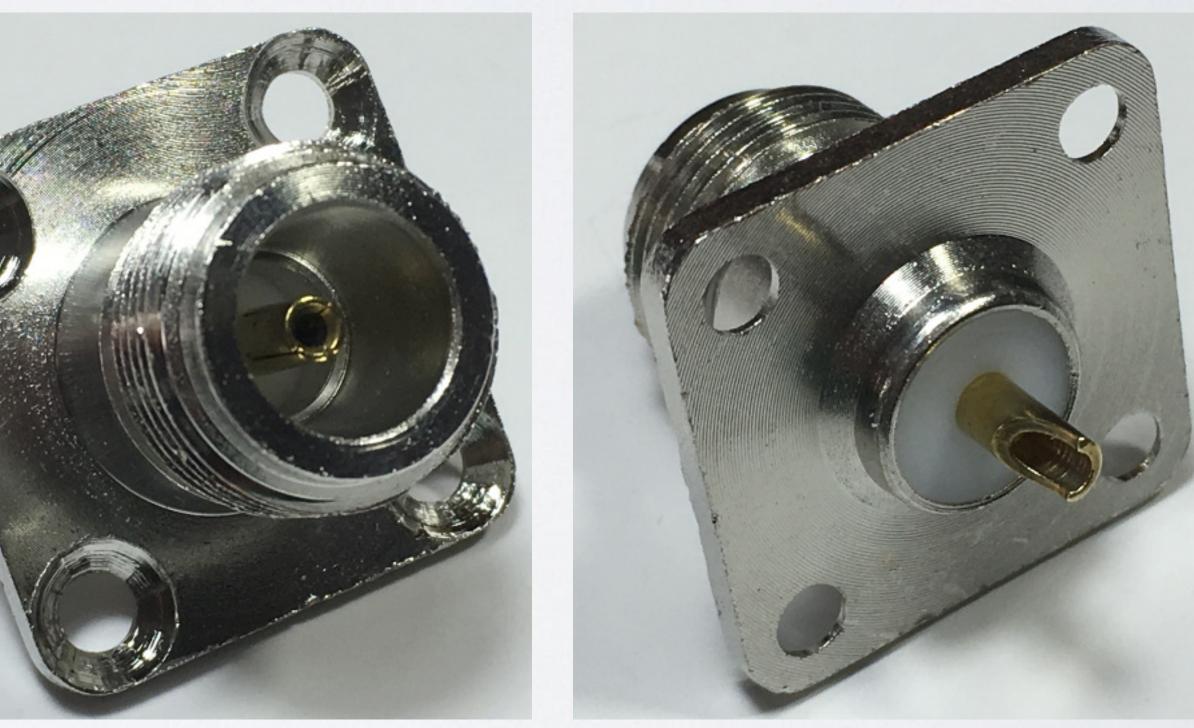
• Based on the 4NEC2 antenna design, after optimisation, I have build the Yagi-Uda antenna.





- Bill of materials
 - Type N female chassis mount 4-hole connector LxW: 2.5 x 2.5 cm / |" x |" Hole diameter: 3.5 mm / 0.137" Impedance: 50Ω Material: Metal alloy Cost: € 0.96



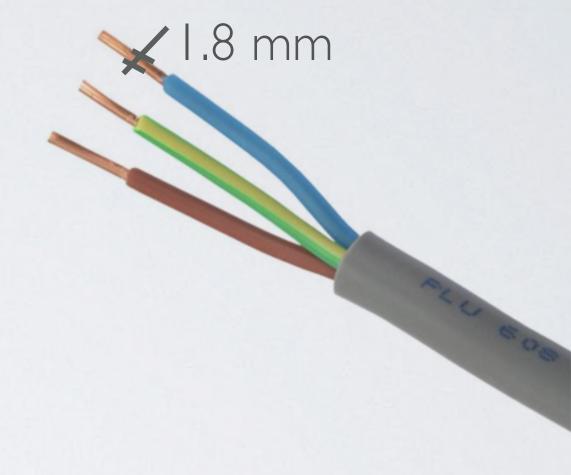




- Outdoor cable XMVK 3x2.5 mm² grey. The copper wire has a diameter of 1.8 mm. Only I meter is needed. Cost: € 1.75 per meter
- The electrical insulator can be easily removed using a Stanley knife.
- Instead of copper wires I used bicycle spokes (stainless steel) which also have a diameter of 1.8 mm.
- With these bicycle spokes I made the reflector, driven element and director.

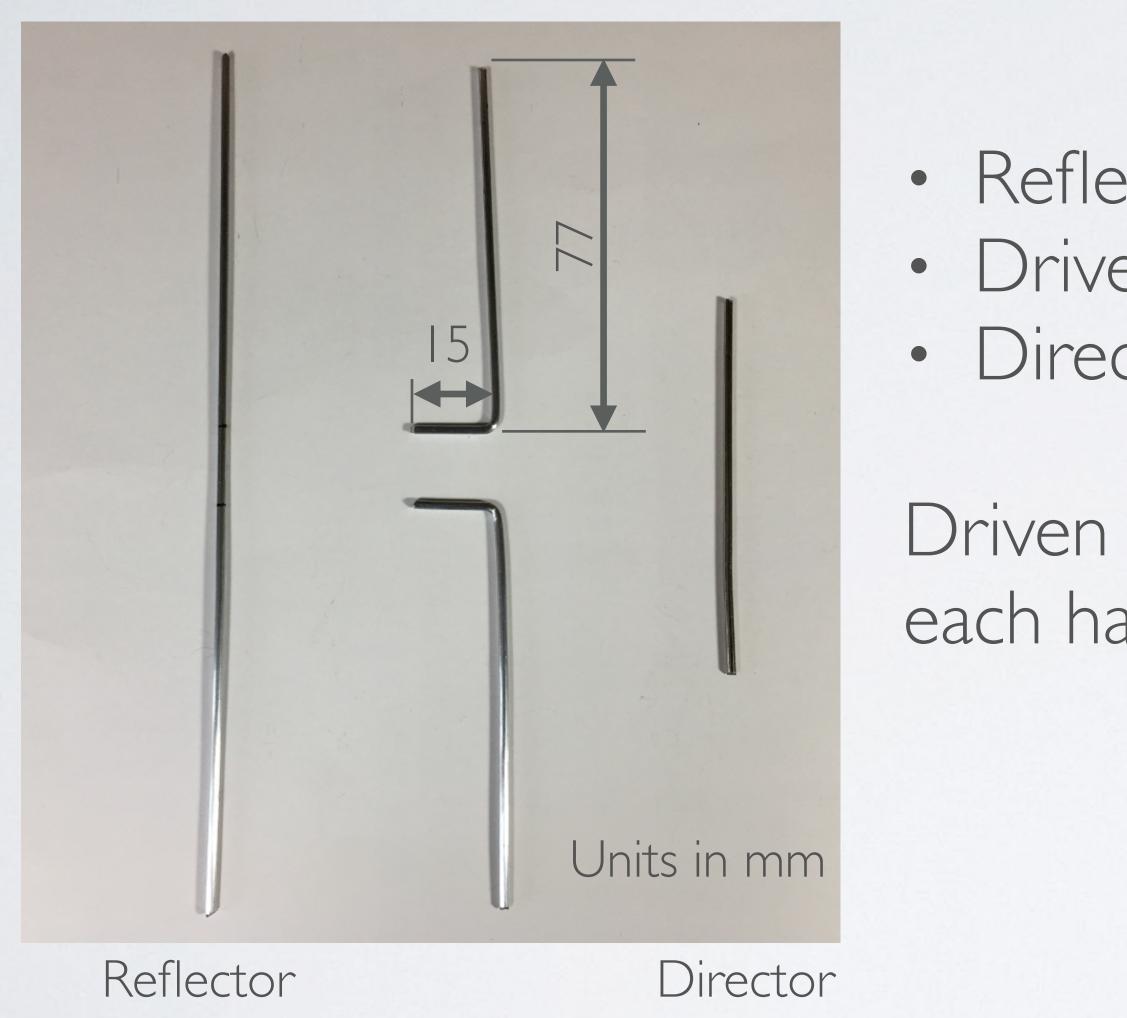












Driven element

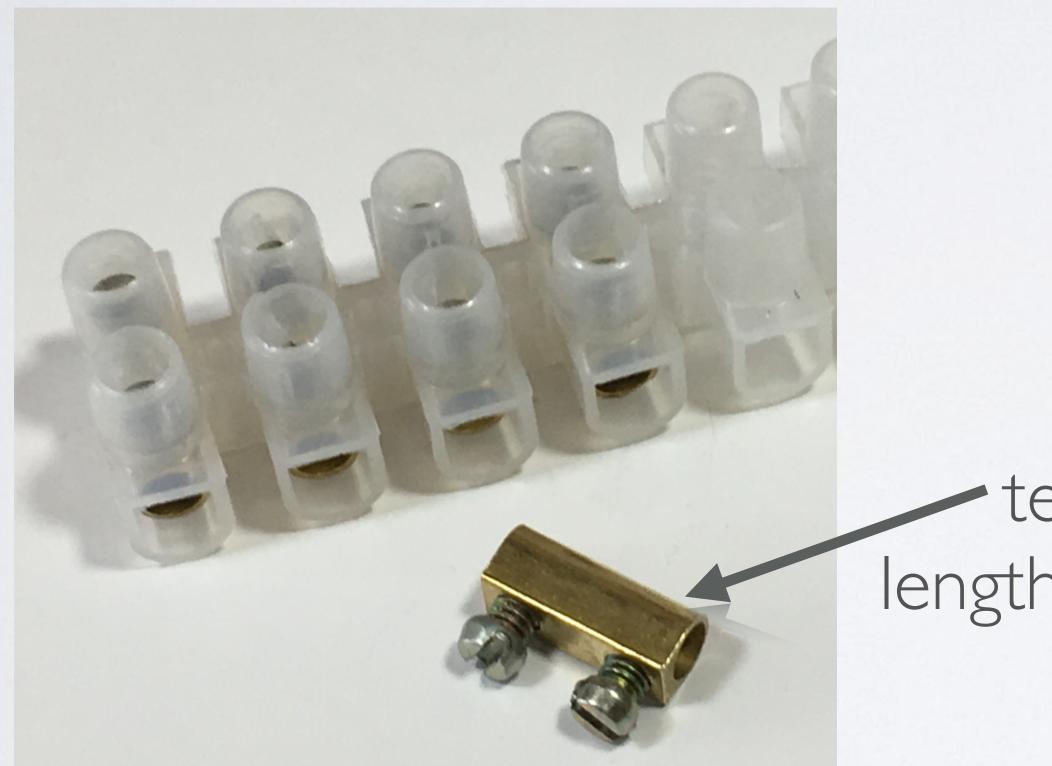
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Reflector length = 171 mm, d = 1.8 mm
Driven element = 154 mm, d = 1.8 mm
Director length = 76 mm, d = 1.8 mm

Driven element consists of two parts, each has a length of 77 mm (= 2x77=154)

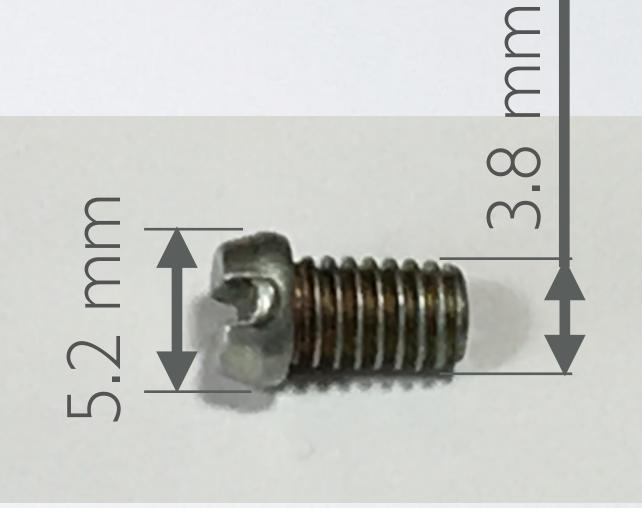


• Terminal strip block (3 Ampere) Cost: € 1.80 (3 strips, each strip has 12 terminals)



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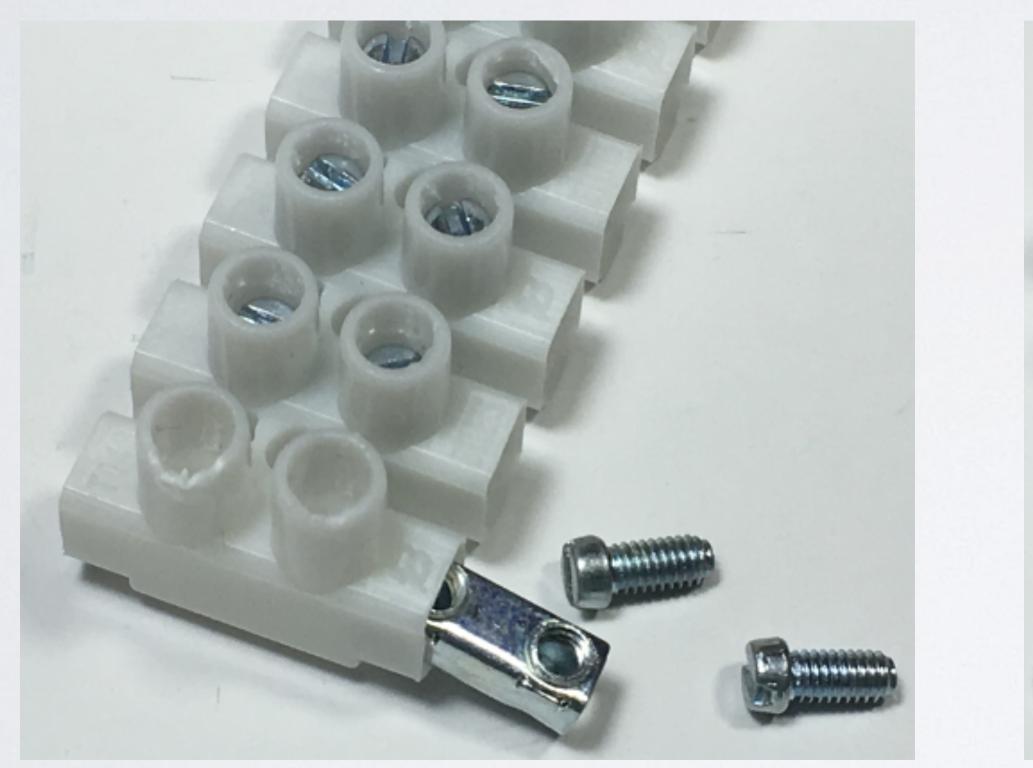




terminal length = 16 mm

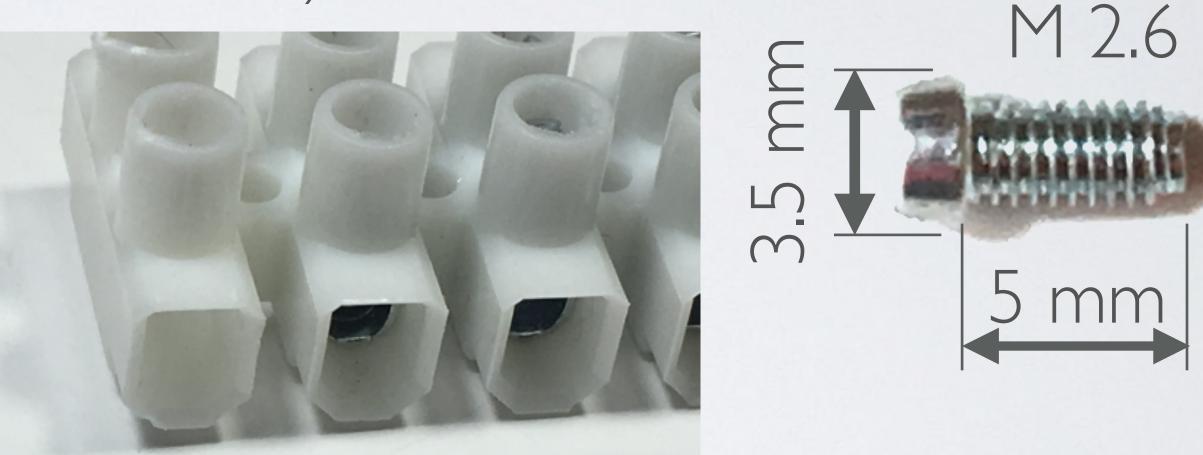


• Terminal strip block 1.5-4.0 mm² To be used for wires with a diameter of 1.38 mm - 2.26 mm Cost: € 1.98 (2 strips, each strip has 12 terminals)



I need the plastic blocks and the terminals!

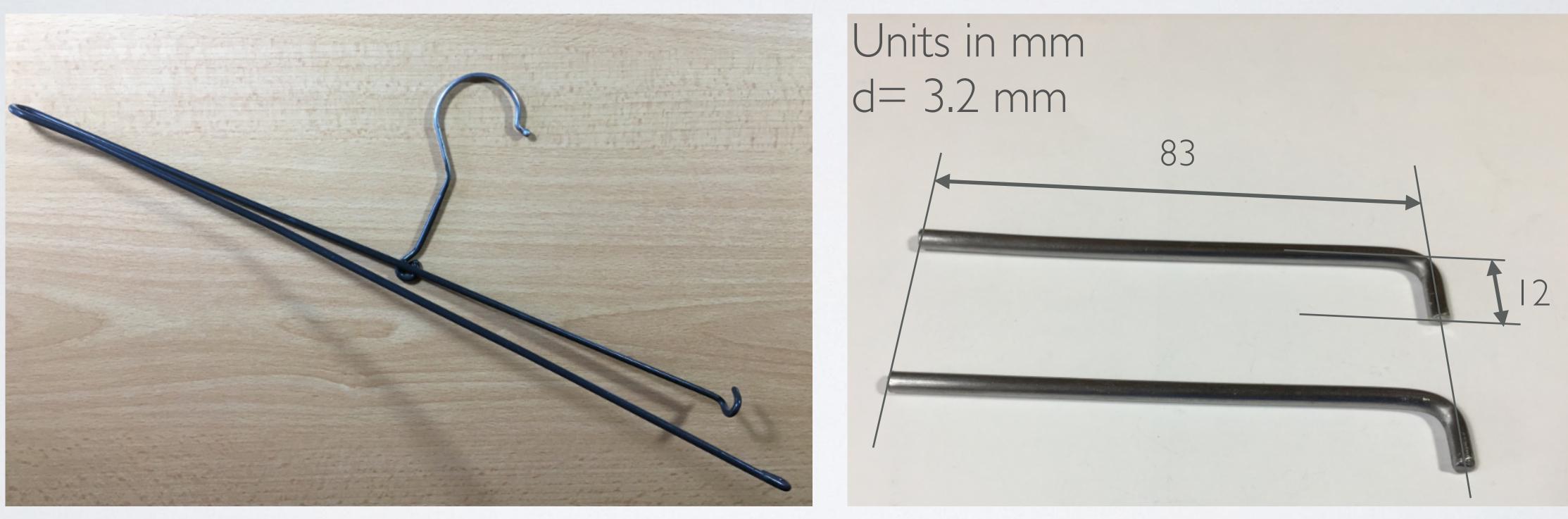






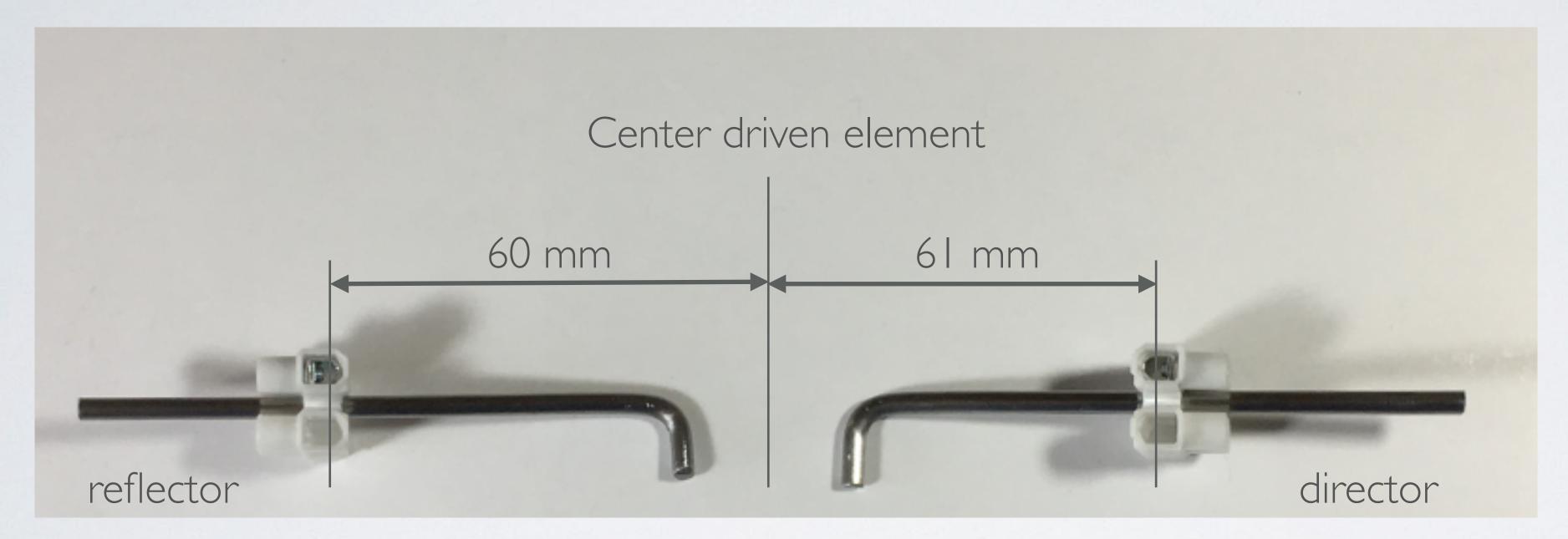


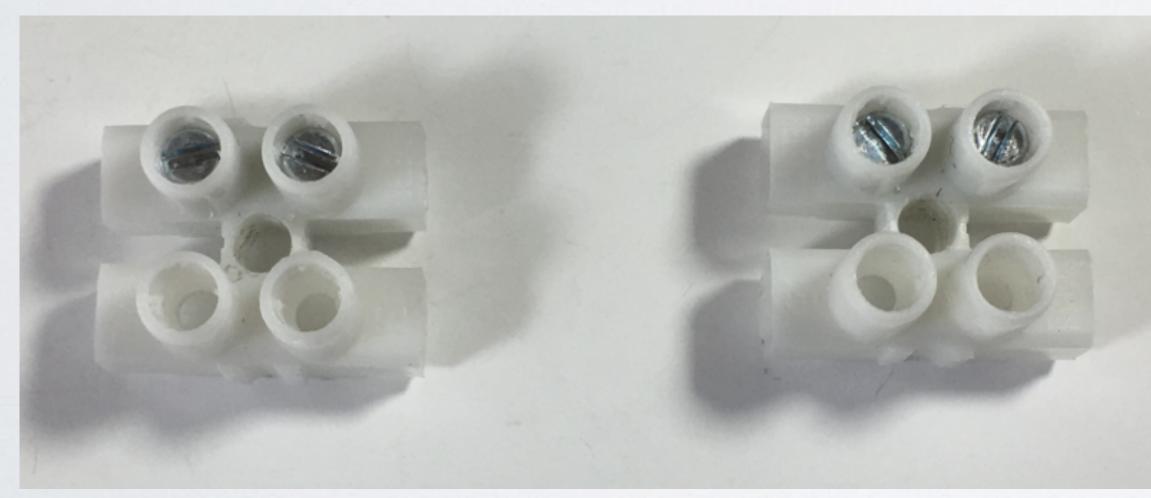
• The support boom is made from a metal cloth hanger. Cost: unknown











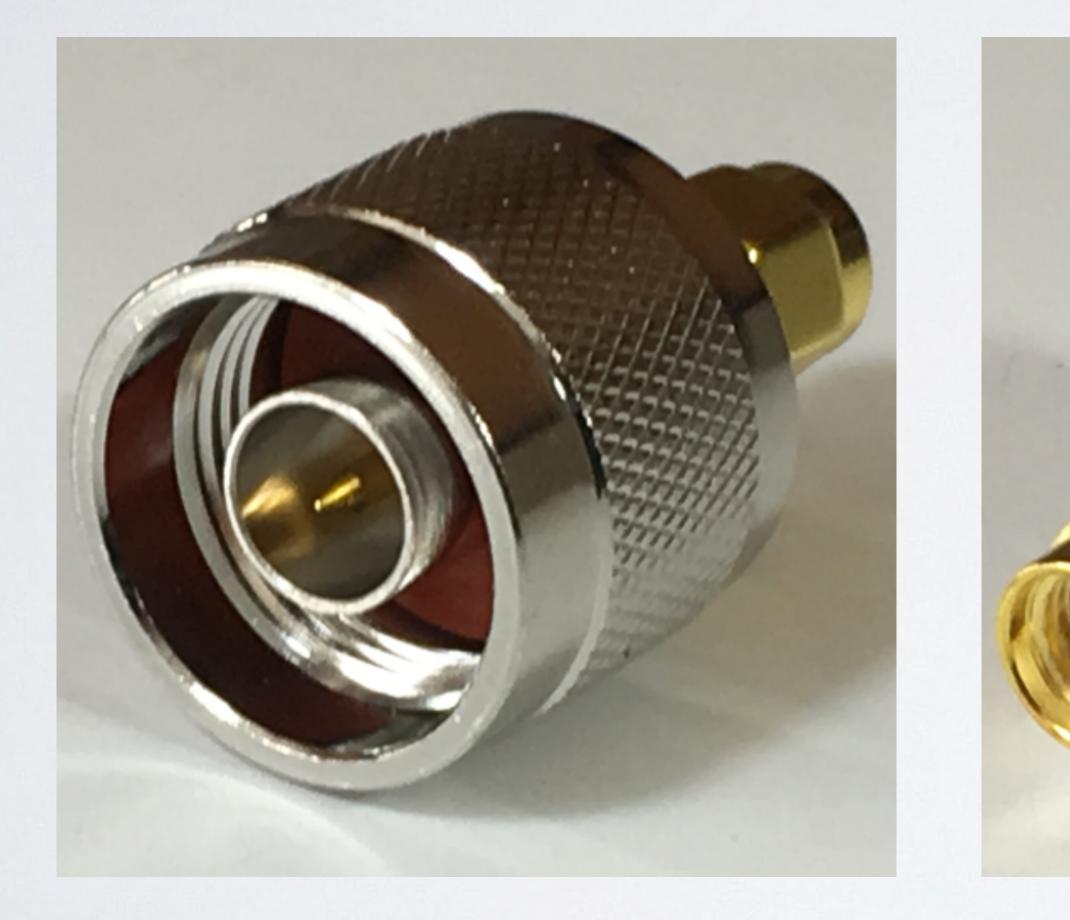
mobilefish.com



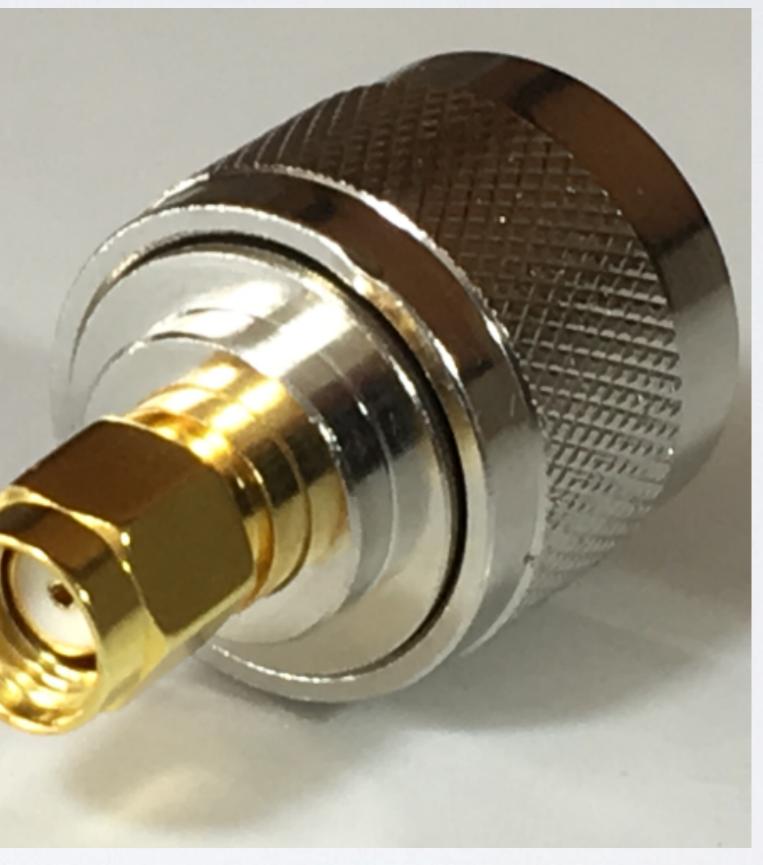
Plastic terminal blocks



• Type N male to RP-SMA male plug adapter coaxial cable connector. Cost: € 1.44









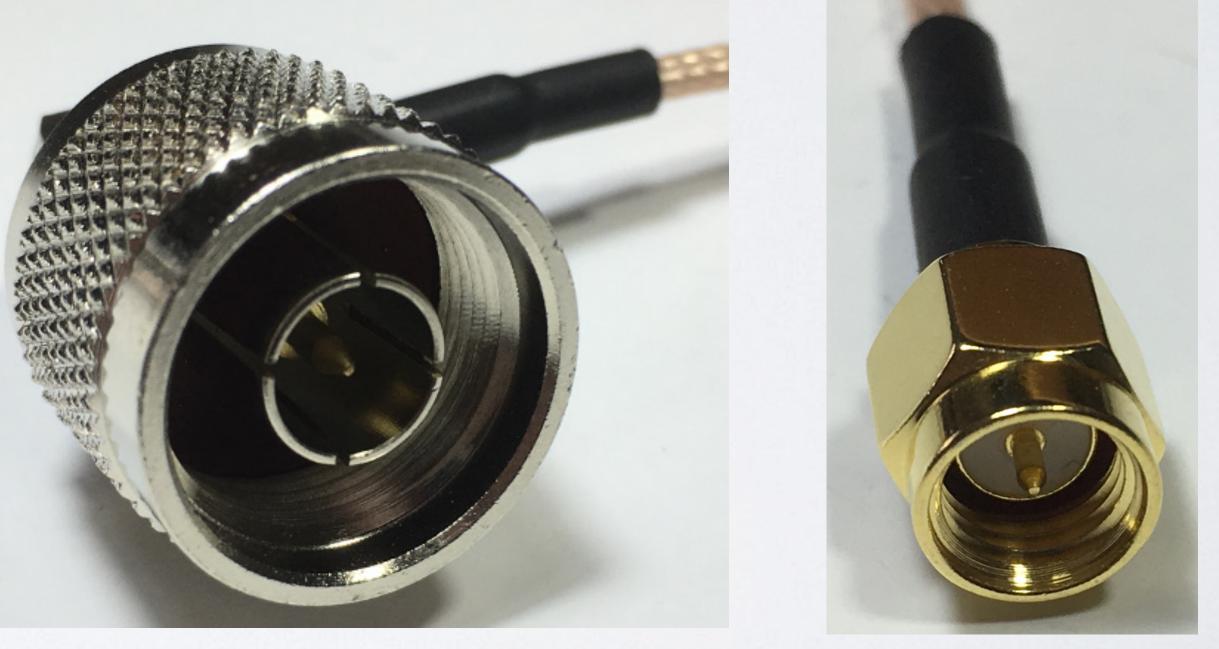
male connector. Impedance: 50Ω Coax: RG316 Cost: € 3.39



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• RF coaxial cable RG316, length 20 cm with type N male plug right angle to SMA





• Bolt: M4x10 (but preferable M4x12) Nut: M4 Metal washer 7.8 \times 4.4 \times 0.5 mm (outer diameter, inner diameter, thickness) Cost: unknown

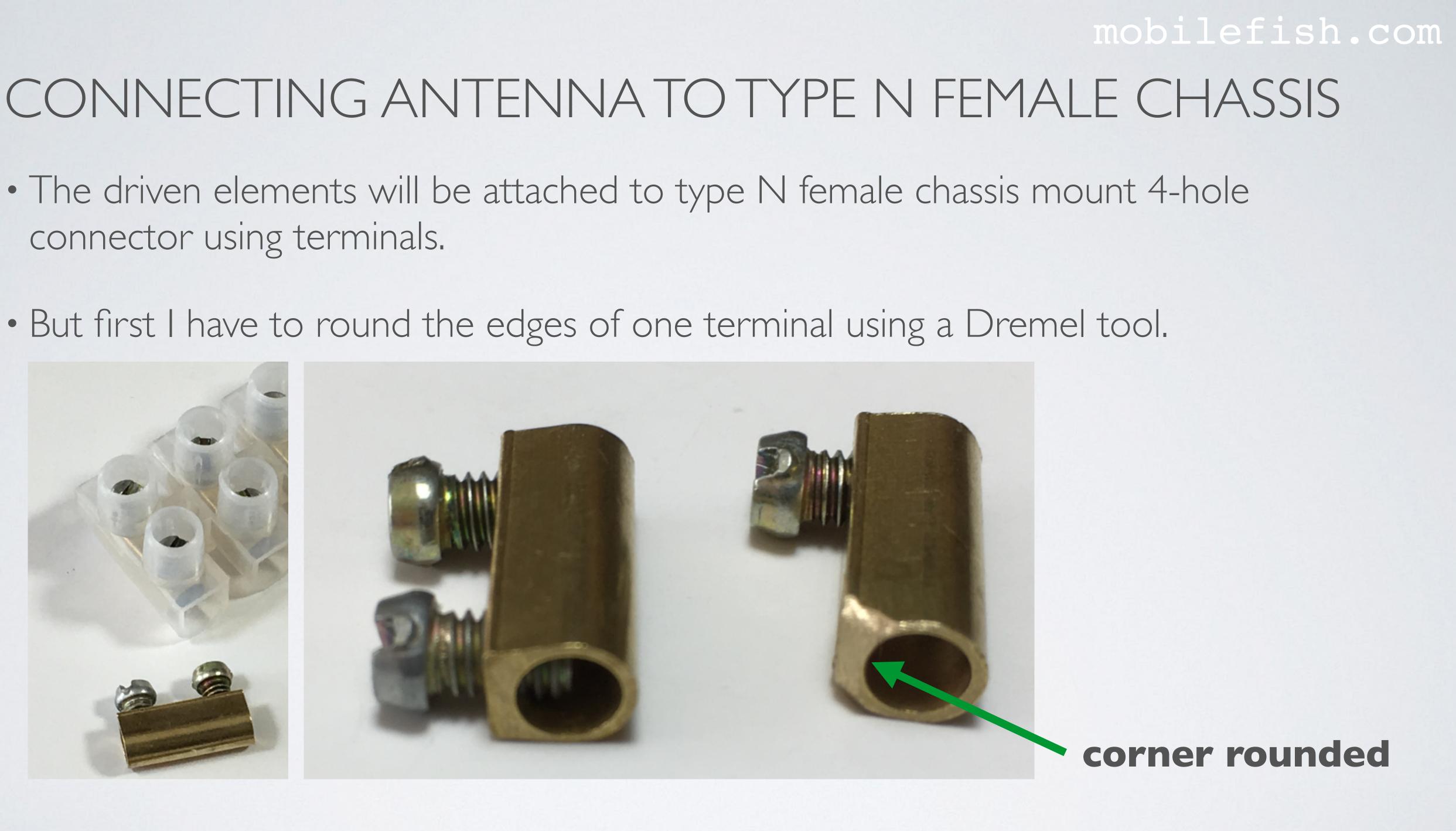




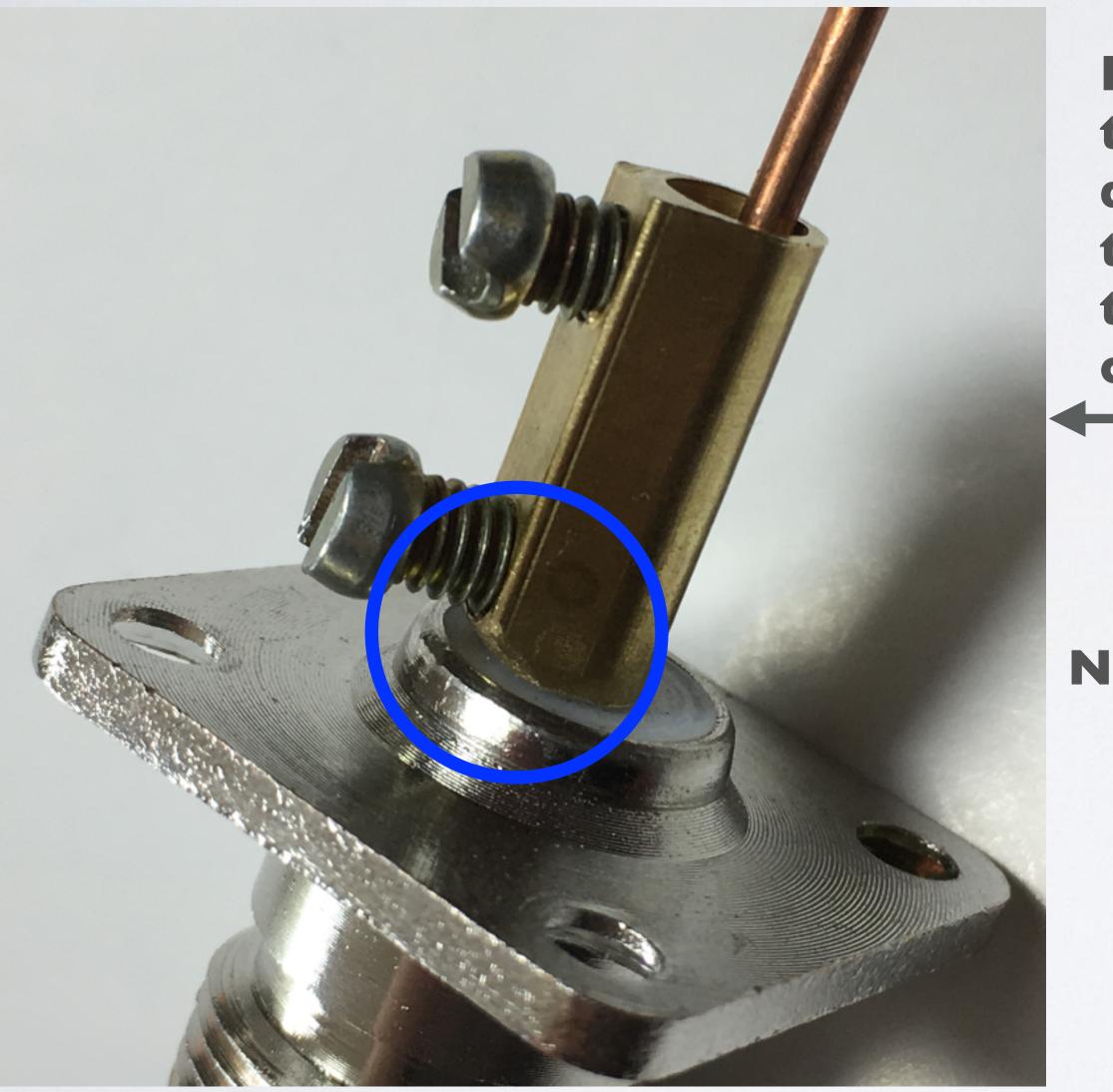


CONNECTING ANTENNA TO TYPE N FEMALE CHASSIS

- connector using terminals.

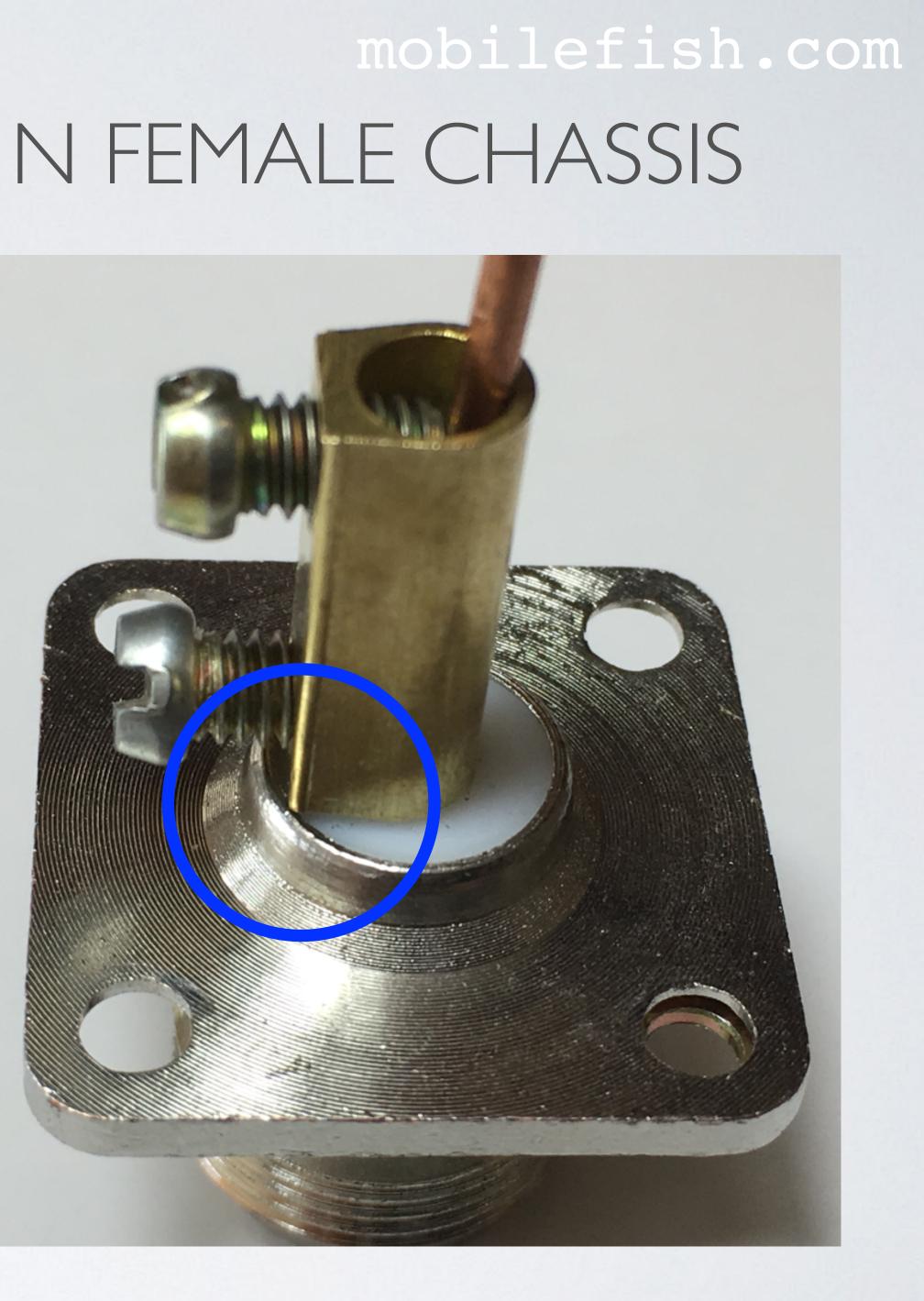


mobilefish. CONNECTING ANTENNA TO TYPE N FEMALE CHASSIS



Rounded, terminal does not touch the type N chassis.

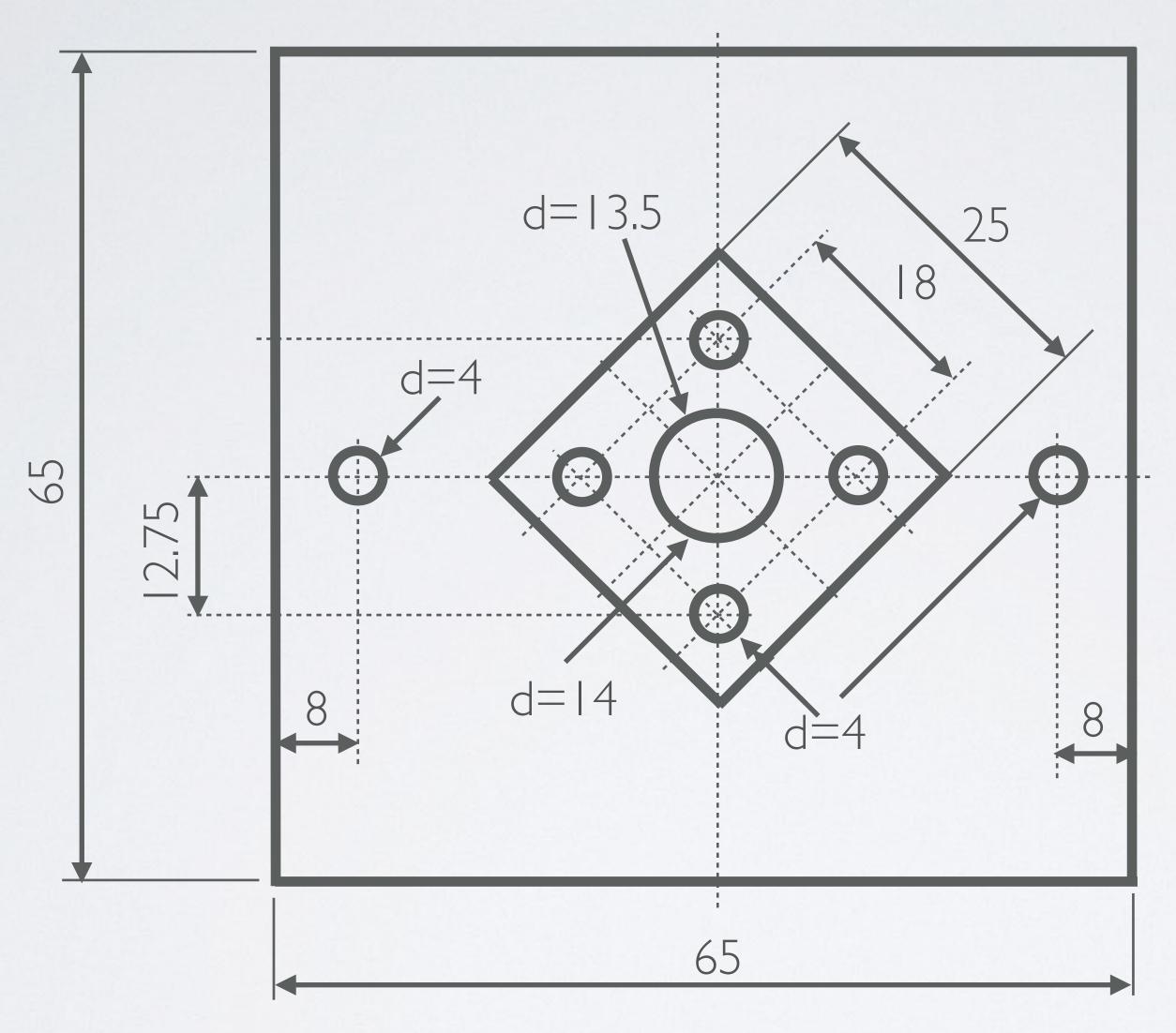
Not rounded, terminal does touch the type N chassis.



Cost: unknown





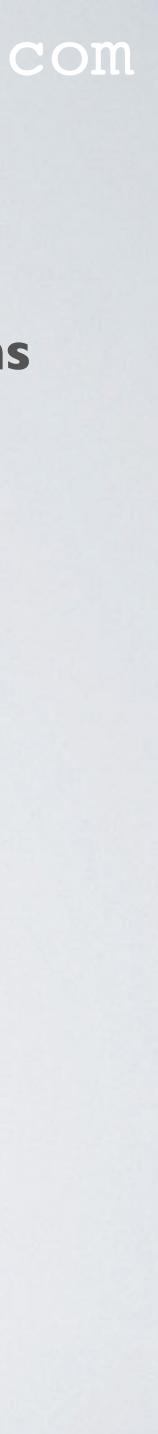


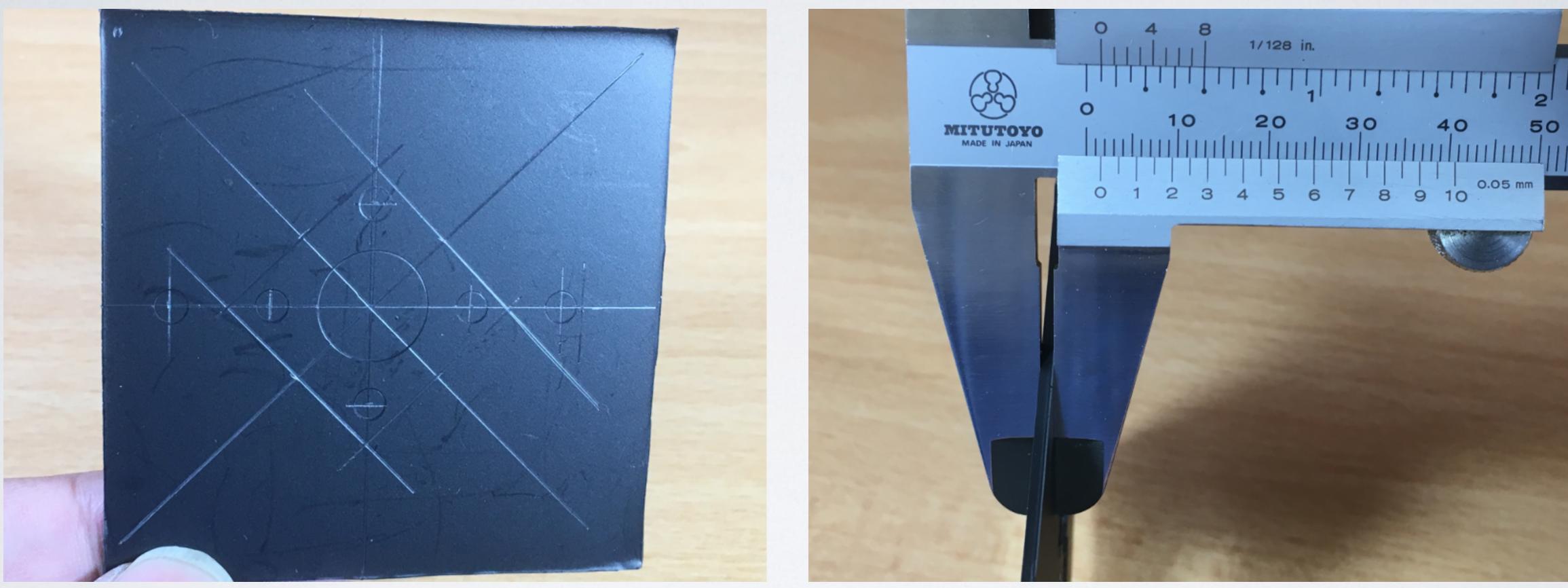
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Plastic plate dimensions

Units in mm Drawing not to scale

Thickness = 1.6 mm

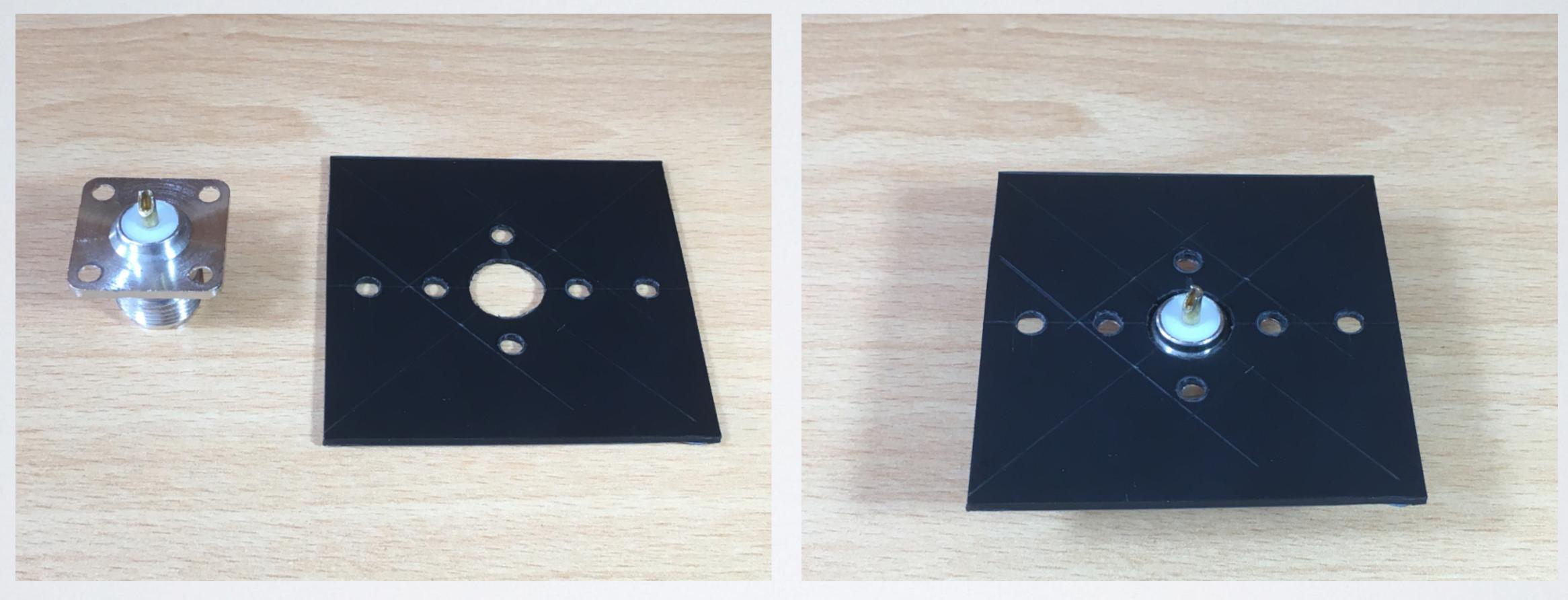




Mark out the locations where holes need to be drilled.



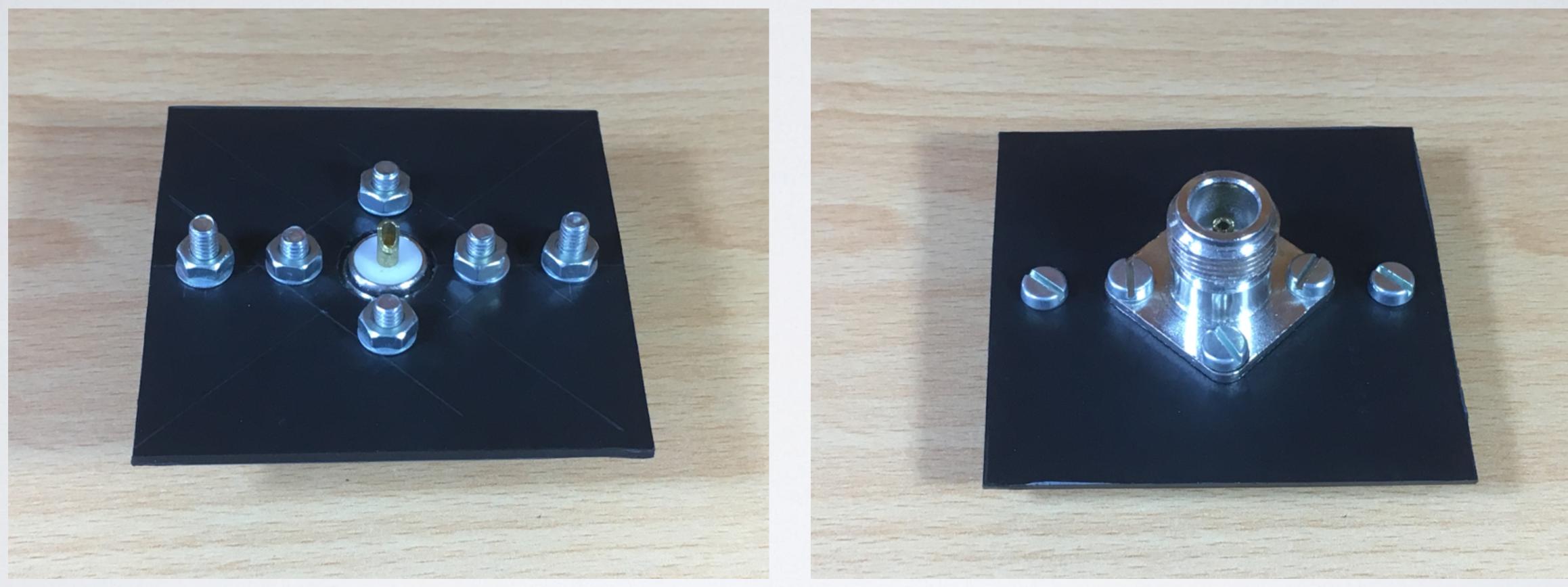








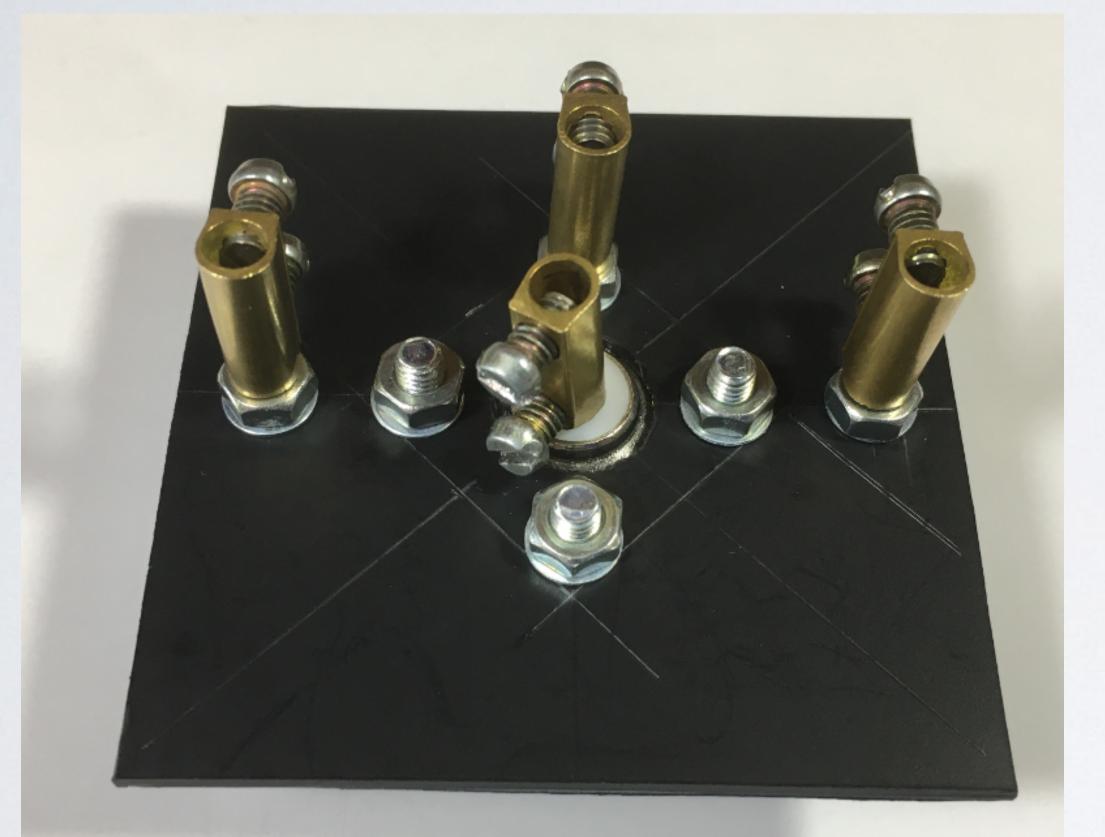




Attach plastic plate to type N connector.







Attach the terminals.

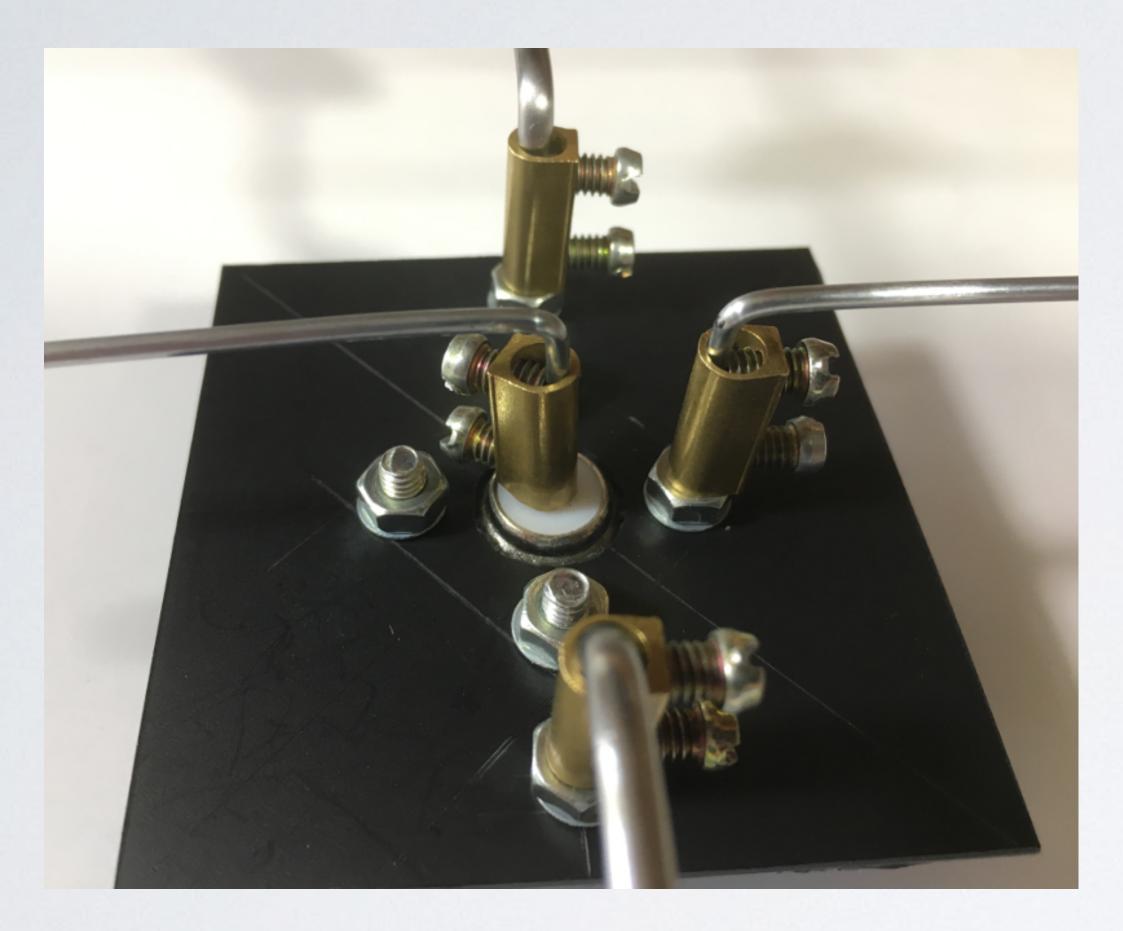
mobilefish.com





Attach driven element & support booms.

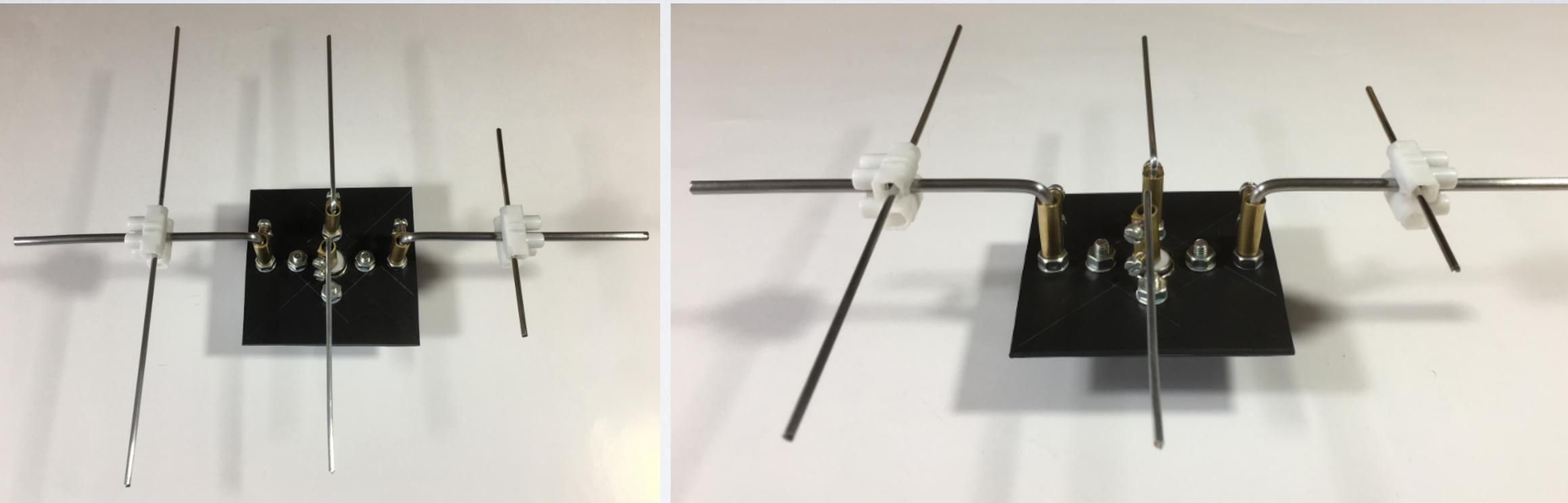




Attach driven element & support booms.

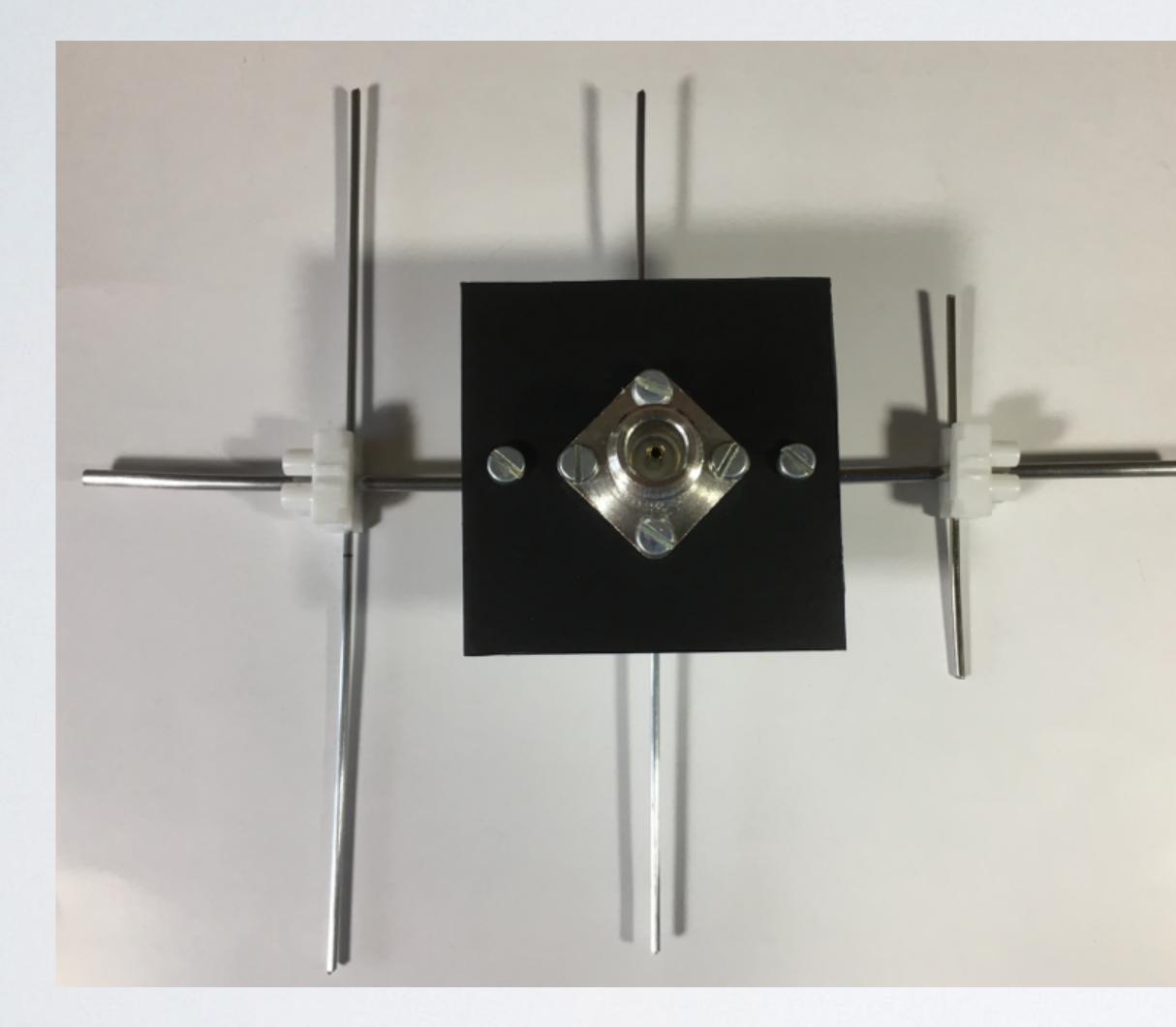






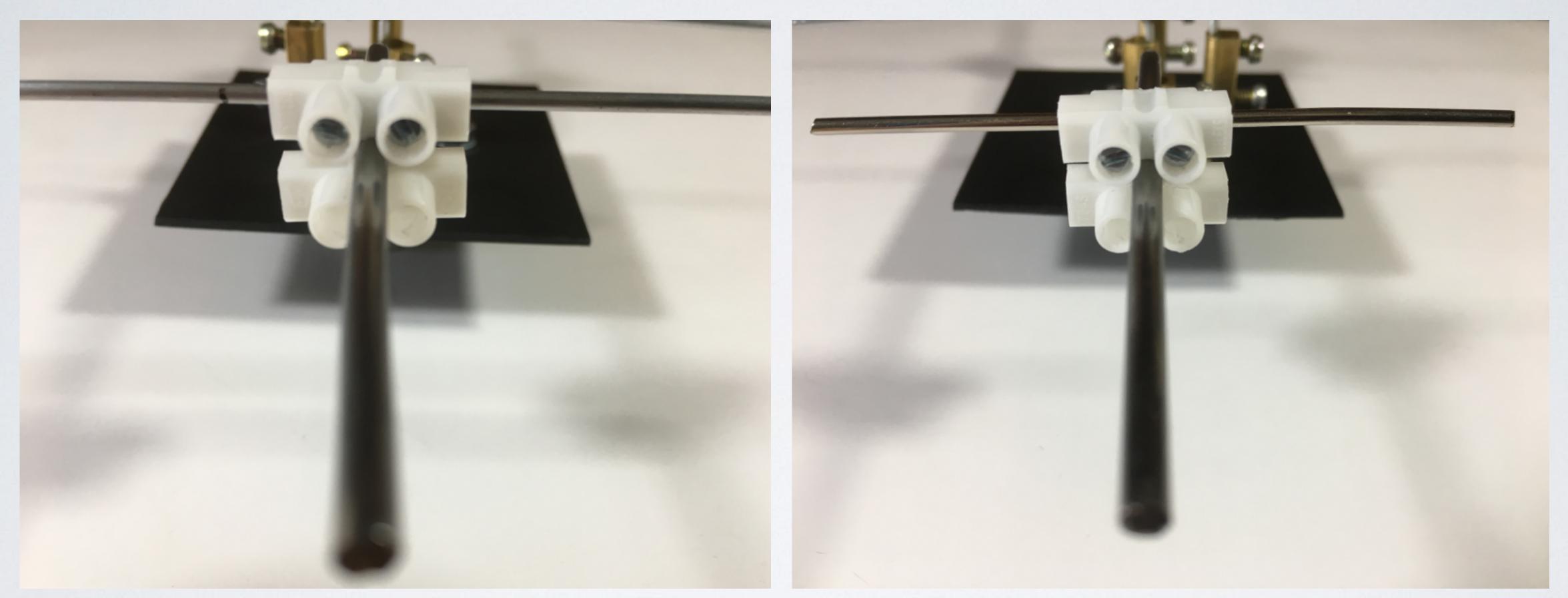
Attach reflector and director





Bottom view.



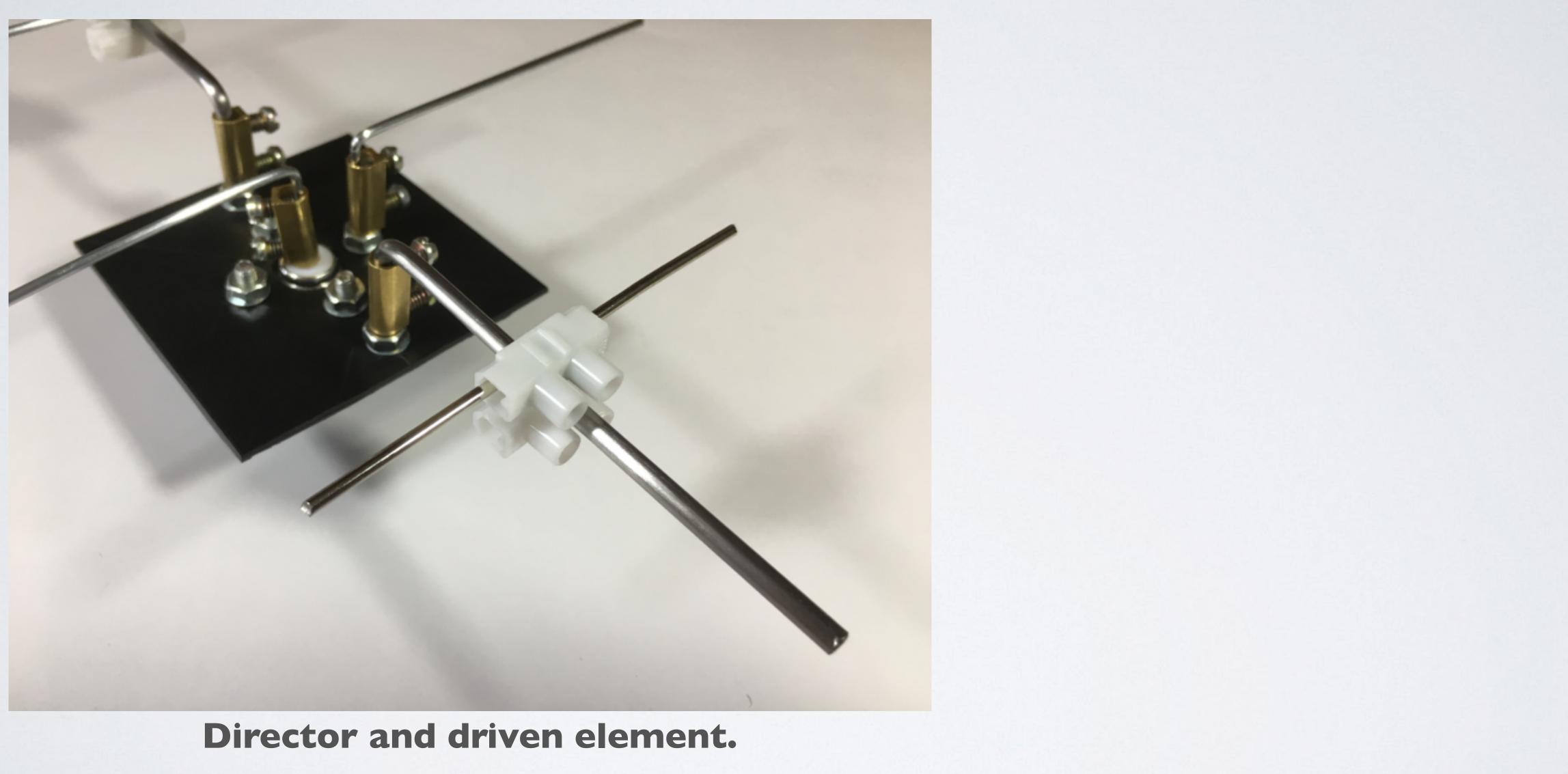


Terminal strip block and reflector

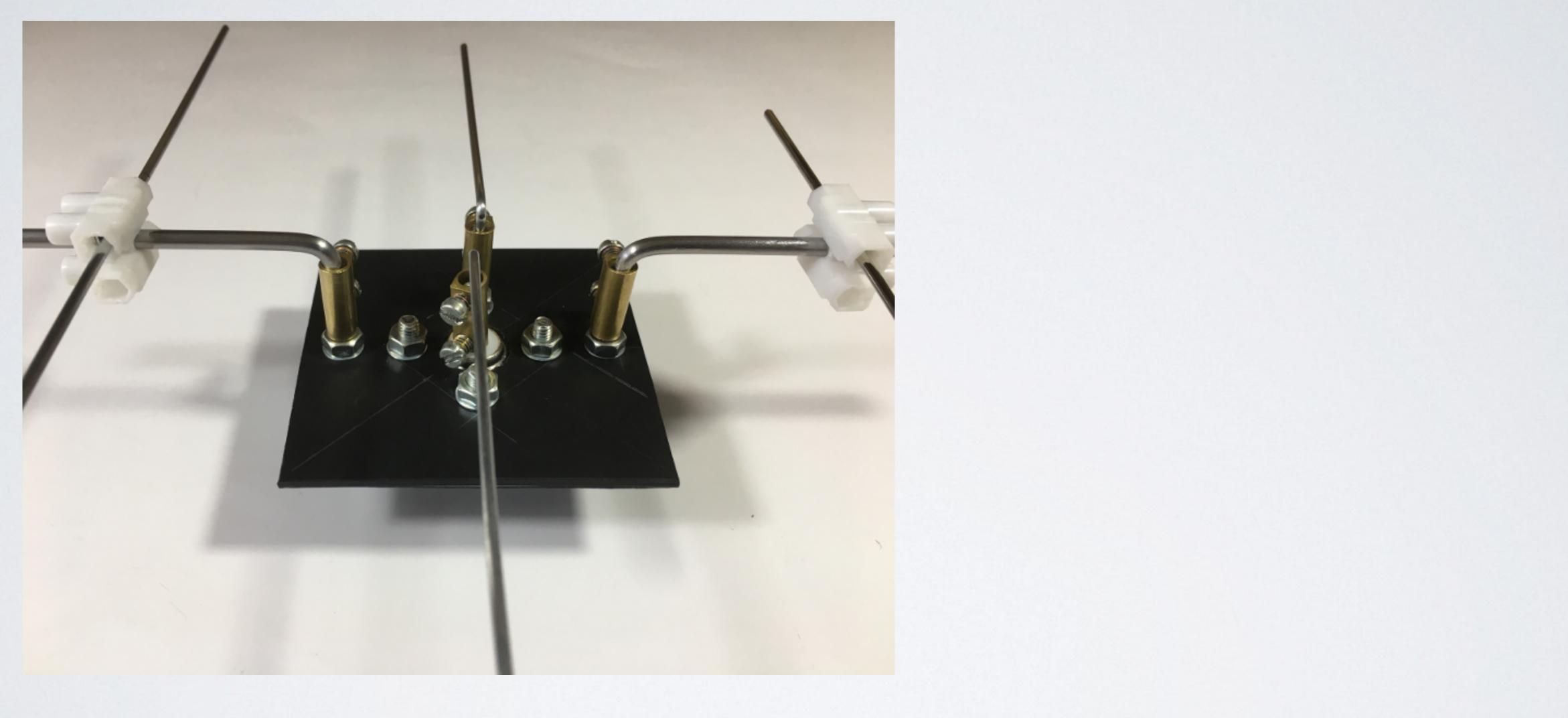
mobilefish.com

Terminal strip block and director





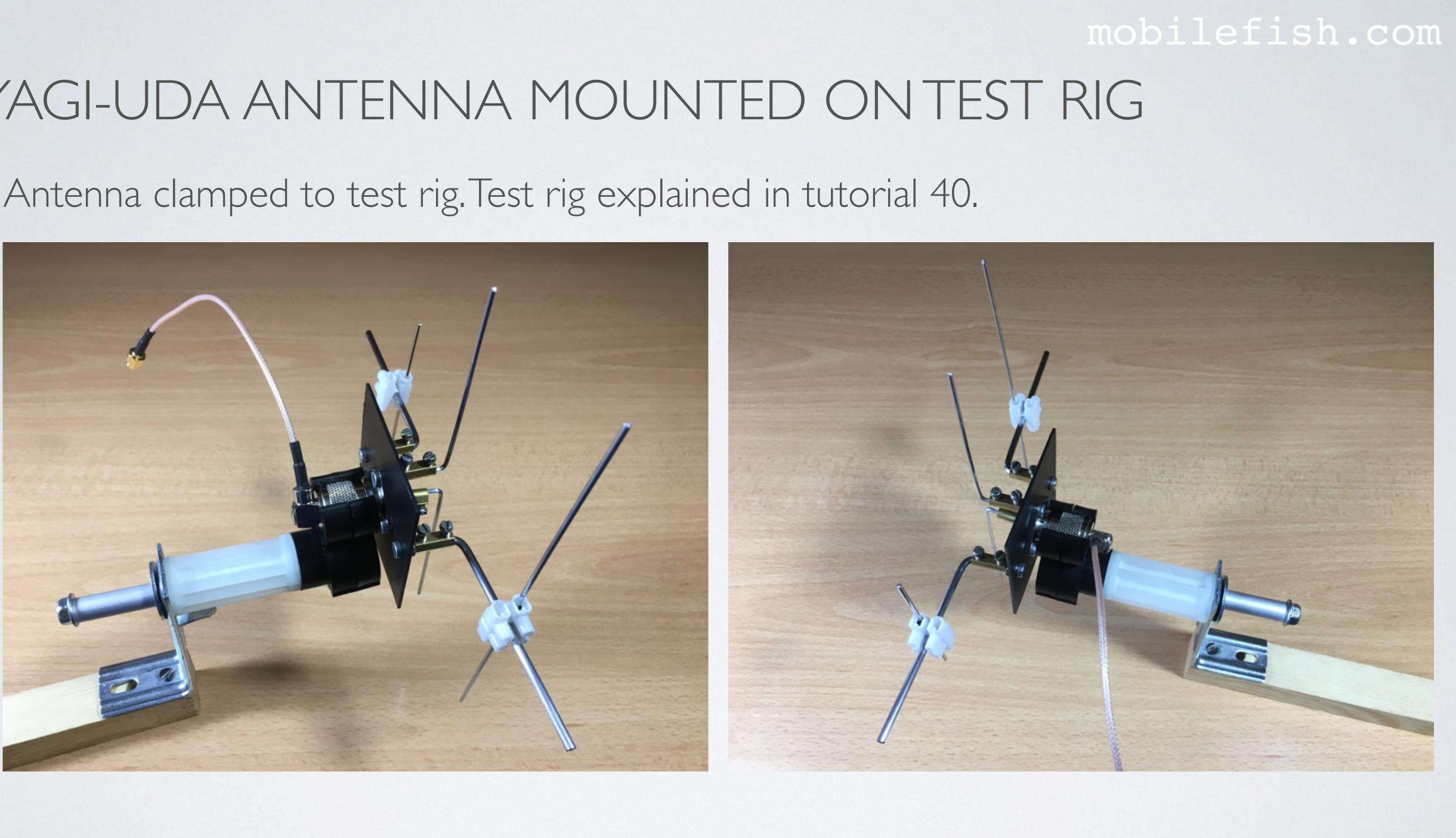


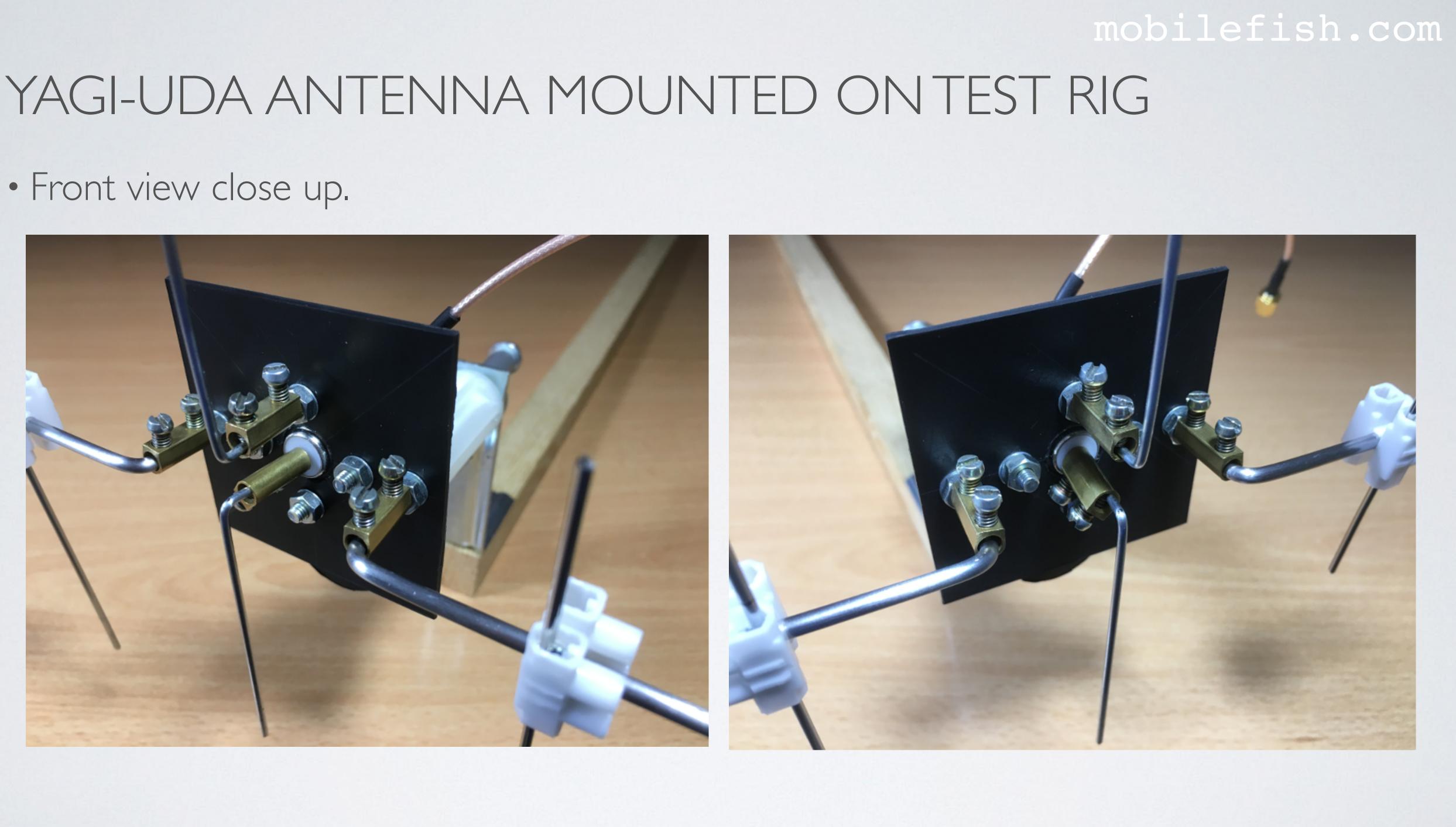


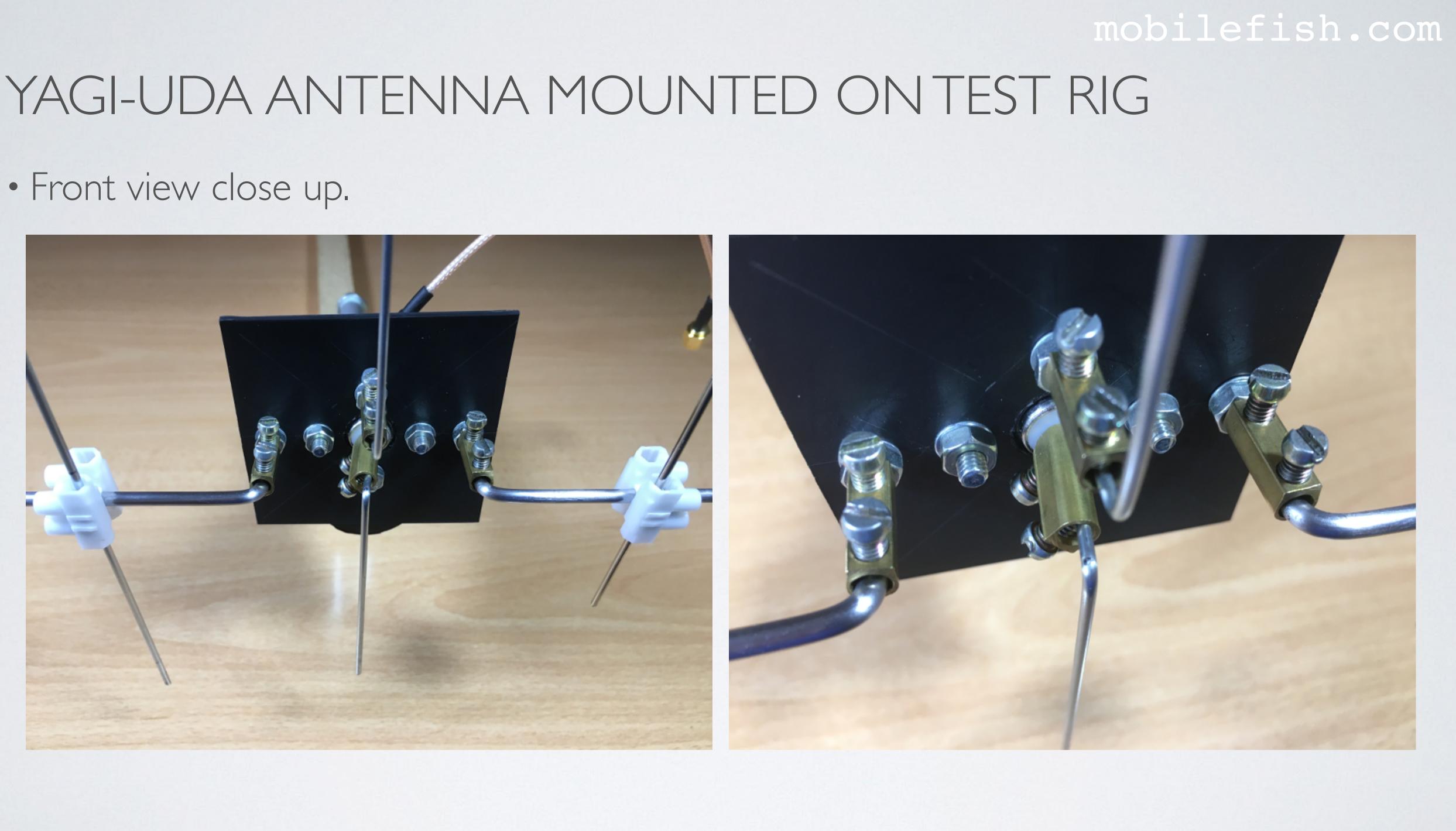
Close up reflector, driven element, director and support booms.



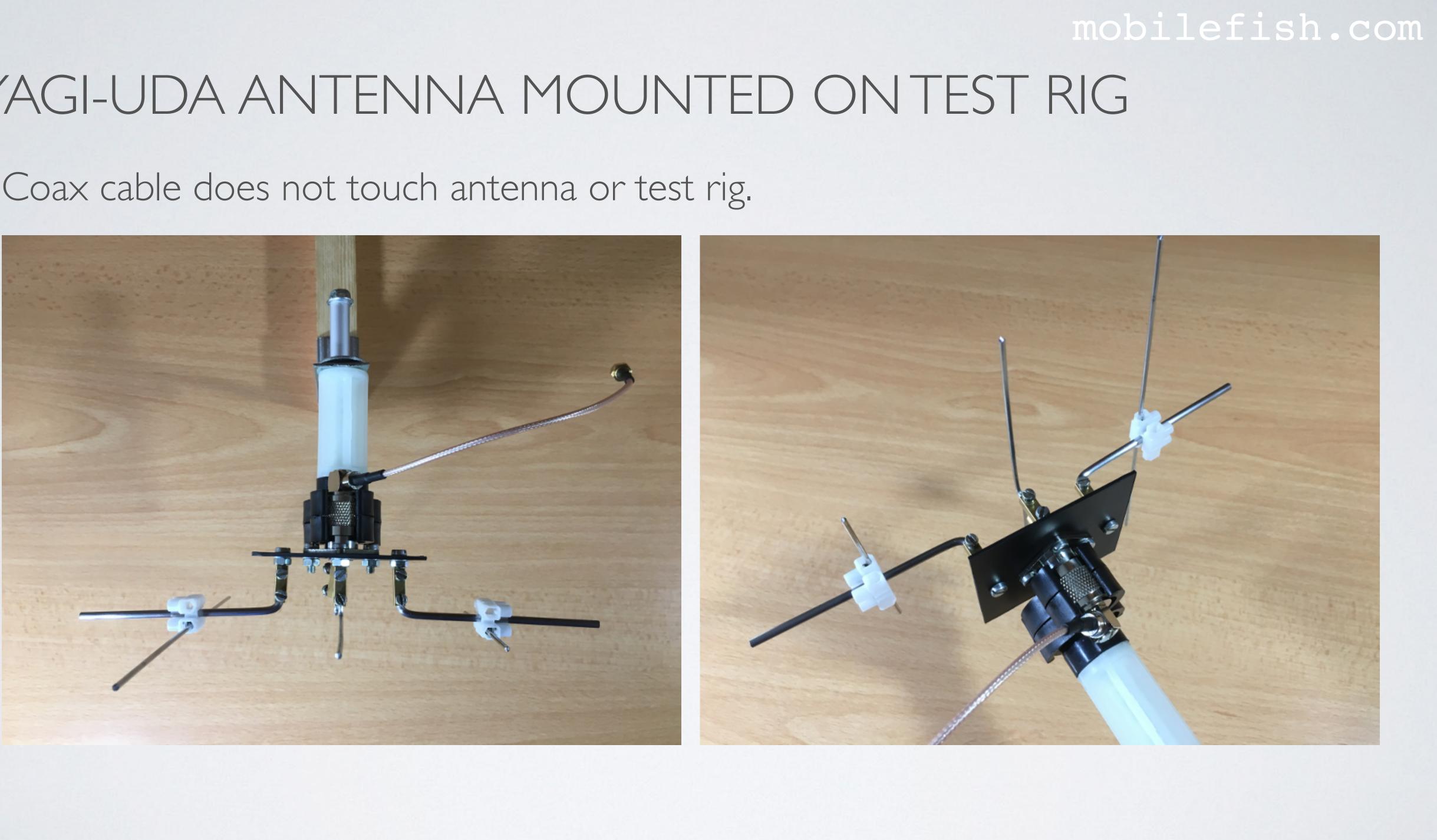
• Antenna clamped to test rig. Test rig explained in tutorial 40.

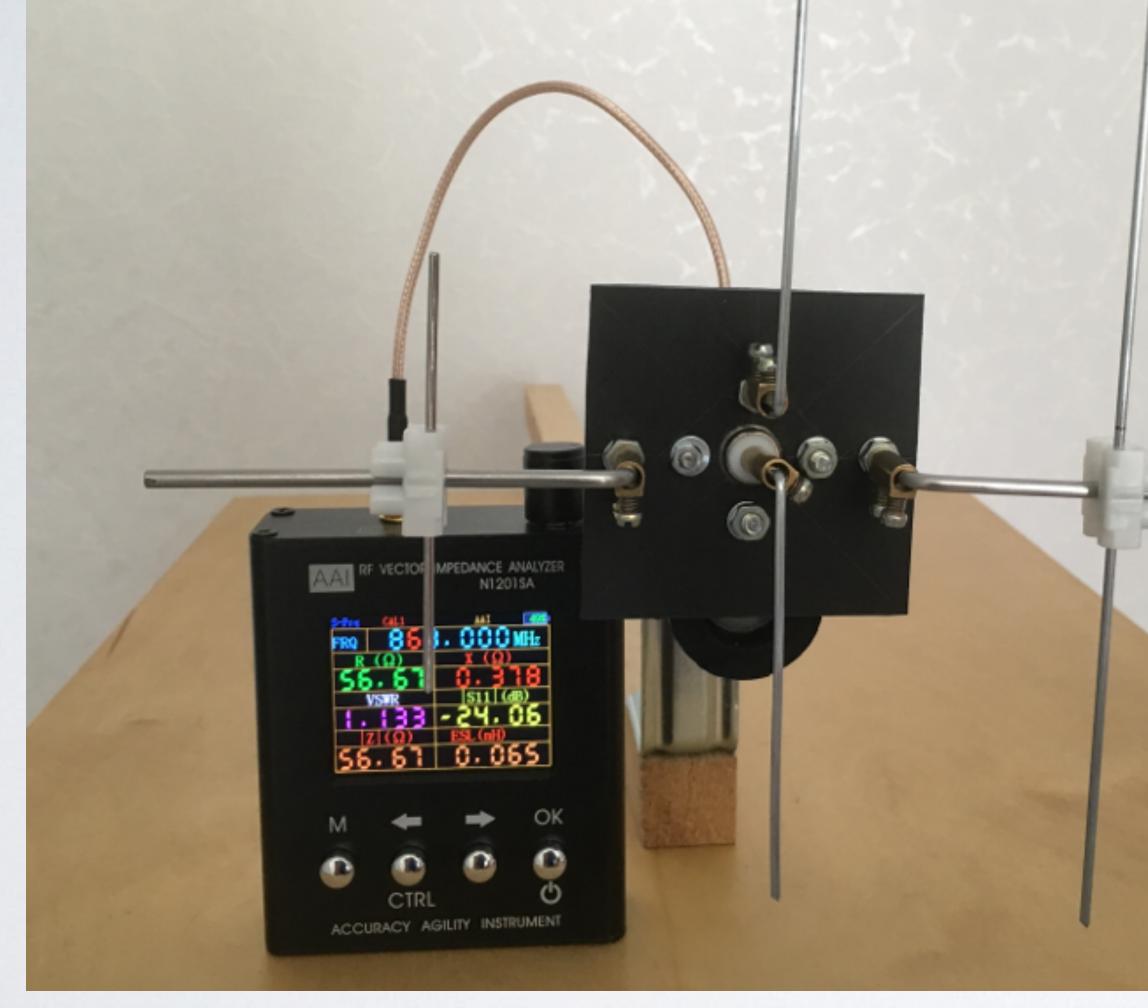






• Coax cable does not touch antenna or test rig.





Measuring antenna parameters

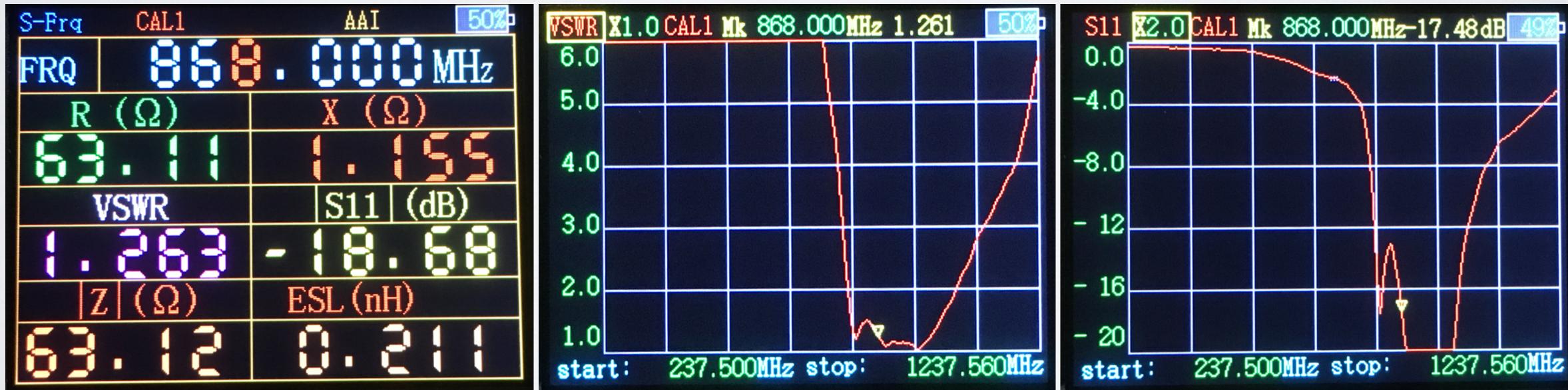
mobilefish.com

The antenna analyser with the Yagi-Uda antenna.



MEASURED ANTENNA PARAMETERS

• Based on the Yagi-Uda design: VSWR \approx 1.3 $Z \approx 63\Omega$ SII \approx -19 dB



mobilefish.com

Good. It is < 2Not good. Should be approx. 50Ω

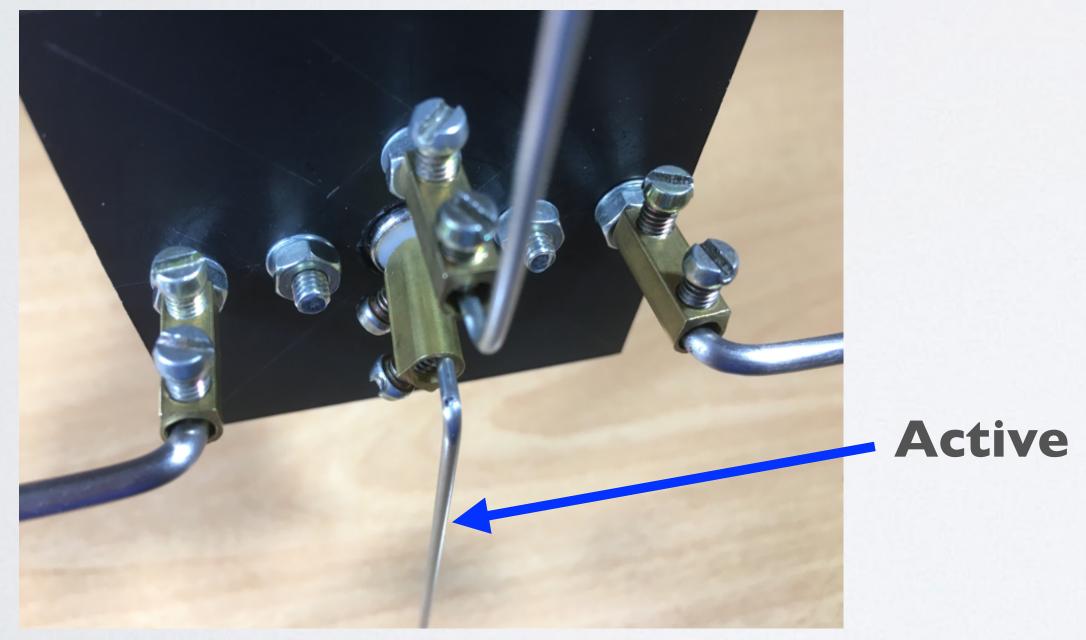


MEASURED ANTENNA PARAMETERS





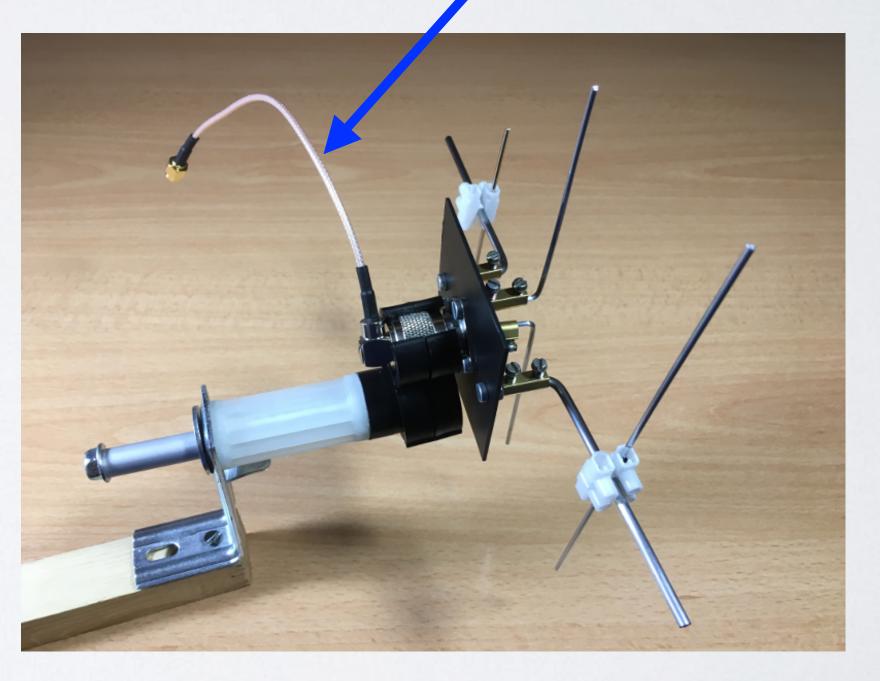
- It is not recommended to use the RF coaxial cable RG316, if you bend the coax RG316.
- Point the active element downwards.



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cable the antenna analyser will show a different result. Use a better quality (thicker) coax cable e.g. RG58. The RG58 has lower signal loss but is less flexible compared to

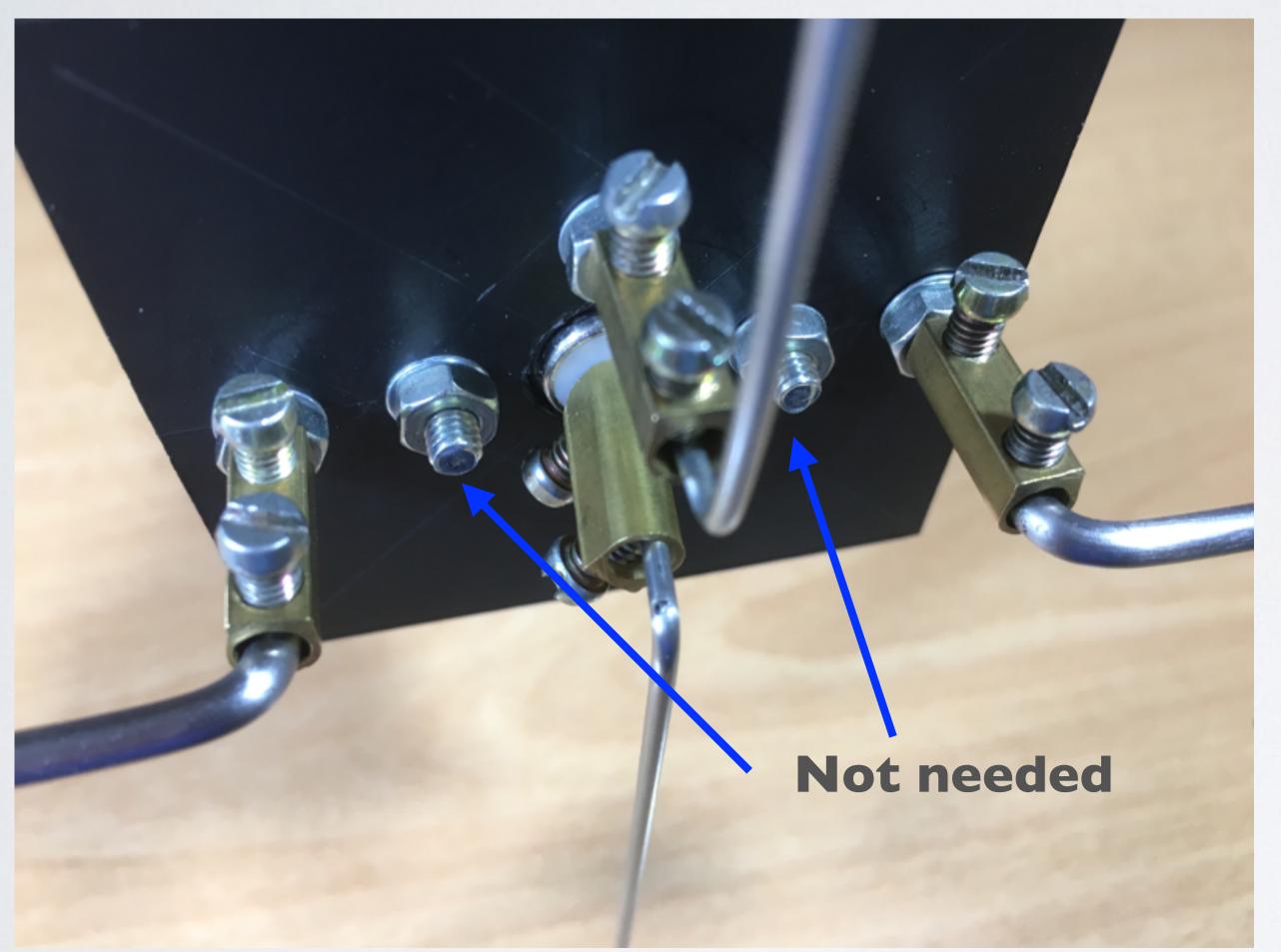
RF coaxial cable RG316



Active element



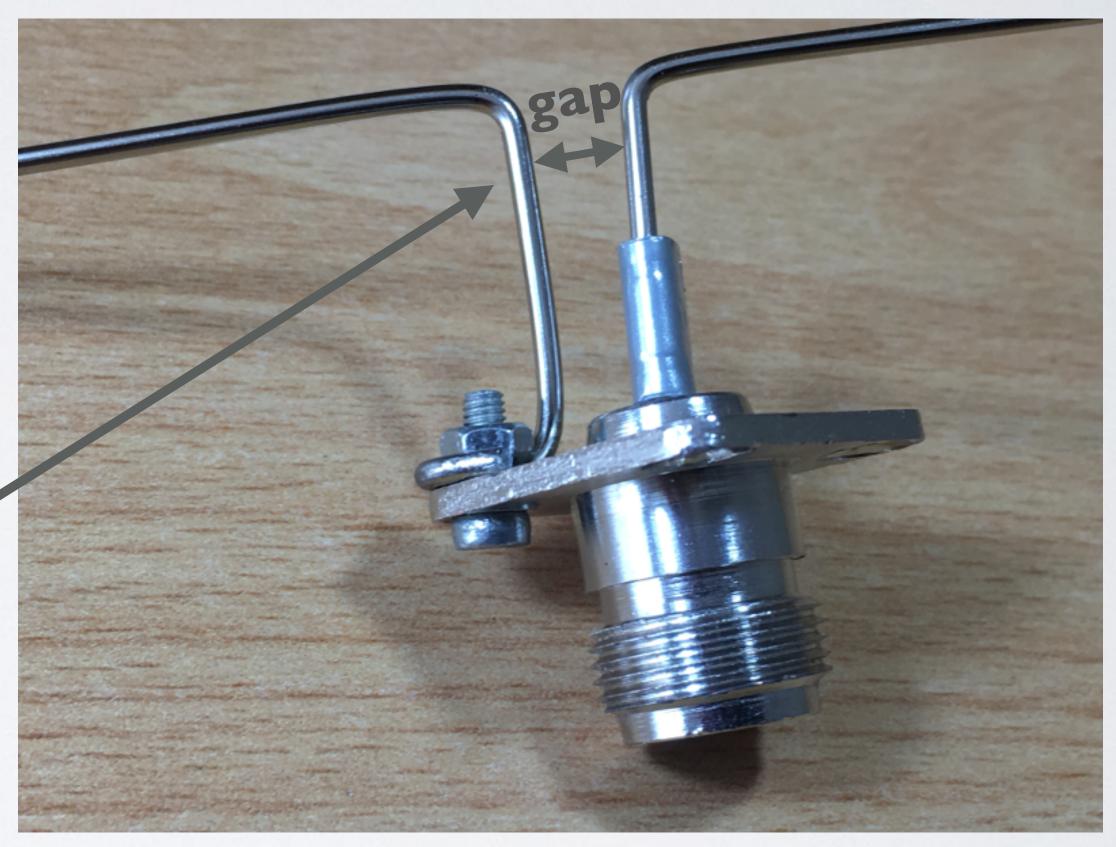
• Minimise the use of bolts and nuts.





• Minimise the use of terminals.







• Use smaller terminals.

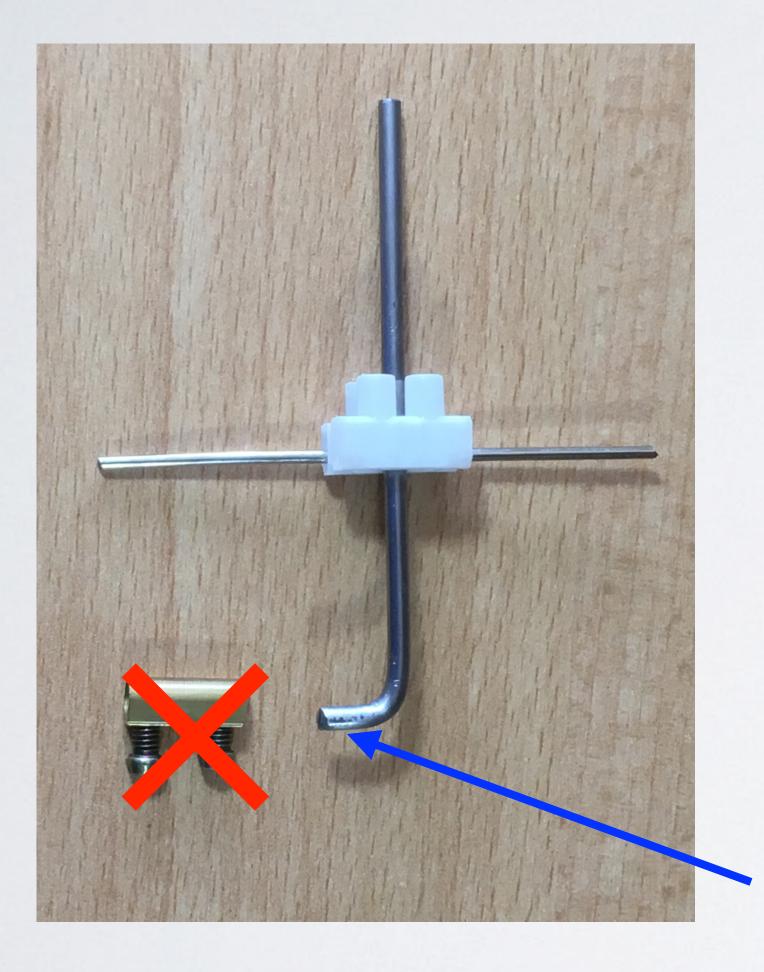


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If possible use a smaller terminal.



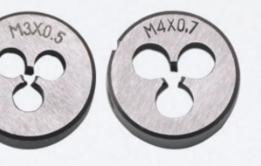
• Use a die set to cut threads on the support booms. I have not tried this myself!





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Use a die to thread the metal rod.



Cut threads at the end and use two nuts to attach the boom to the plastic plate.



ANTENNA PERFORMANCE TESTS

- How well does my self build Yagi-Uda ar performance tests will be conducted.
- Performance test A:

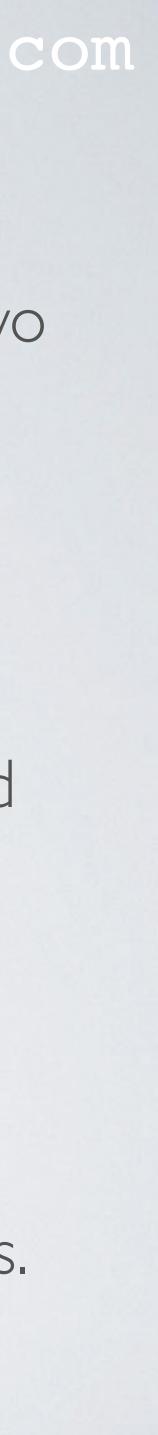
The Yagi-Uda antenna is attached to an end node, which is located inside a building, and transmit messages which will be received by nearby gateways in my area. In this test I am only interested which gateways were able to receive the transmitted sensor data. The test will be repeated using a sleeve dipole antenna.

• Performance test B:

The Yagi-Uda antenna is attached to an end node and transmit messages which will be received by a dedicated gateway 6 meters away. Both devices are indoors. The average RSSI is calculated and also the total time it took to receive 15 messages. The test will be repeated using a $\frac{1}{2}\lambda$ dipole antenna.

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• How well does my self build Yagi-Uda antenna performs? To answer this question, two



ANTENNA PERFORMANCE TESTS

- Performance test A and B are simple tests and will give me a ROUGH
- Both tests are conducted indoors which means the walls reflects the transmitted signals thus influencing the measurements. Therefore take the results with a grain of salt!
- see this procedure: https://github.com/LoRaTracker/AntennaTesting

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INDICATION how well my antenna performs compared to the dipole antenna.

• A much better method to tell how your antenna actually performs in the real world,

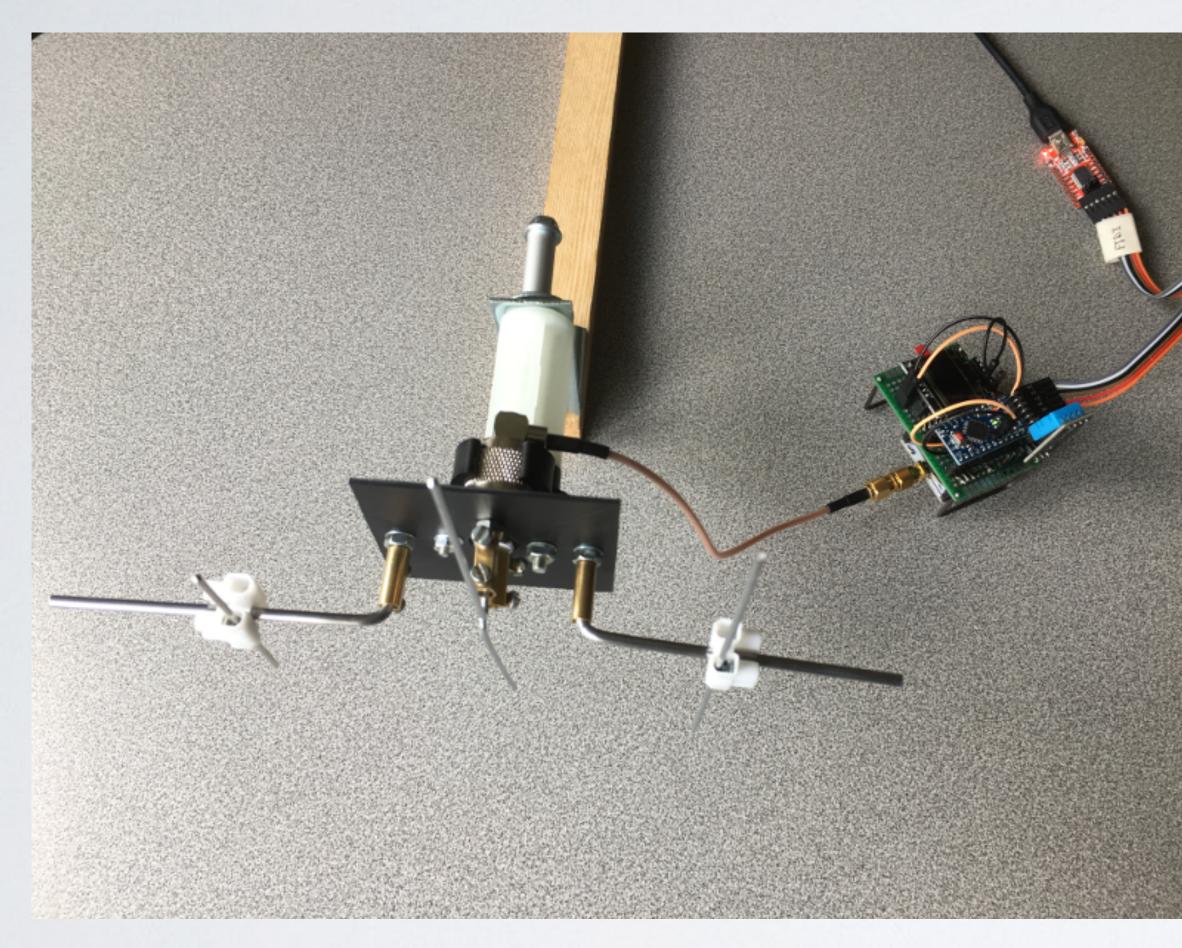


- The Yagi-Uda antenna performance is compared with a sleeve dipole antenna. More information about sleeve dipole antennas, see tutorial 43.
- More information about this end node, see: https://www.mobilefish.com/developer/lorawan/ lorawan quickguide build lora node rfm95 arduino pro mini.html
- The end node uses the MCCI LoRaWAN LMIC Library: https://github.com/mcci-catena/arduino-Imic
- The end node uses the following sketch: https://www.mobilefish.com/download/lora/ttn-otaa-pro-mini-sensors.ino.txt

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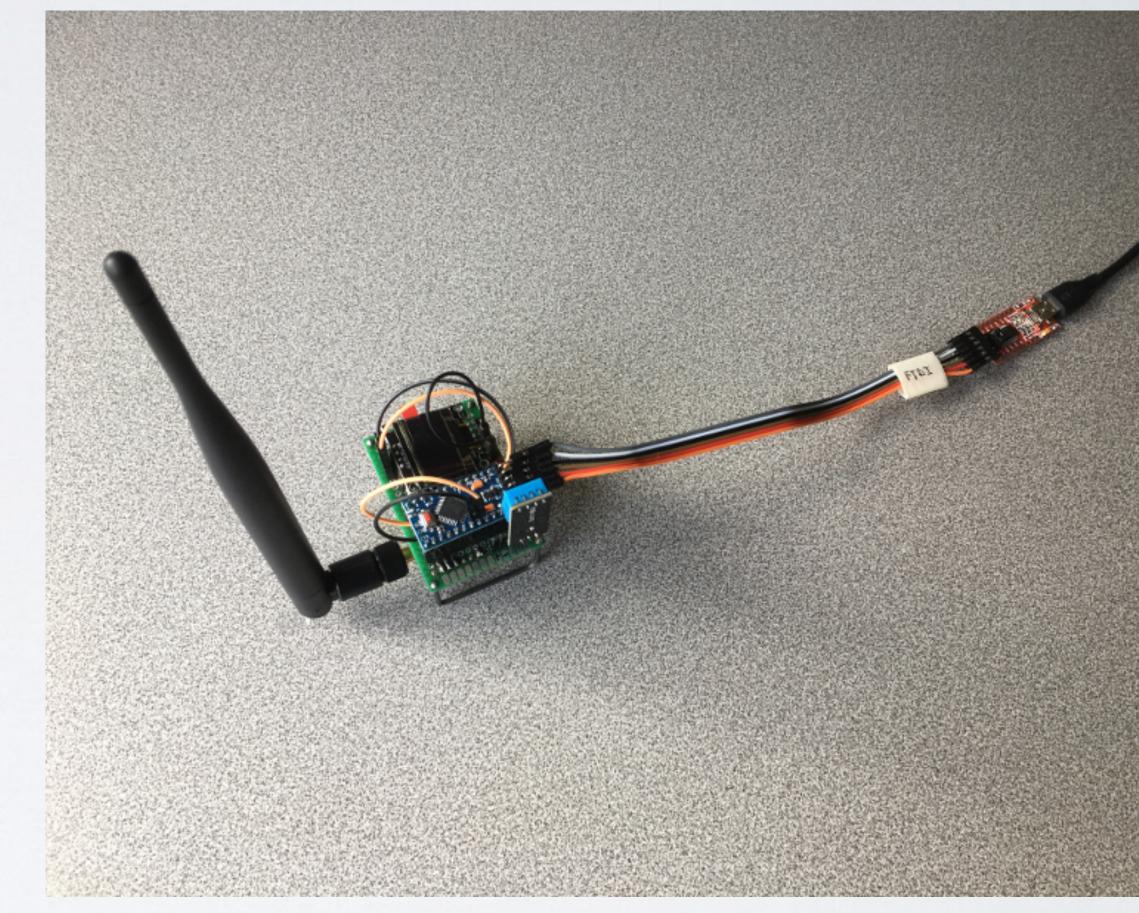
• For this test I am using the end node and antenna C as demonstrated in tutorial 33.





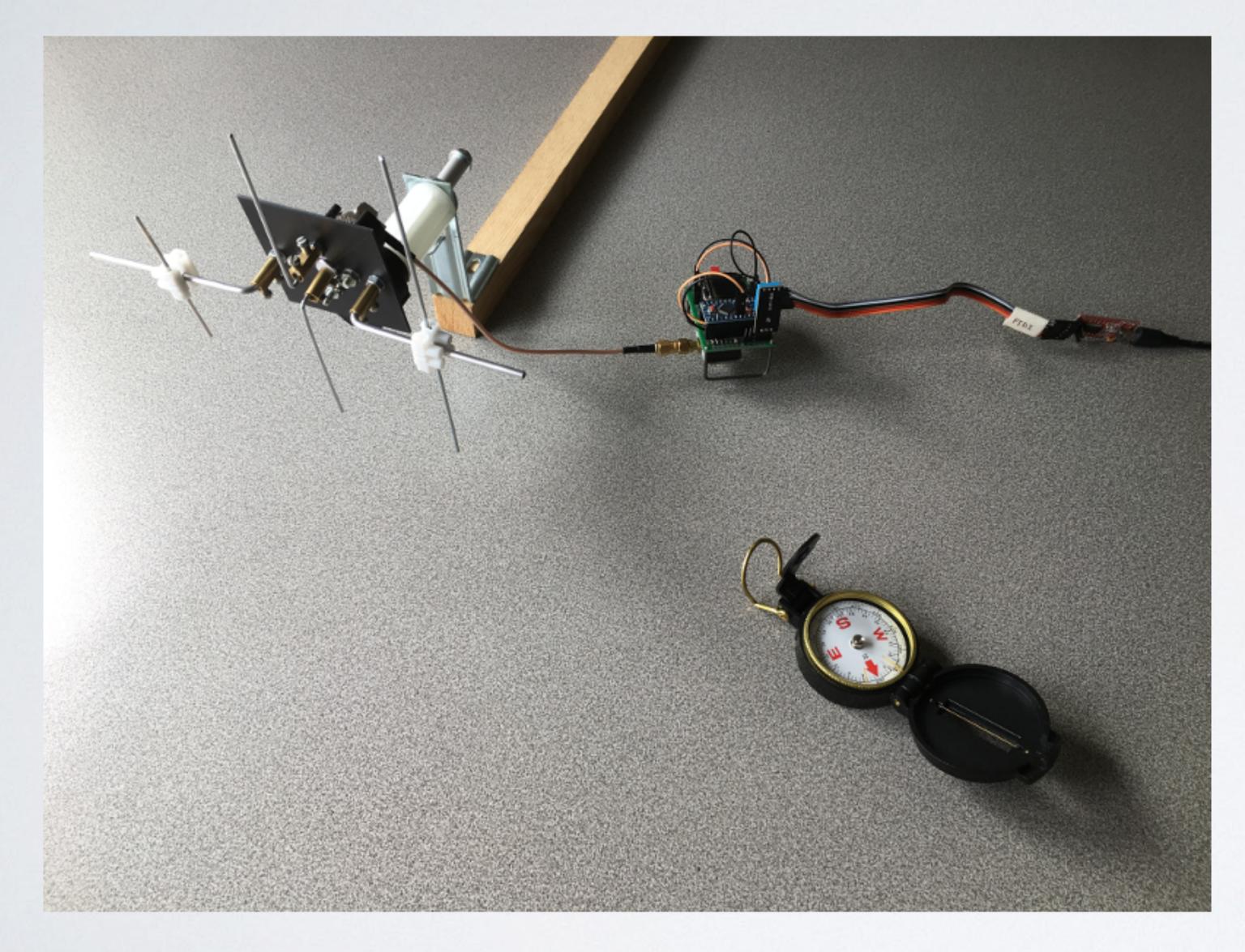
Yagi-Uda + end node

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Sleeve dipole + end node



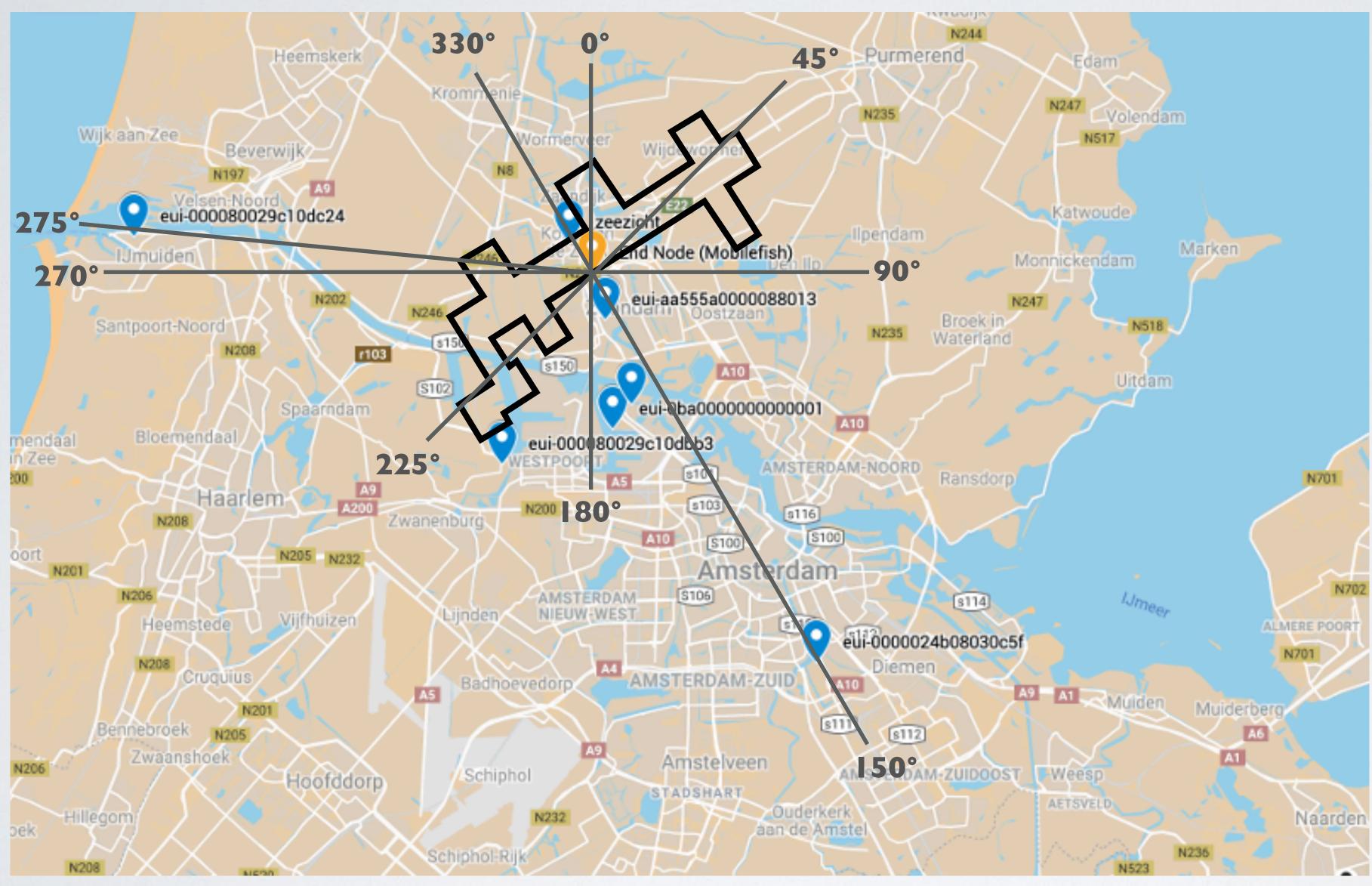


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Use a compass to point the Yagi-Uda antenna to different directions.



ANTENNA TEST SETUP



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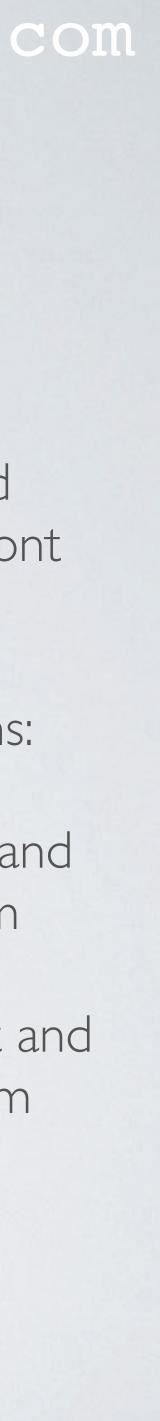
The building circumference.

The end node is placed inside the building in front of a window.

Two end node locations:

Location A, facing East and South. Altitude = ~IIm

Location B, facing West and North. Altitude = ~ 11 m



- antenna.
- In my area there are several gateways and I know that these gateways, which are connected to The Things Network, can receive my transmitted data.
- I have done the same with the sleeve dipole antenna. In both cases two messages per minute were transmitted.
- The logged data can be found at: https://www.mobilefish.com/download/lora/yagi_uda_test_results.txt

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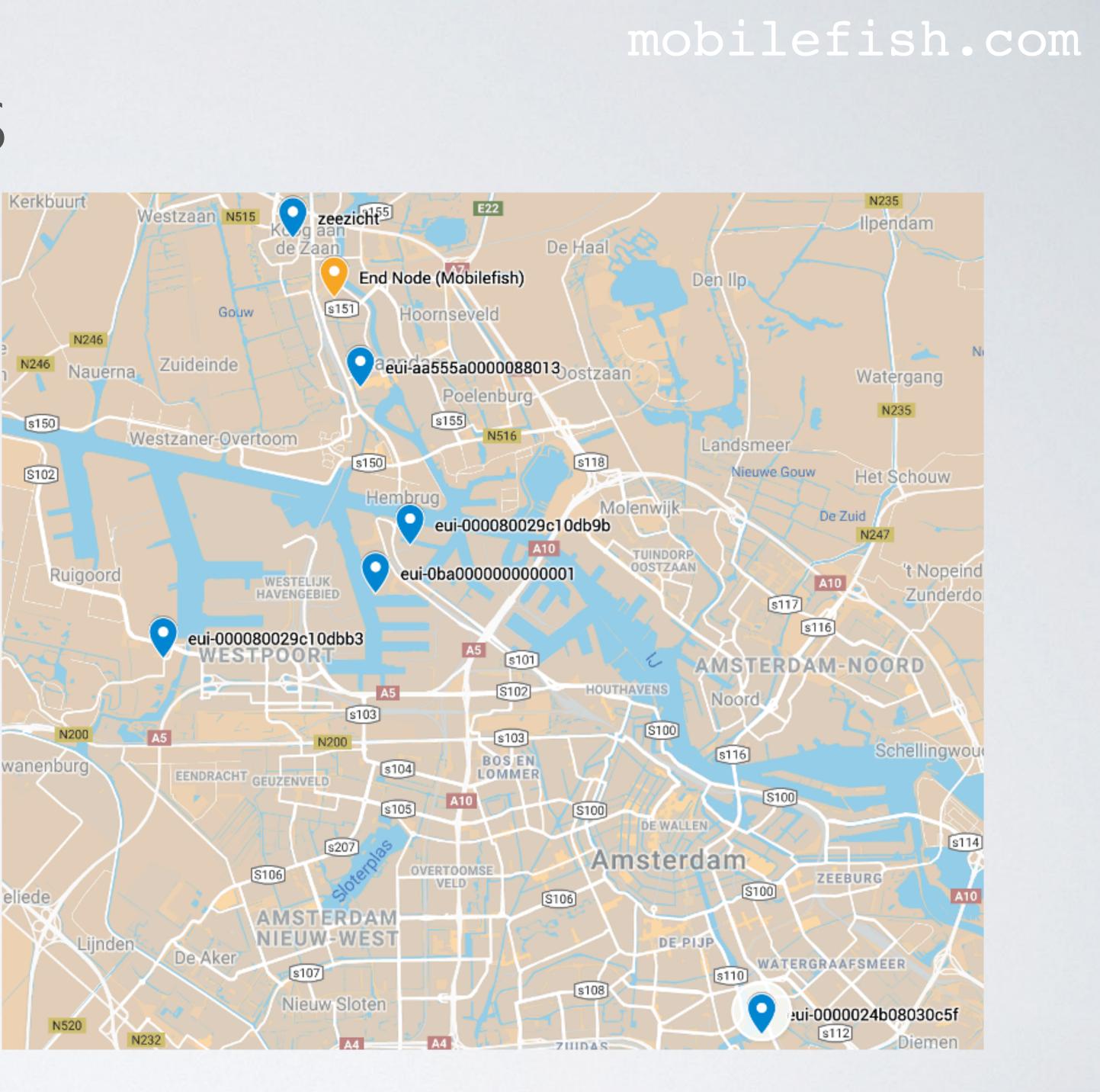
• I have NOT modified the end node transmission power when using the Yagi-Uda

• The Yagi-Uda antenna is attached to the end node at location A and transmits data.



ANTENNA TEST RESULTS

 One or more gateways were able to receive my transmitted sensor data, see: https://drive.google.com/open? id=18SKbHVEIFHU6YjzYpgZL98v uHcmV4OPQ&usp=sharing



End node tx power = 14 dBm
 Data from: yagi_uda_test_results.txt

Gateway	Distance from end device [km]	Altitude [m]	Sleeve dipole	Yagi-Uda
eui-aa555a0000088013	1.57	42		
eui-0ba00000000000000000	5.03	20		
eui-0000024b08030c5f	14.4	40		
eui-000080029c10db9b	4.36	30		
eui-000080029c10dbb3	6.73	5		
zeezicht	1.23	10		

The Yagi-Uda antenna was pointed to different directions. Green = Gateway has received the transmitted sensor data.

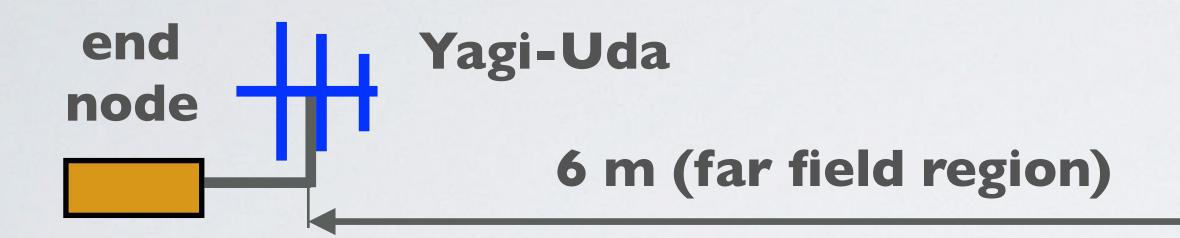


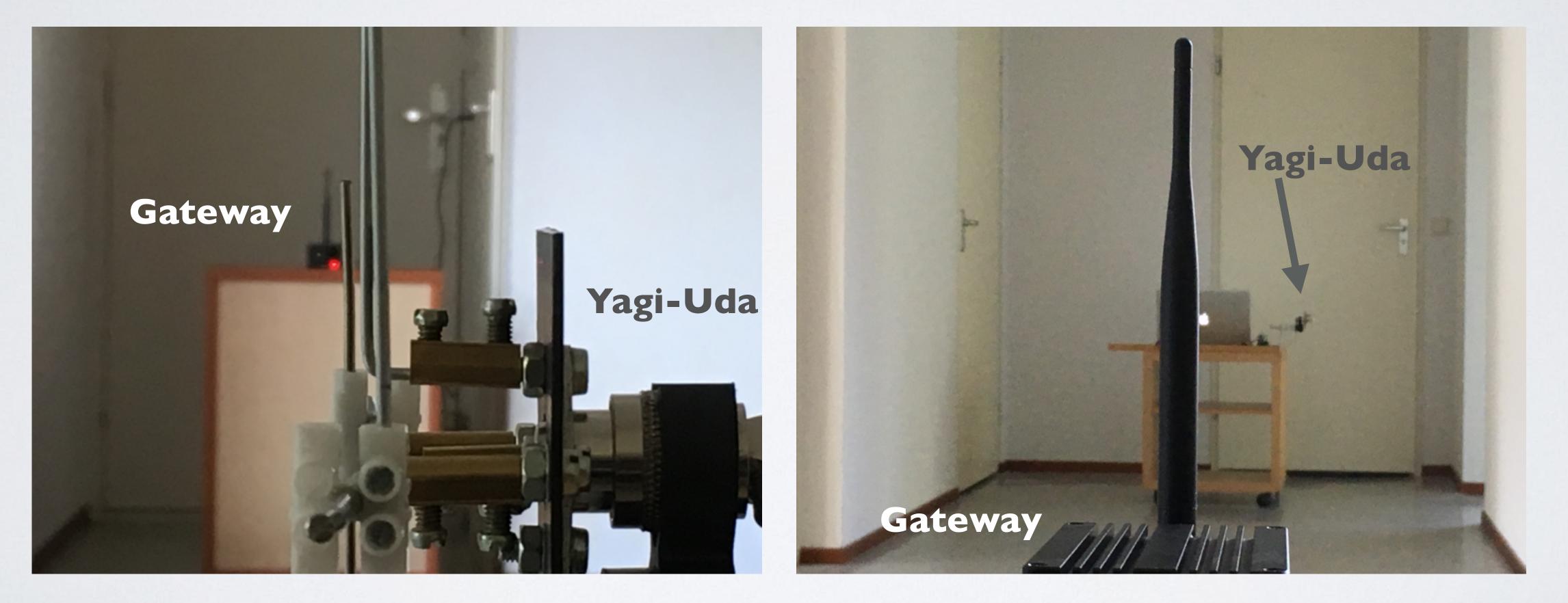
PERFORMANCE TEST B

- Make sure you keep everything in your setup the same when switching from the Yagi-Uda antenna to the $1/_2\lambda$ dipole antenna.
- A slight change can impact your measurements.
- Do not change the height of the end node and the height of the gateway. - Do not change the distance between end node and the gateway. - Use the exact same end node and gateway. - Use the same coax cables and connectors. - During the measurements I did not stay in the same room. - The distance between transmitter and receiver should be $> 4\lambda$ (Far field region) More information about near and far field, see tutorial 34.



PERFORMANCE TEST B





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gateway using antenna C (see tutorial 33)



end ½λ dipole node

6 m (far field region)

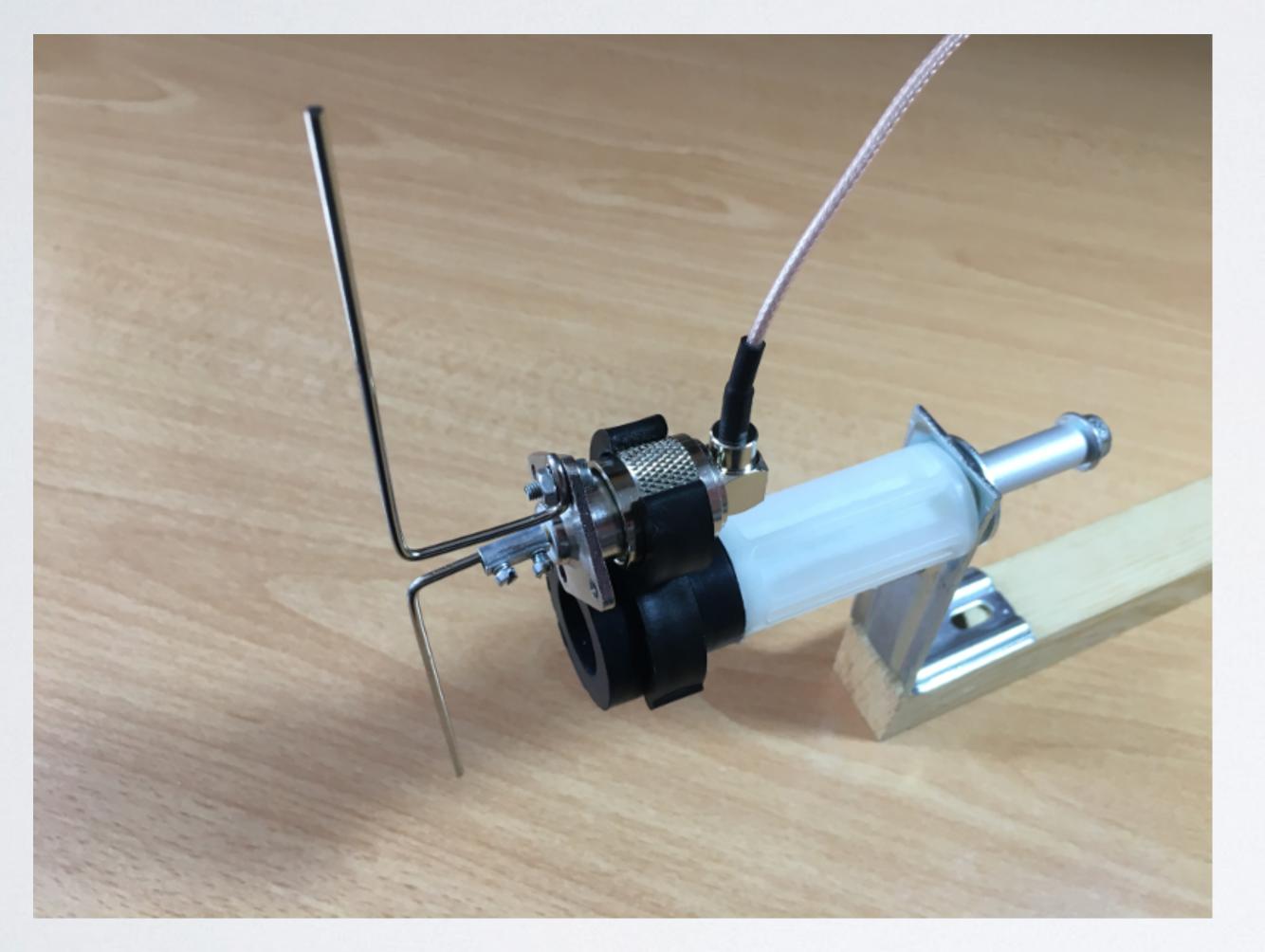


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gateway using antenna C (see tutorial 33)



• This $\frac{1}{2}\lambda$ dipole antenna is used in this setup, see tutorial 41.



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VSWR \approx 1.1 Z \approx 54 Ω SII \approx -27 dB



- The logged data can be found at: https://www.mobilefish.com/download/lora/yagi_uda_antenna_gain.txt
- The average RSSI when using the $1/_2\lambda$ dipole antenna: -28.0 dBm The average RSSI when using the Yagi-Uda antenna: -22.1 dBm



- Using the $\frac{1}{2}\lambda$ dipole antenna: 15 minutes Using the Yagi-Uda antenna: 15 minutes
- The Arduino sketch is configured to transmit I message per minute. In a perfect situation it should take 15 to 16 minutes to transmit these 15 messages.
- Conclusion: Yagi-Uda antenna performs better compared to the sleeve dipole antenna.but...

the Yagi-Uda antenna is a directional antenna, you need to point it to the correct direction. The sleeve dipole antenna is an omnidirectional antenna.

• The time it took for the gateway to receive the 15 messages from the end node:

Based on the average RSSI test results and the results from performance test A, the



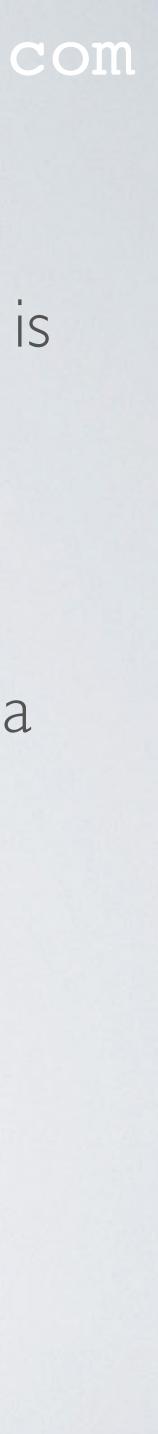
REMARKS

- other antenna parameters are just a rough indication of how the real Yagi-Uda antenna behaves.
- measurements should be performed in an anechoic chamber.
- Let's assume you bought a Yagi-Uda antenna with a maximum gain of 10 dBi and attached it to the gateway. This is the same as 7.85 dBd Calculation: dBi = dBd + 2.15; IO = dBd + 2.15; dBd = IO - 2.15 = 7.85In the gateway global_conf.json file (see tutorial 30) you must specify the antenna_gain = 7.85

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• The 4NEC2 program simulates how the antenna behaves but MY Yagi-Uda antenna is not accurately modelled. Which means that the generated radiation patterns and

• If you want accurate radiation patterns and other antenna parameters, these antenna

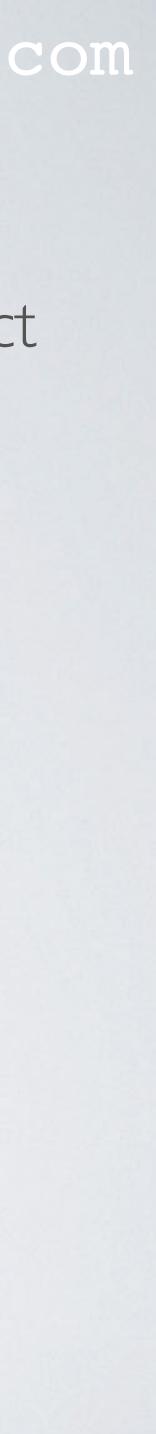


REMARKS

- join the network.
- When using a sleeve dipole antenna, which is omnidirectional, the end node can easier join the network without having to "point" it to the correct direction.
- The Yagi-Uda antenna, which is directional, can send data to gateways which are further away.

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• When using the Yagi-Uda antenna at the end node make sure it points to the correct direction where a gateway is located otherwise the end node has a difficult time to



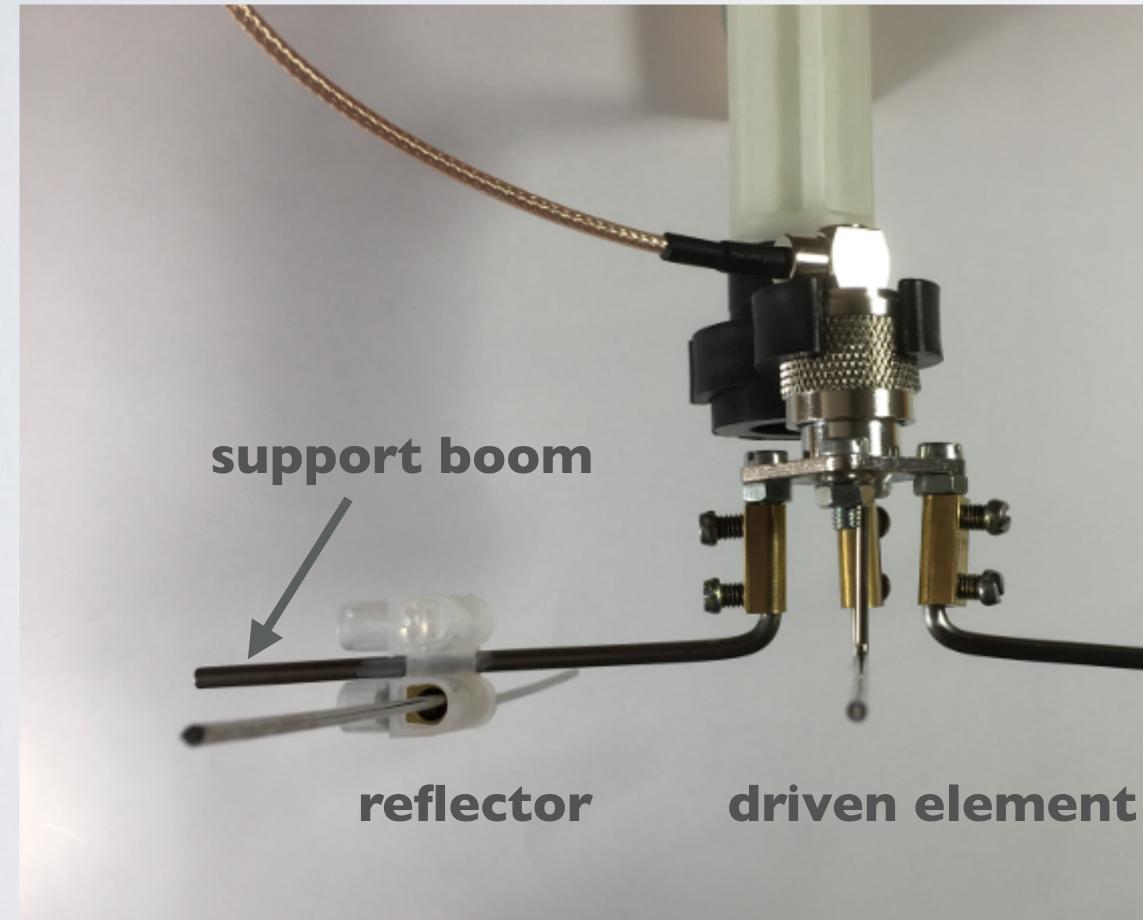
Experiment

Attach support booms to type N female chassis, not using plastic plate.

DO NOT DO THIS!



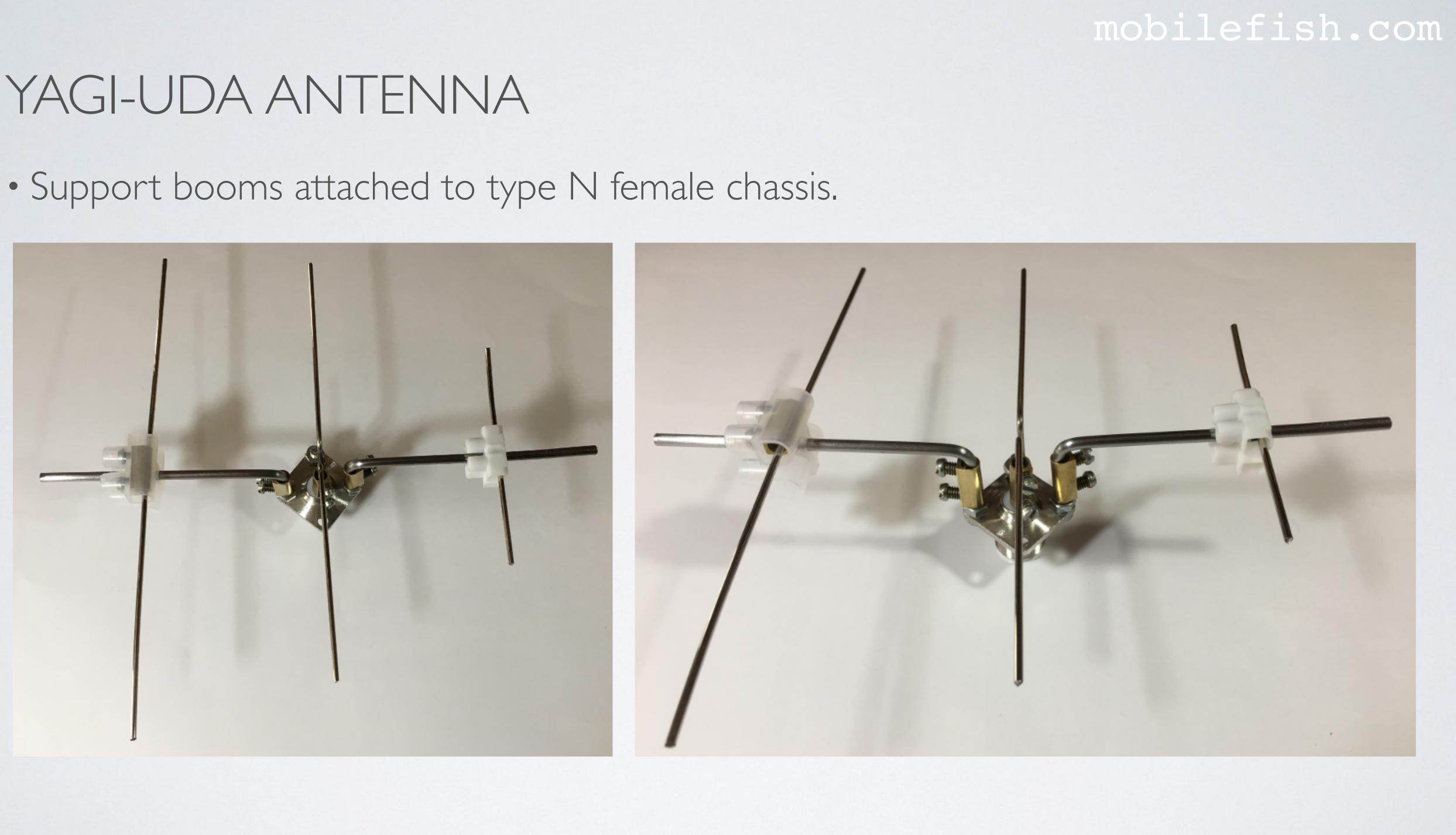
• Support booms attached to type N female chassis.



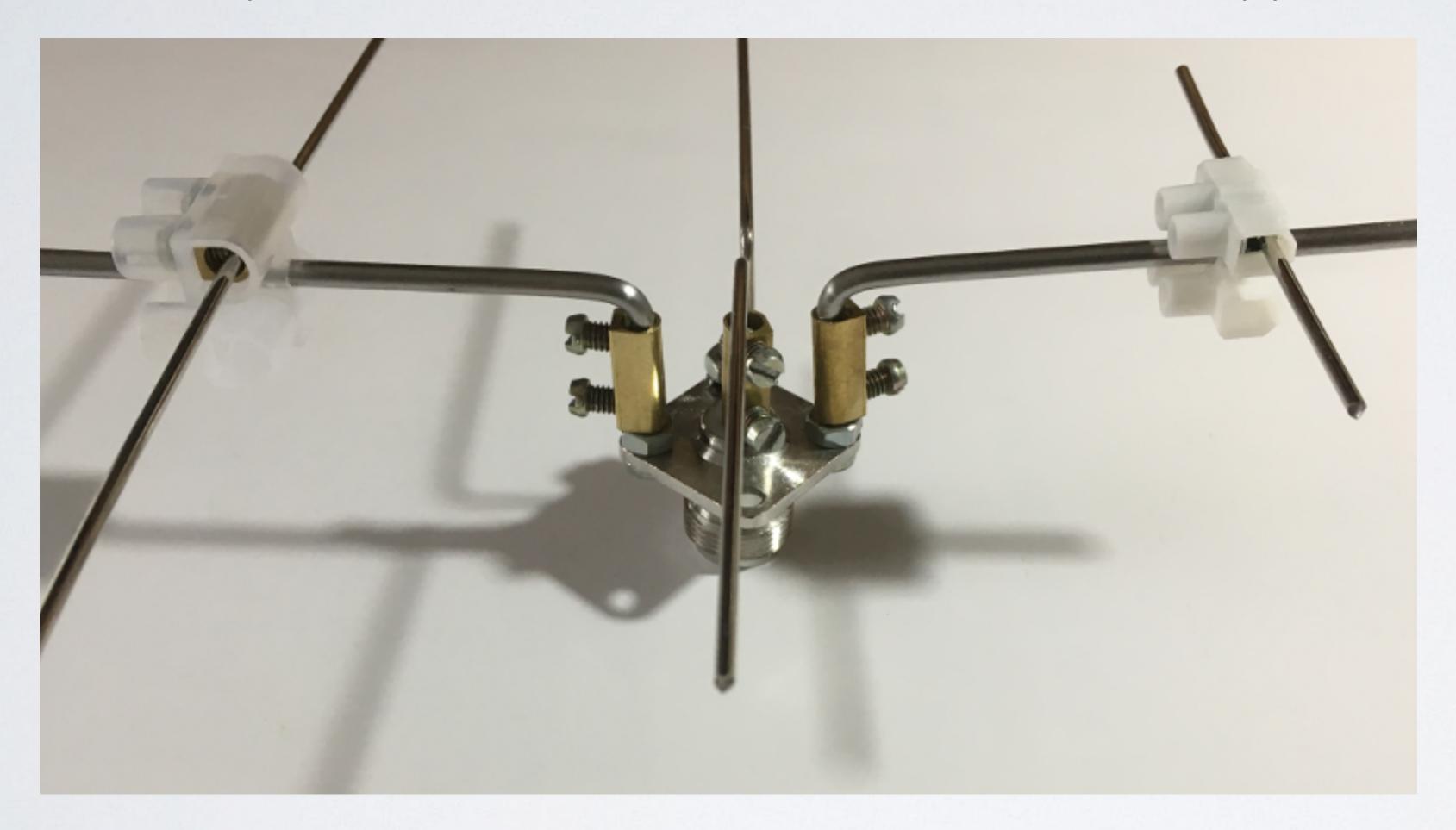
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support boom director



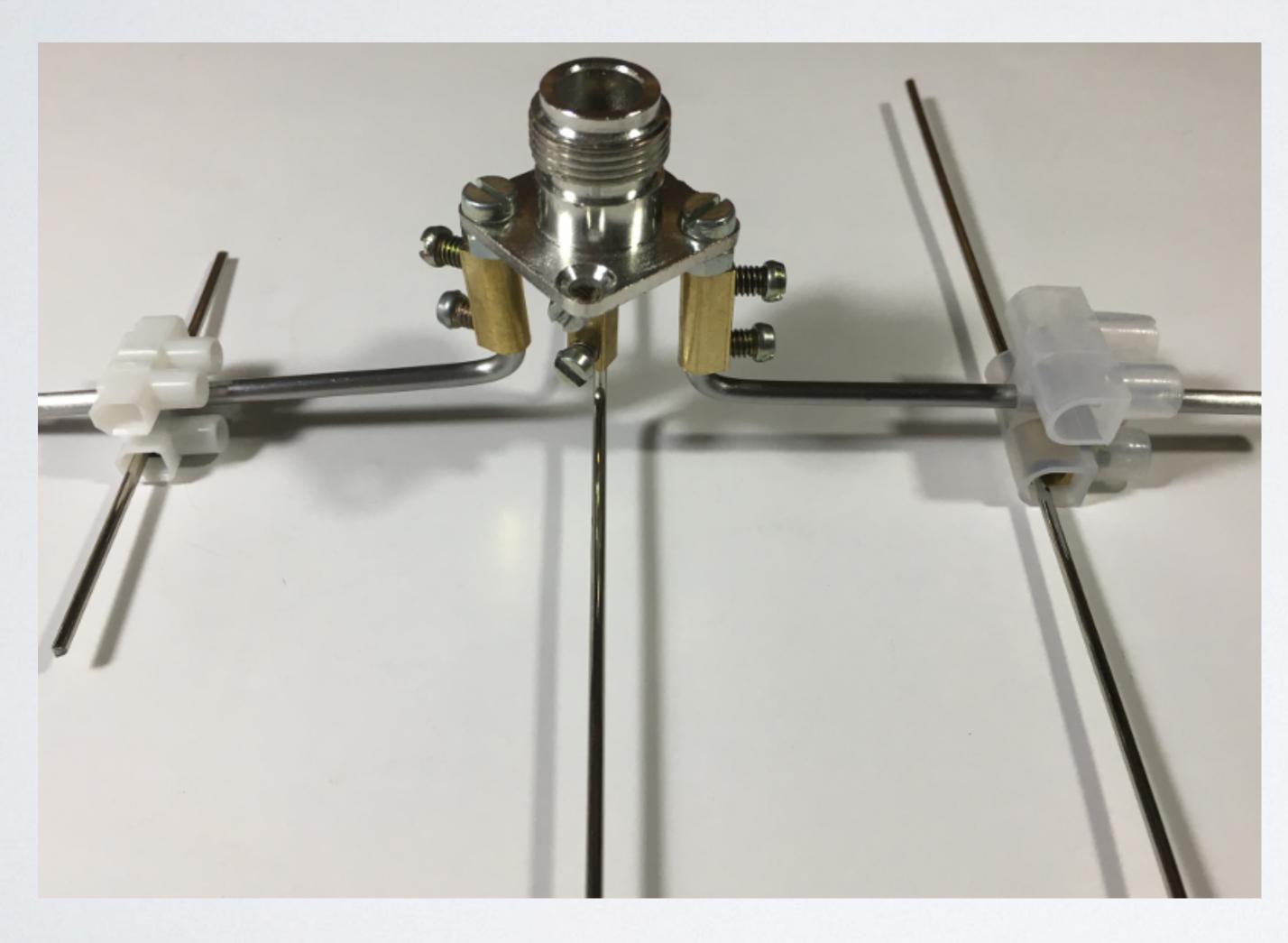


• Close up reflector, driven element, director and support boom.



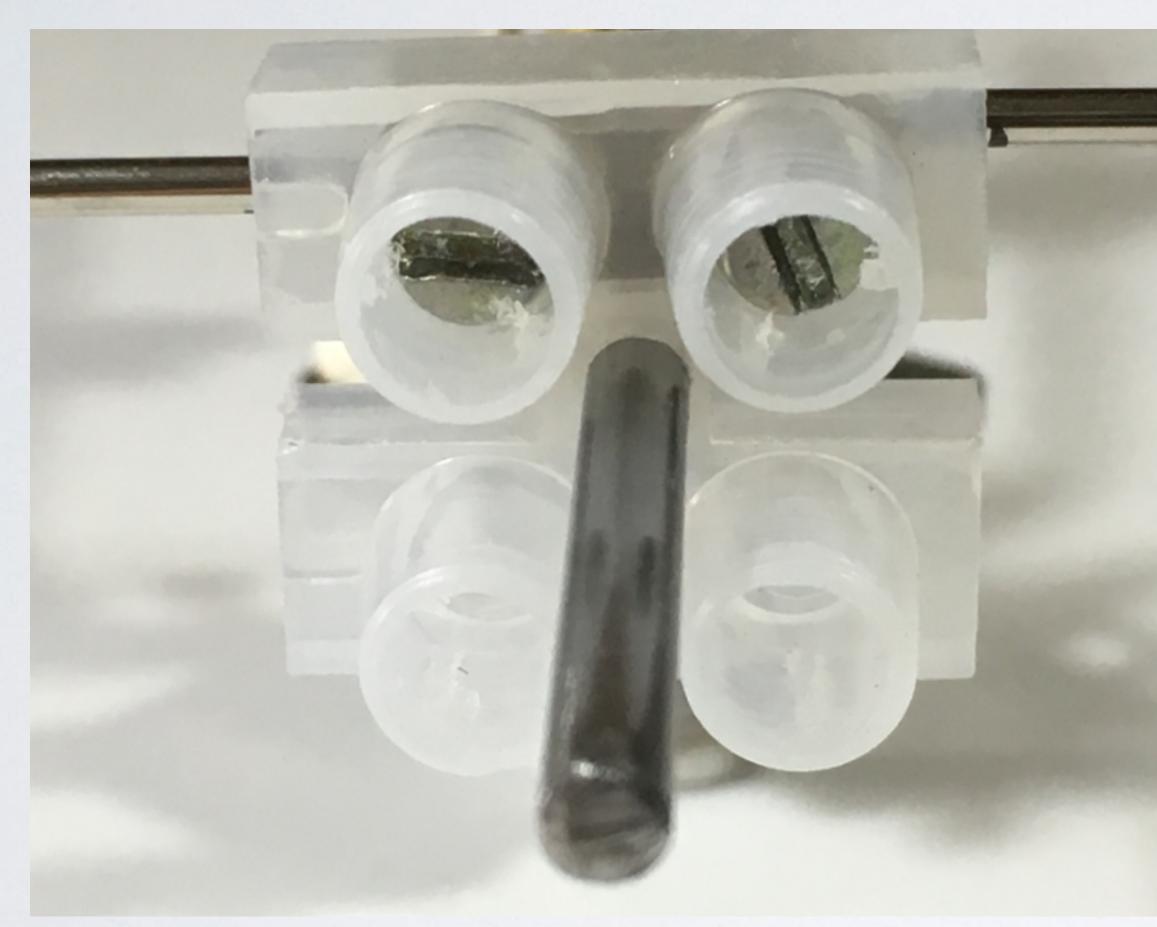


• Bottom view.



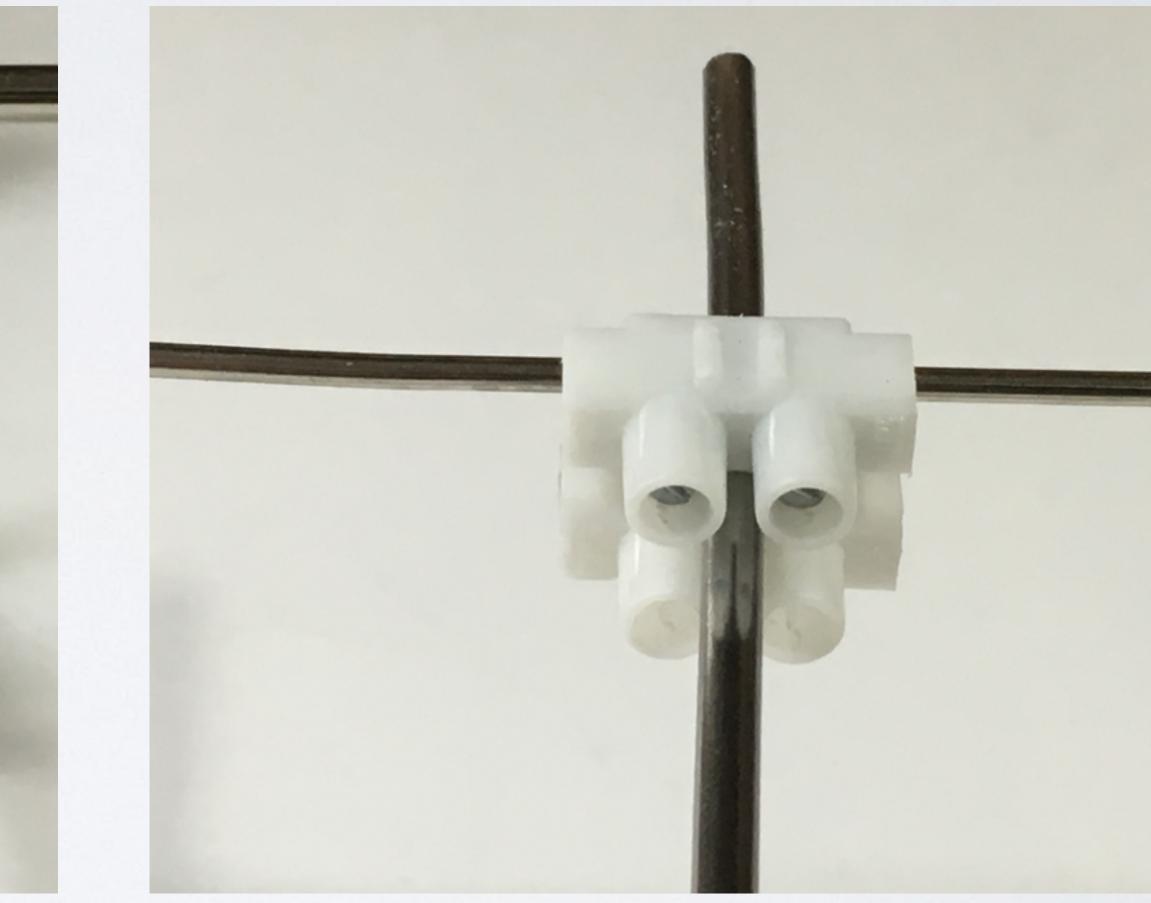


Close up terminal strip blocks



Large terminal strip block for reflector

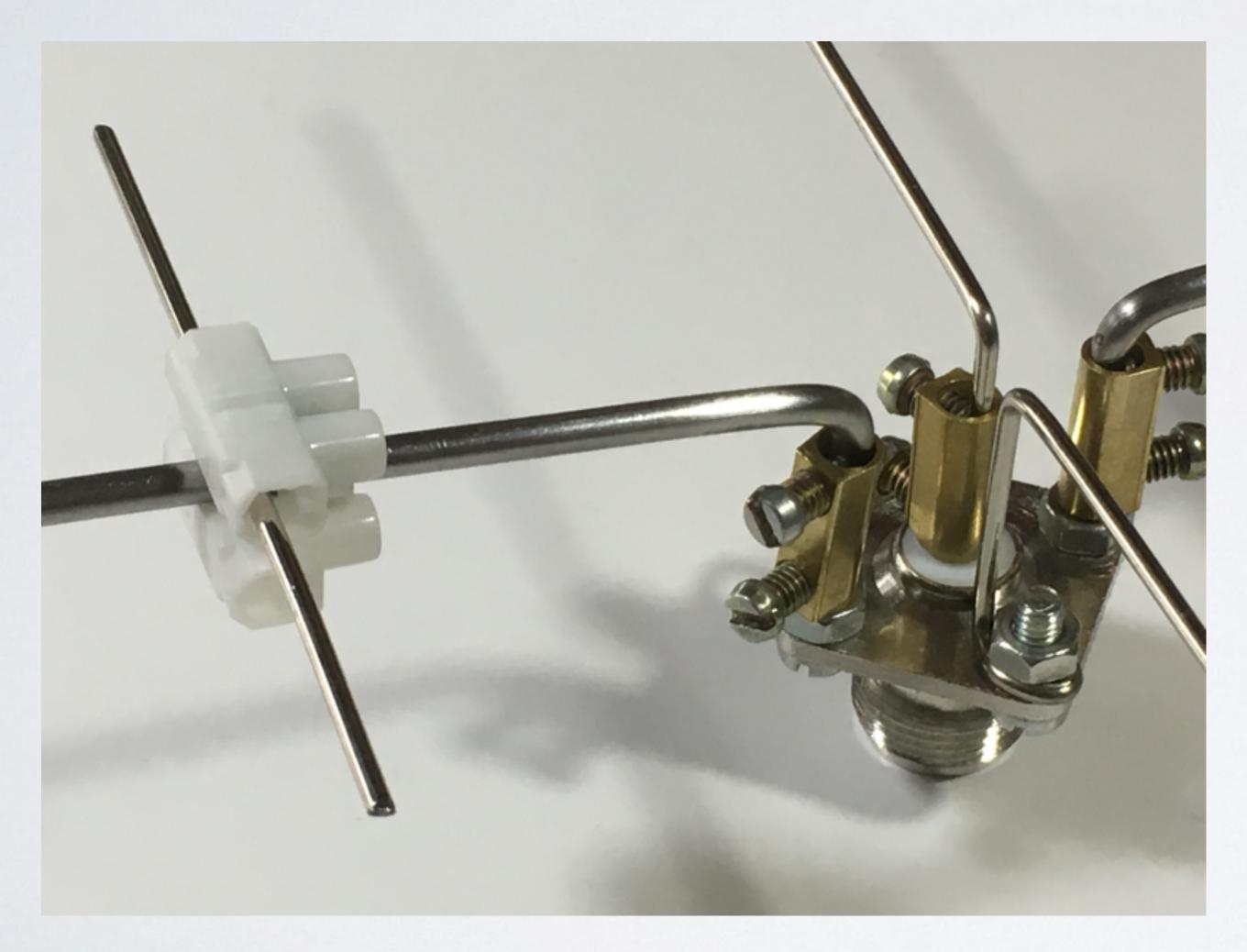
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Small terminal strip block for director

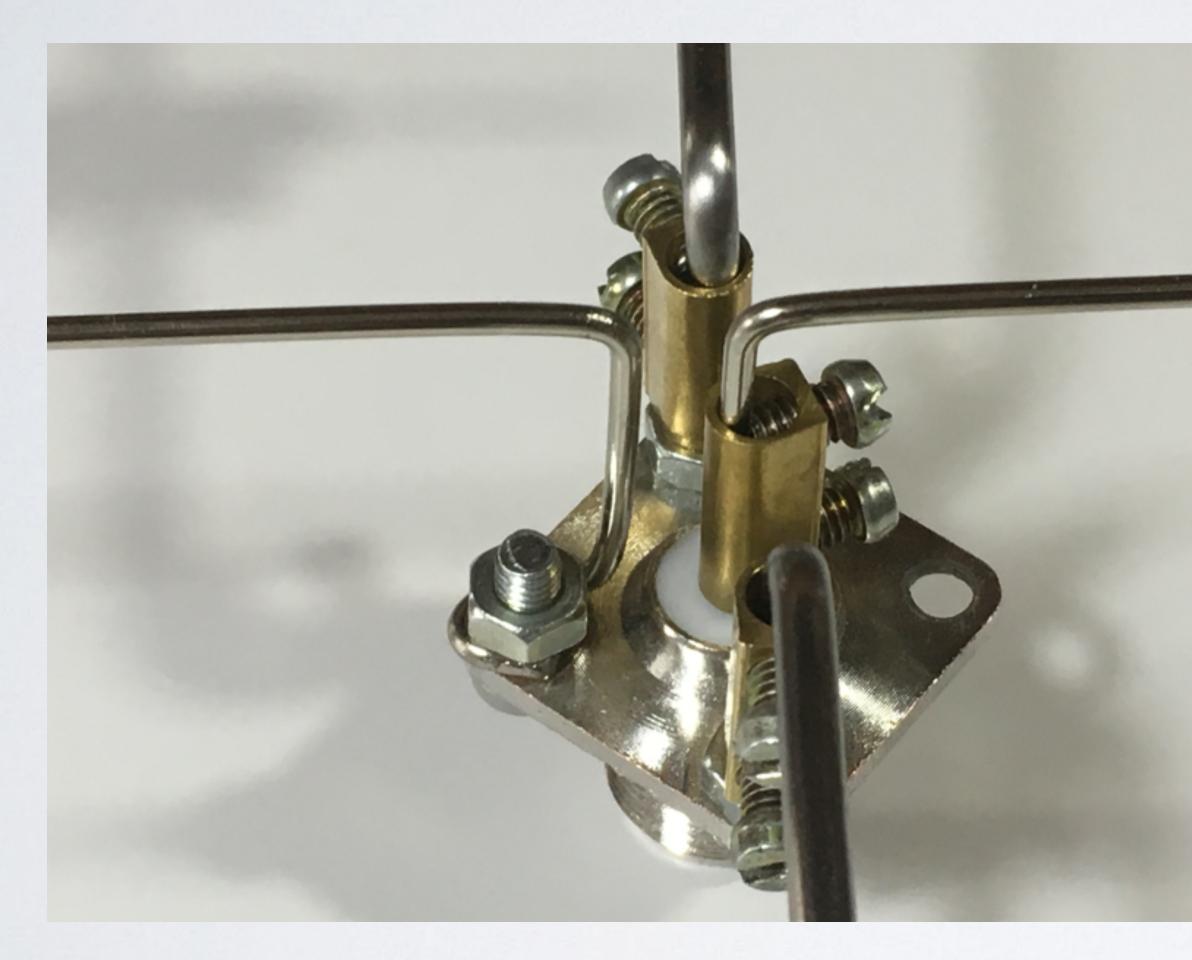


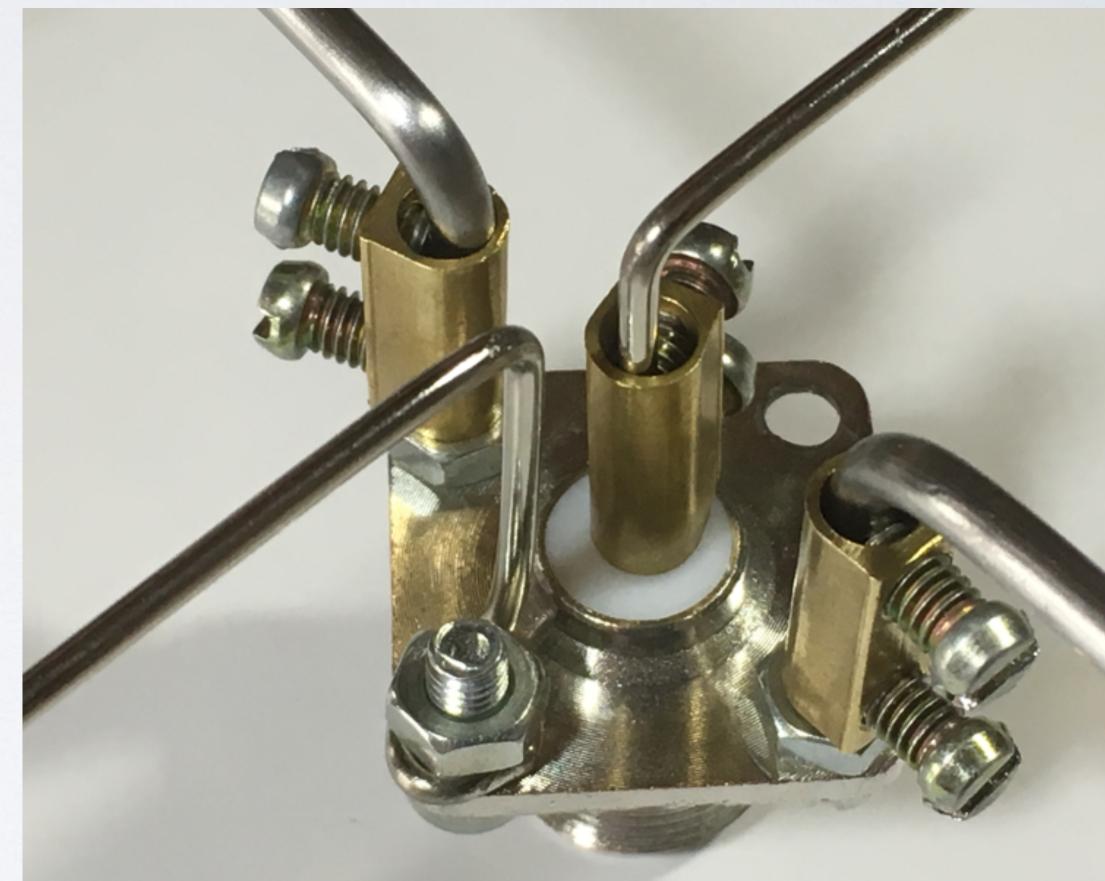
• Director and driven element.





• Close up driven element.

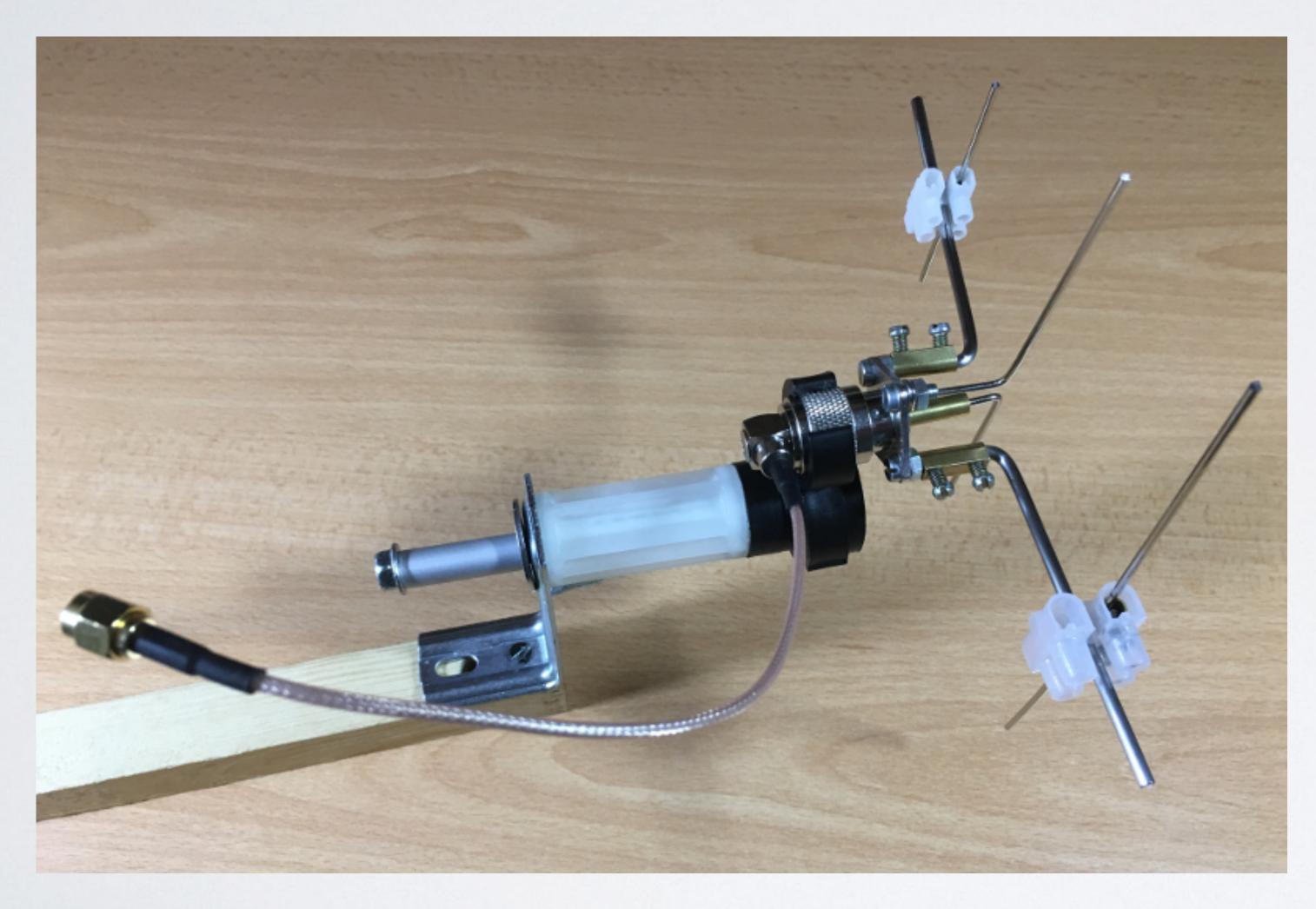


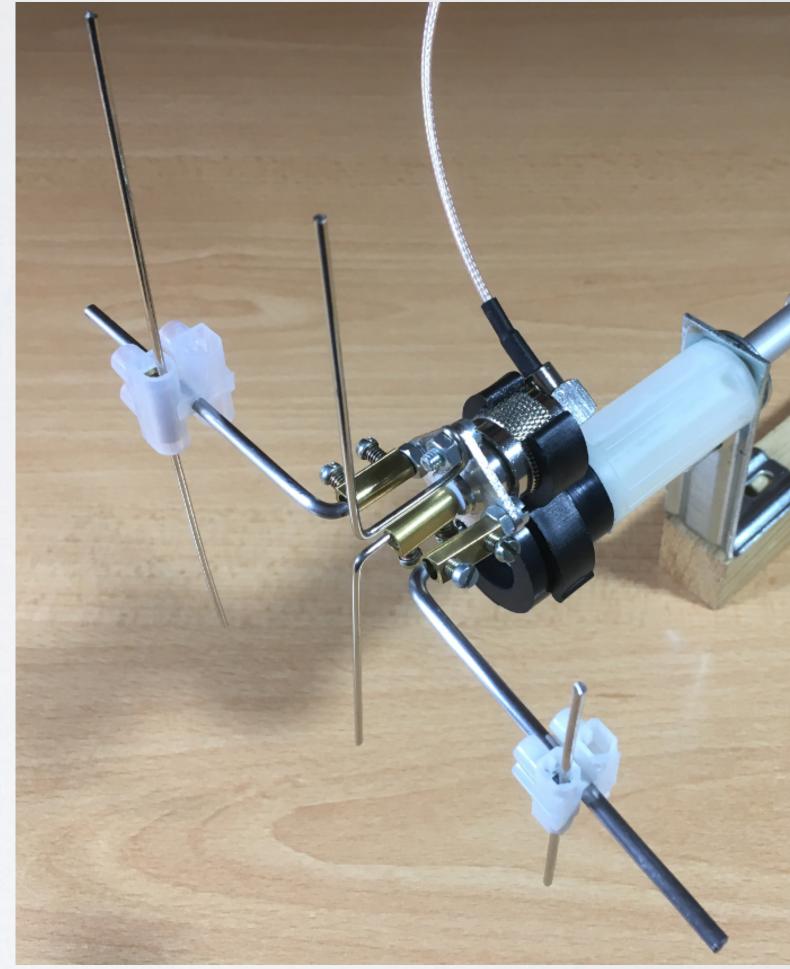




YAGI-UDA ANTENNA MOUNTED ON TEST RIG

• Antenna clamped to test rig.

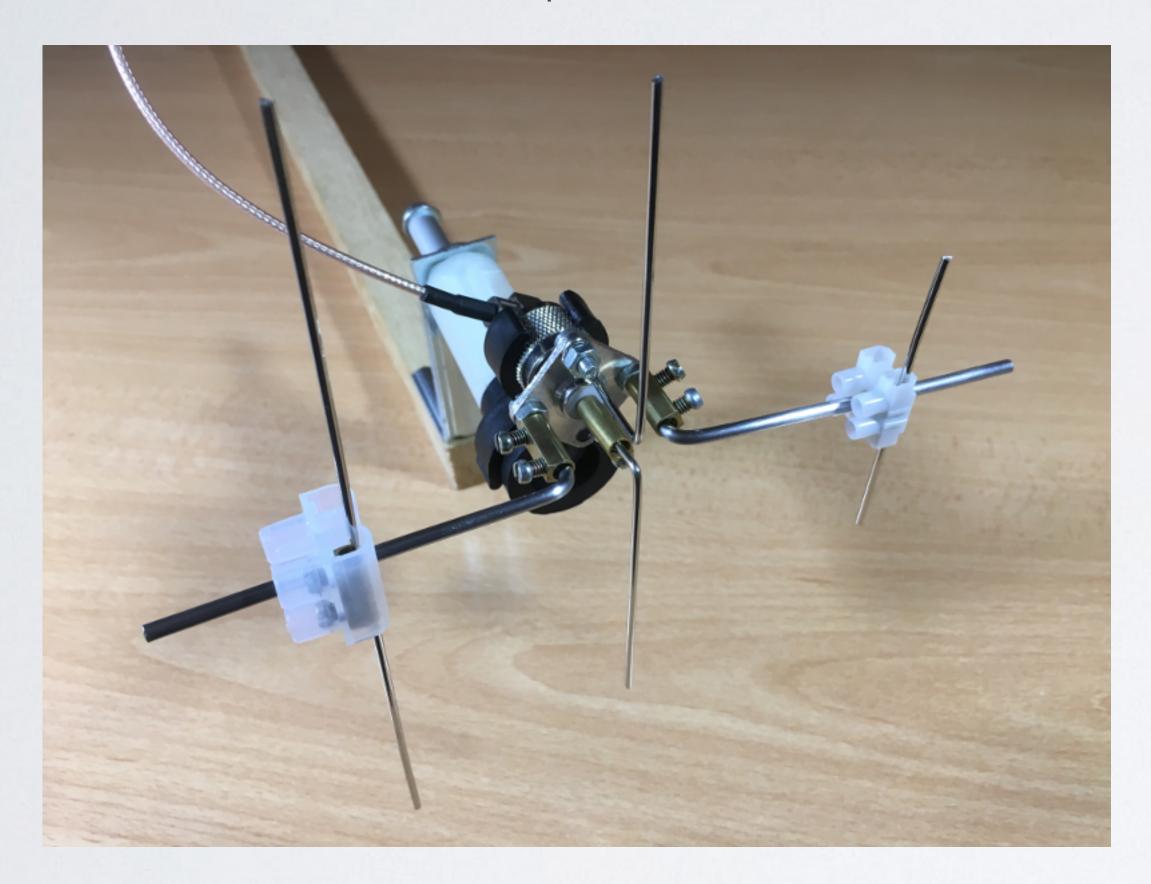


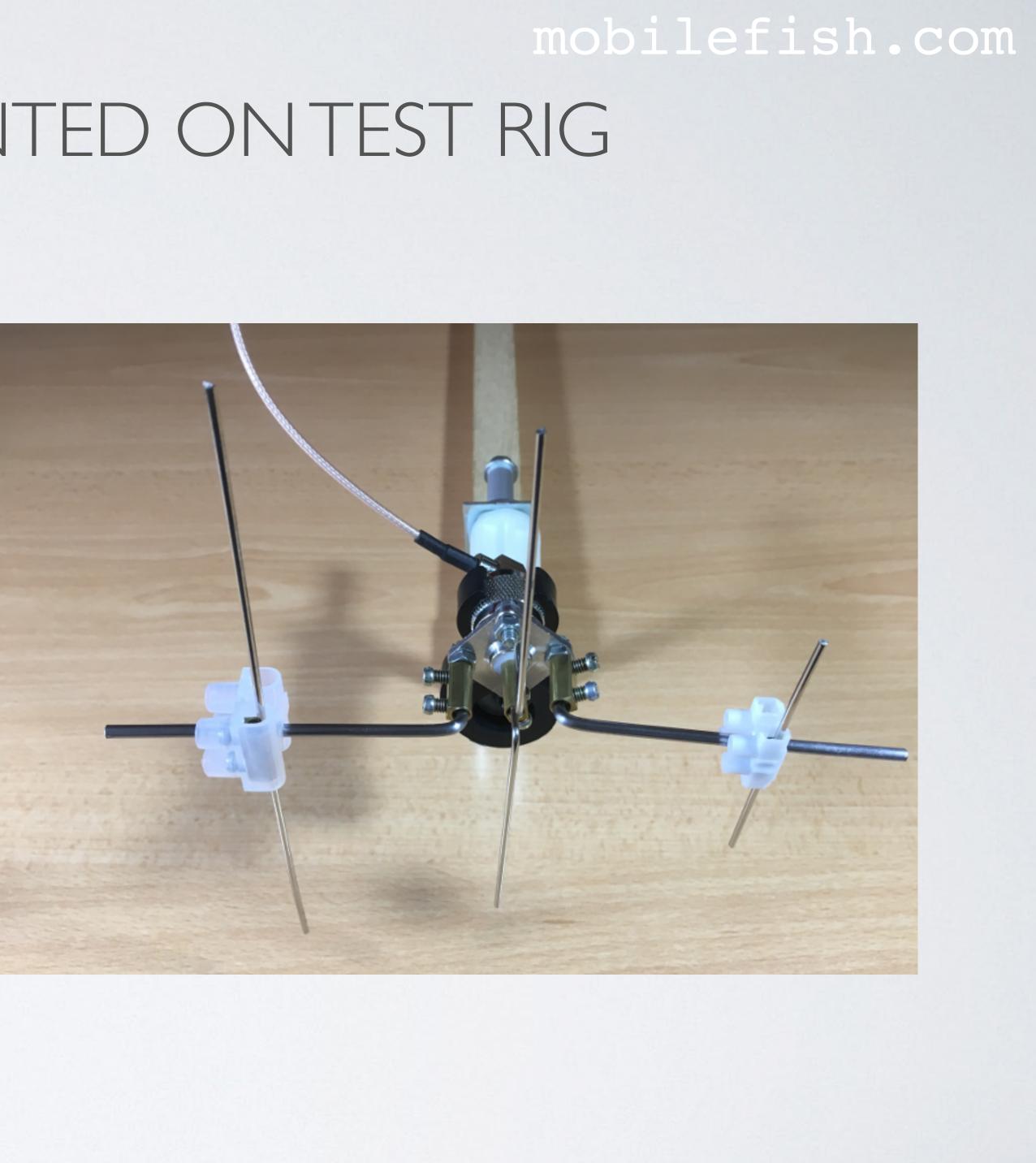




YAGI-UDA ANTENNA MOUNTED ON TEST RIG

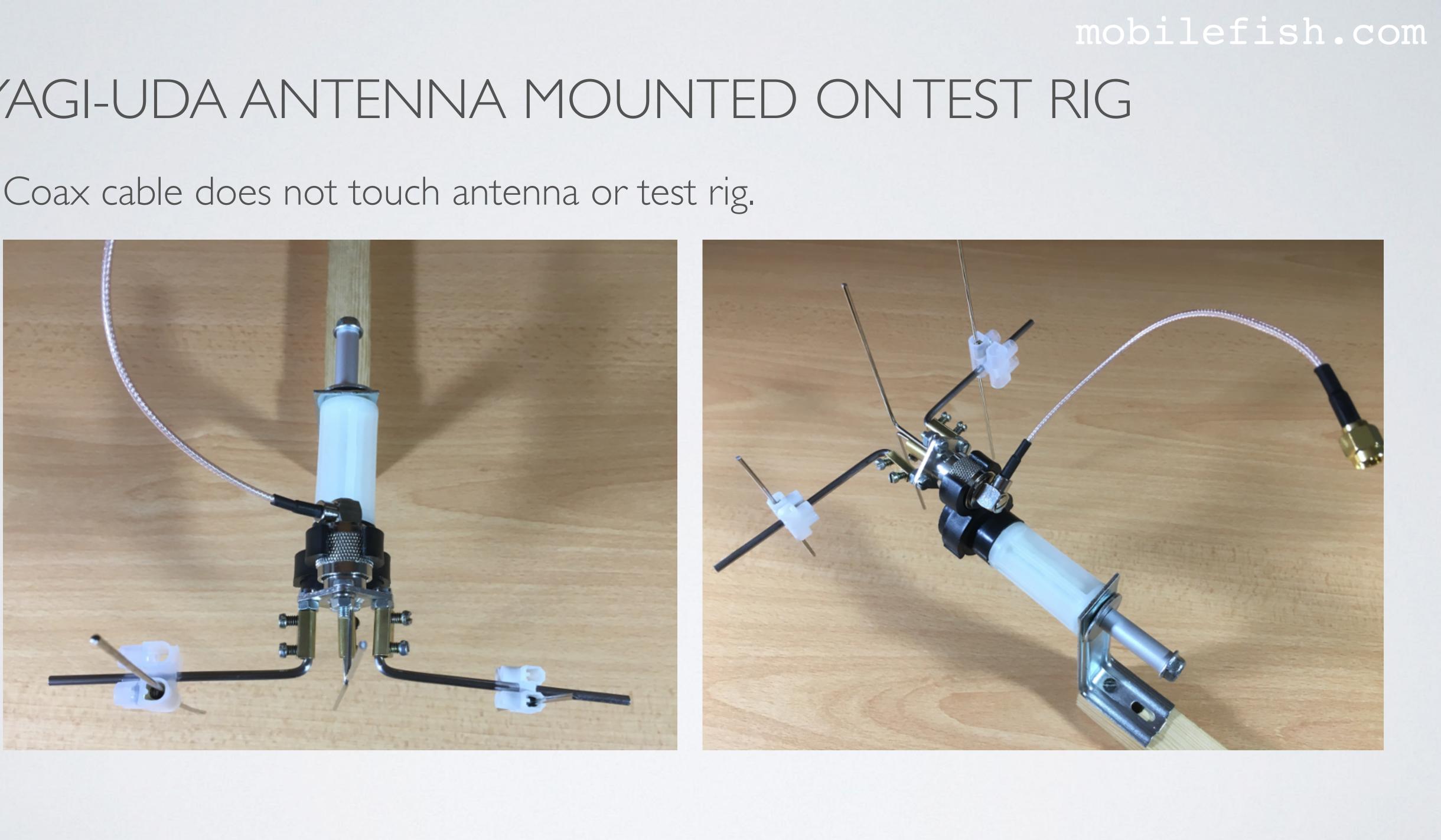
• Front view close up.





YAGI-UDA ANTENNA MOUNTED ON TEST RIG

• Coax cable does not touch antenna or test rig.





Measuring antenna parameters

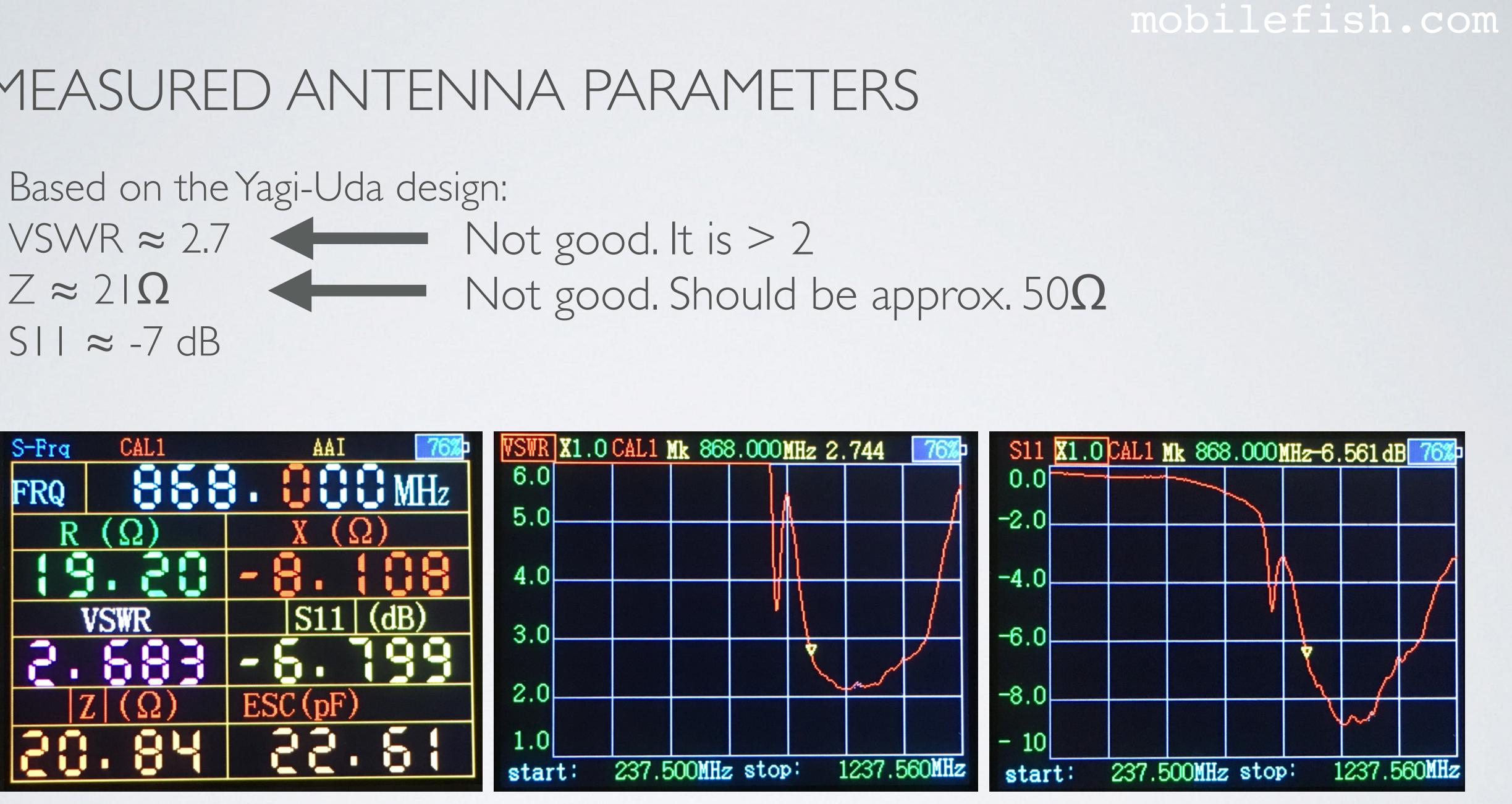
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The antenna analyser with the Yagi-Uda antenna.

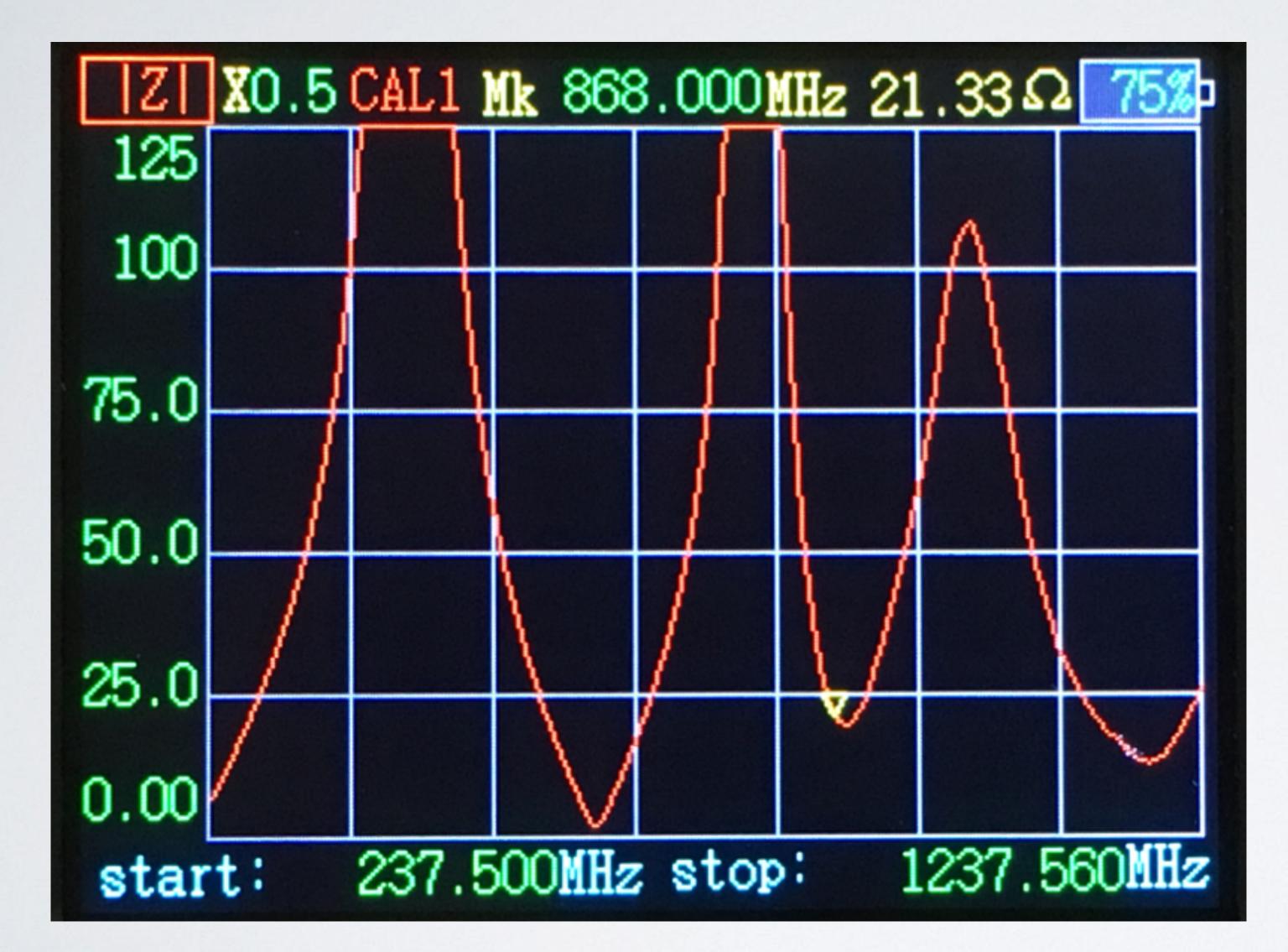


MEASURED ANTENNA PARAMETERS

• Based on the Yagi-Uda design: $Z \approx 2 | \Omega$ $S|| \approx -7 \, dB$



MEASURED ANTENNA PARAMETERS





DISCREPANCY

- When using the 4NEC2 antenna modelling software, the VSWR=1.04
- After building the actual Yagi-Uda antenna and testing it with the NI20ISA the VSWR=2.7
- What causes this discrepancy?
- The support booms are also connected to the N type connector (ground).

 Conclusion: Do not conductively attach the support booms to the N type connector, use the plastic plate.

